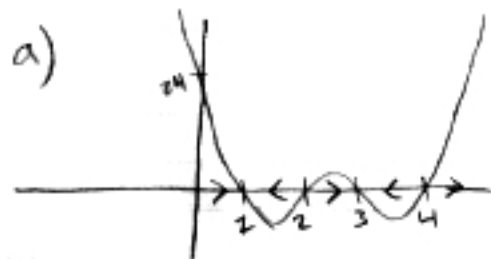


110A Problem Set #1 due 10/4

I. $\dot{u} = (u-1)(u-2)(u-3)(u-4)$



b) $u^* = 1$, stable fixed point

$u^* = 2$, unstable fixed point

$u^* = 3$, stable fixed point

$u^* = 4$, unstable fixed point

c) $u_0 = 1/2$, $u(\infty) = 1$

d) $u_0 = 3/2$, $u(\infty) = 1$

e) $u_0 = 5/2$, $u(\infty) = 3$

f) $u_0 = 7/2$, $u(\infty) = 3$

g) $u_0 = 9/2$, $u(\infty) = 4$

$$2. \ddot{x} + \Omega^2 x = 0$$

$$a) \ddot{x} = -\Omega^2 x \rightarrow \frac{d^2 x}{dt^2} = -\Omega^2 x, \quad v = \dot{x} = \frac{dx}{dt}$$

$$\frac{d}{dt} \begin{pmatrix} x \\ v \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -\Omega^2 & 0 \end{pmatrix} \begin{pmatrix} x \\ v \end{pmatrix} = \begin{pmatrix} v \\ -\Omega^2 x \end{pmatrix}$$

$$\text{where } \dot{\phi} = \frac{d}{dt} \begin{pmatrix} x \\ v \end{pmatrix}, \quad M = \begin{pmatrix} 0 & 1 \\ -\Omega^2 & 0 \end{pmatrix}, \quad \phi = \begin{pmatrix} x \\ v \end{pmatrix}$$

$$b) \dot{\phi} = M \phi, \quad \phi(t) = e^{Mt} \phi(0)$$

$$e^{Mt} = 1 + Mt + \frac{1}{2!} M^2 t^2 + \frac{1}{3!} M^3 t^3 + \dots$$

$$M^2 = \begin{pmatrix} 0 & 1 \\ -\Omega^2 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -\Omega^2 & 0 \end{pmatrix} = \begin{pmatrix} -\Omega^2 & 0 \\ 0 & -\Omega^2 \end{pmatrix} = -\Omega^2 \mathbb{1}$$

$$\therefore M^{2k} = (-\Omega^2)^k \mathbb{1} \rightarrow \text{even}$$

$$M^{2k+1} = (-\Omega^2)^k M \rightarrow \text{odd}$$

$$e_{\text{even}}^{Mt} = 1 + \frac{1}{2!} M^2 t^2 + \frac{1}{4!} M^4 t^4 + \dots$$

$$e_{\text{odd}}^{Mt} = Mt + \frac{1}{3!} M^3 t^3 + \frac{1}{5!} M^5 t^5 + \dots$$

$$\rightarrow \text{Remember: } \begin{cases} \cos x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!} = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots \\ \sin x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!} = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots \end{cases}$$

$$e_{\text{even}}^{Mt} = 1 + \frac{1}{2!} M^2 t^2 + \dots = \mathbb{1} \left(1 - \frac{\Omega^2 t^2}{2!} + \frac{\Omega^4 t^4}{4!} - \dots \right)$$

$$e_{\text{odd}}^{Mt} = Mt + \frac{1}{3!} M^3 t^3 + \dots = \frac{M}{\Omega} \left(\Omega t - \frac{\Omega^3 t^3}{3!} + \frac{\Omega^5 t^5}{5!} - \dots \right)$$

$$\therefore e_{\text{even}}^{Mt} = \mathbb{1} \cos(\Omega t), \quad e_{\text{odd}}^{Mt} = \frac{M}{\Omega} \sin(\Omega t)$$

2 b) continued.

