

Canonical Perturbation Theory:

Solar P.T., Tides, Island Formation

Canonical Perturbation Theory - An Introduction

→ not surprisingly, few systems are integrable, in sense of action-angle variables, i.e.

can be written as: $H = H(I_1, \dots, I_n)$

$$\dot{I}_c = 0, \quad \forall c.$$

$$\frac{\partial H}{\partial \dot{Q}_c} = 0$$

$$\dot{\Theta}_c = \frac{\partial H}{\partial I_c}$$

$$\dot{\Theta}_c = \omega(I_c) + \dot{\Theta}_c^*$$

→ thus, frequently encounter/view the system as perturbation about integrable system

e.g. for 1 degree of freedom:

$$H = H_0(I) + G(H, I, \Theta)$$

\uparrow
unperturbed
integrable
motion

→ perturbation \rightleftarrows
breaks symmetry.

→ seek to "integrate" H perturbatively, where "integrate" \Rightarrow

(old) (new)

canonically transform $I, \Theta \rightarrow J, \phi$

such that: $\dot{J} = 0 \quad \left. \begin{array}{l} \dot{\phi} = \omega(J) \\ \omega = \omega(J) \end{array} \right\} \text{to specified order in } P.T.$

obviously understand here that:

$$\begin{aligned} J &= I + O(\epsilon) \\ \phi &= \Theta + O(\epsilon) \quad \text{etc} \end{aligned}$$

→ Proceeding:

- note structure:

old: I, Θ

s.t. $J = 0$, to $O(\epsilon)$

new: J, ϕ

{ known property of new Hamiltonian }

⇒ type 2, also $H - J$, transformation:

$$\begin{array}{l} p \leftrightarrow I, \quad q \leftrightarrow J \\ q \leftrightarrow \Theta, \quad Q \leftrightarrow \phi \end{array}$$

and under dep

$$\begin{array}{l} q \leftrightarrow \Theta \\ p \leftrightarrow I \\ Q \leftrightarrow \phi \end{array}$$

so, can write

$$C_p = \frac{\partial F}{\partial q} = \frac{\partial S}{\partial q} \Rightarrow I = \frac{\partial S}{\partial \Theta}$$

($F = S$, here)

$$Q = \frac{\partial F}{\partial P} = \frac{\partial S}{\partial P} \Rightarrow \phi = \frac{\partial S}{\partial J}$$

But here?

$$S = S_0 + \epsilon S_1 + \dots$$

$$H'(J) \equiv k(J) = k_0(J) + \epsilon k_1(J) + \dots$$

$$\underset{S}{\underbrace{}} \quad (\text{re-label})$$

New Hamiltonian
(fctn J only)

$$\Rightarrow k(J) = H(I, \theta)$$

$$= H_0\left(\frac{\partial S}{\partial \theta}, \theta\right) + \epsilon H_1\left(\frac{\partial S}{\partial \theta}, \theta\right) + \dots$$

Now here, $S = S_0 + \epsilon S_1$
 $J = I + \epsilon \tilde{I}$
 $\phi = \theta + \epsilon \tilde{\theta}$
 $\rightarrow \text{old } \tilde{I}$

$$\therefore S_0 = J\theta \quad (I = \bar{J}, \phi = \theta \text{ to lowest order})$$

\uparrow
new θ

$$\underline{\underline{S_0}} \quad \underline{\underline{P}} = J\theta + \epsilon S_1 + \dots$$

- Now plugging S into $H' = k = H$
equation:

$$K_0(J) + \epsilon K_1(J) + \epsilon^2 K_2(J) + \dots$$

$$= H_0 \left(J + \epsilon \frac{\partial S_1}{\partial \theta} + \epsilon^2 \frac{\partial S_2}{\partial \theta} + \dots \right)$$

$$+ \epsilon H_1 \left(J + \epsilon \frac{\partial S_1}{\partial \theta} + \dots, \theta \right)$$

grinding it out:

to $\mathcal{O}(\epsilon^2)$

$$\begin{aligned} K_0(J) + \epsilon K_1(J) + \epsilon^2 K_2(J) &= H_0(J) + \epsilon \frac{\partial S_1}{\partial \theta} \frac{\partial H_0}{\partial J} \\ &+ \epsilon^2 \frac{\partial S_2}{\partial \theta} \frac{\partial H_0}{\partial J} + \epsilon H_1(J, \theta) + \epsilon^2 \frac{\partial S_1}{\partial \theta