$$e_{\text{even}}^{mt} + e_{\text{odd}}^{mt} = \mathbb{1} \cos(\Omega t) + \frac{M}{\Omega} \sin(\Omega t) = e^{mt}$$

$$\begin{pmatrix} x(t) \\ v(t) \end{pmatrix} = \begin{pmatrix} \cos \Omega t & 0 \\ 0 & \cos \Omega t \end{pmatrix} \begin{pmatrix} x_0 \\ v_0 \end{pmatrix} + \frac{M \dot{\phi}(0) \sin(\Omega t)}{\Omega}$$

note: $\dot{\phi}(0) = M \phi(0)$

$$\begin{pmatrix} x(t) \\ v(t) \end{pmatrix} = \begin{pmatrix} \cos \Omega t & 0 \\ 0 & \cos \Omega t \end{pmatrix} \begin{pmatrix} x_0 \\ v_0 \end{pmatrix} + \frac{\sin(\Omega t)}{\Omega} \begin{pmatrix} v_0 \\ -\Omega^2 x_0 \end{pmatrix}$$

$$\therefore x(t) = x_0 \cos(\Omega t) + \frac{v_0}{\Omega} \sin(\Omega t)$$

$$v(t) = v_0 \cos(\Omega t) - \Omega x_0 \sin(\Omega t)$$

3. $\dot{A} = \epsilon A - gA^3$: supercrit for $g > 0$.

$\dot{A} = \epsilon A - gA^3 - kA^5$: subcrit for $g < 0$.

a) Landau eqn: $\dot{A} = \epsilon A - gA^3$

$$A^* \propto \epsilon^\beta \rightarrow \epsilon A - gA^3 = 0, A^* = 0$$

$$A_{\pm}^* = \pm \sqrt{\frac{4\epsilon g}{2g}} = \pm \epsilon^{1/2}$$

\therefore the Landau eqn predicts $A^* \propto \epsilon^\beta$ where $\beta = .5$, confirming the experimental results of $\beta = .5 \pm .01$.

b) $\dot{A} = \epsilon A - gA^3 - kA^5$

for $g = 0$, $\dot{A} = \epsilon A - kA^5$

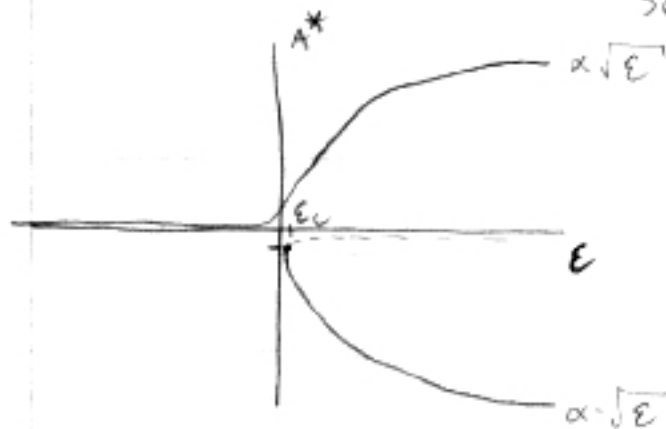
$$A^* = 0, A_{\pm}^* = \pm \sqrt[4]{\frac{\epsilon}{k}} \propto \epsilon^{1/4}$$

c) $\dot{A} = h + \epsilon A - gA^3 - kA^5$ $k > 0$ fixed, $h > 0$, $h \ll 1$

$\dot{A} = h + \epsilon A - gA^3 - kA^5 = 0$ in order to solve for roots analytically, let $h \rightarrow +0$.

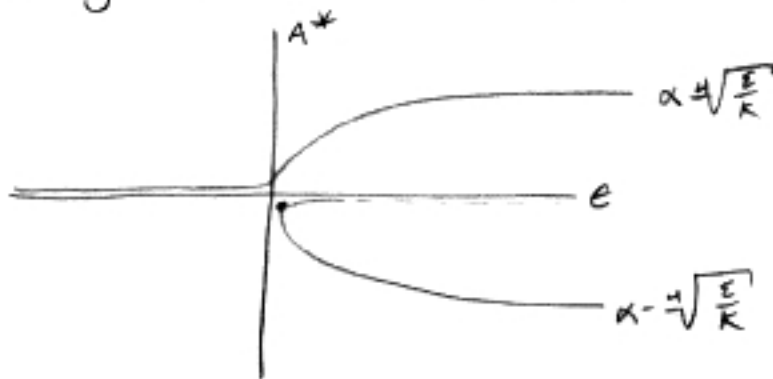
i) $A^* \approx 0, \pm \sqrt{\epsilon}$

we have an imperfect supercritical pitchfork.



$$\text{where } \epsilon_c \propto \frac{3}{2^{2/3}} |h|^{2/3}$$

$$\text{ii) } g=0, \quad A^* \approx 0, \quad \pm \sqrt{\frac{\epsilon}{K}}$$

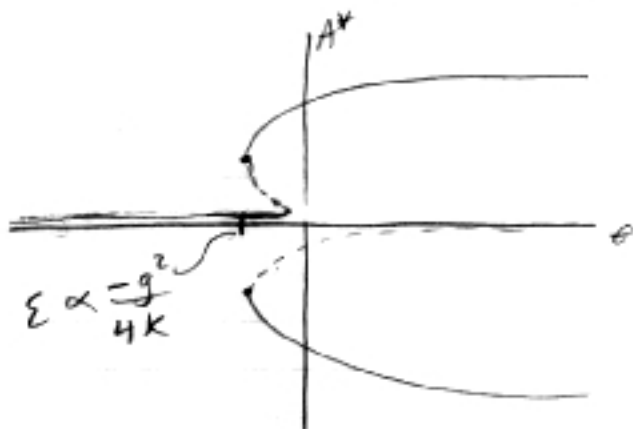


$$\text{iii) } g < 0, \quad A^* \approx 0, \quad \left(+ \frac{g\epsilon}{2K} \pm \sqrt{\frac{g^2}{4K^2} + \frac{\epsilon}{K}} \right)^{1/2}$$

$$\epsilon < -\frac{g^2}{4K}, \quad \text{one real root}$$

$$0 > \epsilon > -\frac{g^2}{4K}, \quad 5 \text{ real roots}$$

$$\epsilon > 0, \quad 3 \text{ real roots}$$



$$4. a) \begin{cases} \dot{x} = x - y = 0 \\ \dot{y} = x^2 - 4 = 0 \end{cases} \quad (x^*, y^*) = (2, 2)$$

$$M = \begin{pmatrix} 1 & -1 \\ 2x & 0 \end{pmatrix}$$

for $(x^*, y^*) = (2, 2)$, $T = 1$, $D = 4$

here, $D > \frac{1}{4}T^2 \therefore$ unstable spiral @ $(2, 2)$

$$b) \begin{cases} \dot{x} = 1 + y - e^{-x} = 0 \\ \dot{y} = x^3 - y = 0 \end{cases} \quad M = \begin{pmatrix} e^{-x} & 1 \\ 3x^2 & -1 \end{pmatrix}$$

$$(x^*, y^*) = (0, 0)$$

for $(0, 0)$, $T = 0$, $D = -1$

here, $D < 0$ we have a saddle @ $(0, 0)$

$$c) \begin{cases} \dot{x} = \sin y = 0 \\ \dot{y} = \cos x = 0 \end{cases} \quad (x^*, y^*) = \left(\frac{\pi}{2} + n\pi, n\pi\right), n=0, 1, 2, \dots$$

$$M = \begin{pmatrix} 0 & \cos y \\ -\sin x & 0 \end{pmatrix}$$

\hookrightarrow no flow in this case.
b/c $\lambda_{\pm} = 0$

$$\sin y - \cos x = 0 \rightarrow x = y = \frac{\pi}{4} + n\pi$$

$$M = \begin{pmatrix} 0 & \frac{\sqrt{2}}{2} \\ -\frac{\sqrt{2}}{2} & 0 \end{pmatrix}$$

$$T = 0, D = \frac{2}{4} = \frac{1}{2}$$

since $T = 0, D > 0$, $\lambda_{\pm} = \pm i\sqrt{\frac{1}{2}}$
 \therefore centers @ $(x^*, y^*) = \left(\frac{\pi}{4} + n\pi, \frac{\pi}{4} + n\pi\right)$

$$5. \dot{N}_1 = r_1 N_1 \left(1 - \frac{N_1}{K_1}\right) - b_1 N_1 N_2$$

$$\dot{N}_2 = r_2 N_2 - b_2 N_1 N_2$$

a) $t \rightarrow \alpha \tau, N_1 \rightarrow \beta n_1, N_2 \rightarrow \gamma n_2$

$$\frac{\beta dn_1}{\alpha d\tau} = r_1 \beta n_1 \left(1 - \frac{\beta n_1}{K_1}\right) - b_1 \beta n_1 \gamma n_2$$

$$\frac{dn_1}{d\tau} = \alpha r_1 n_1 \left(1 - \frac{\beta n_1}{K_1}\right) - b_1 \alpha \gamma n_1 n_2$$

$$\frac{\gamma dn_2}{\alpha d\tau} = r_2 \gamma n_2 - b_2 \beta n_1 \gamma n_2$$

$$\frac{dn_2}{d\tau} = \alpha r_2 n_2 - b_2 \alpha \beta n_1 n_2$$

$$b_1 \alpha \gamma = 1 \Rightarrow b_1 \gamma = b_2 \beta \quad \alpha r_1 = 1, \quad \frac{r_2}{r_1} = \epsilon$$

$$b_2 \alpha \beta = 1$$

$$\frac{\beta}{K_1} = K$$

$$\dot{n}_1 = n_1 \left(1 - \frac{n_1}{K}\right) - n_1 n_2$$

$$\dot{n}_2 = \epsilon n_2 - n_1 n_2$$

b) $\dot{n}_1 = 0, \dot{n}_2 = 0$

$$n_1 \left(1 - \frac{n_1}{K}\right) - n_1 n_2 = 0 \quad \rightarrow K \text{ is the carrying capacity.}$$

$$\epsilon n_2 - n_1 n_2 = 0$$

for K large:

$$\begin{aligned} \dot{n}_1 &\approx n_1 - n_1 n_2 = n_1(1 - n_2) = 0 \\ \dot{n}_2 &= \epsilon n_2 - n_1 n_2 = n_2(\epsilon - n_1) = 0 \end{aligned}, \quad M = \begin{pmatrix} 1 - n_2 & -n_1 \\ -n_2 & \epsilon - n_1 \end{pmatrix}$$

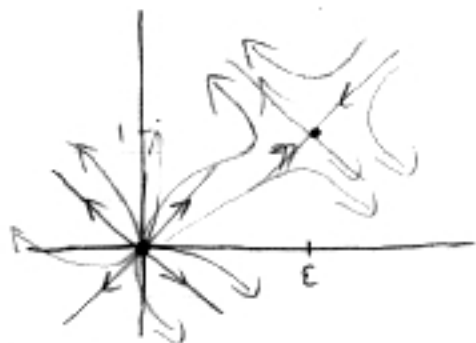
$$(n_1^*, n_2^*) = (0, 0), (\epsilon, 1)$$

pt $(0, 0)$: $M = \begin{pmatrix} 1 & 0 \\ 0 & \epsilon \end{pmatrix} \quad T = 1 + \epsilon, \quad D = \epsilon \quad \text{for } \epsilon > 0,$

we get $0 < D < \frac{1}{4} T^2 \rightarrow$ unstable node

$$\text{pt}(\varepsilon, 1): M = \begin{pmatrix} 0 & -\varepsilon \\ -1 & 0 \end{pmatrix} \quad T=0, D=-\varepsilon$$

we get a saddle point



for k small:

$$\begin{aligned} \dot{n}_1 &= n_1 \left(1 - \frac{n_1}{k}\right) - n_1 n_2 = 0 \\ \dot{n}_2 &= \varepsilon n_2 - n_1 n_2 = 0 \end{aligned}$$

$$(n_1^*, n_2^*) = (0, 0), (k, 0), \left(\varepsilon, \frac{\varepsilon}{k} - 1\right)$$

$$M = \begin{pmatrix} 1 - \frac{2n_1}{k} - n_2 & -n_1 \\ -n_2 & \varepsilon - n_1 \end{pmatrix}$$

$$\text{pt}(0,0): M = \begin{pmatrix} 1 & 0 \\ 0 & \varepsilon \end{pmatrix} \rightarrow \text{unstable node}$$

$$\text{pt}(k,0): M = \begin{pmatrix} -1 & -k \\ 0 & \varepsilon - k \end{pmatrix} \quad T = \varepsilon - k - 1, D = k - \varepsilon, T > 0$$

$$\frac{1}{4}T^2 > D > 0 \therefore \text{unstable node}$$

$$\text{pt}\left(\varepsilon, \frac{\varepsilon}{k} - 1\right): M = \begin{pmatrix} 2 - \frac{3\varepsilon}{k} & -\varepsilon \\ 1 - \frac{\varepsilon}{k} & 0 \end{pmatrix} \quad T = 2 - \frac{3\varepsilon}{k}, D = \varepsilon - \frac{\varepsilon^2}{k}$$

$$D < 0 \therefore \text{saddle}$$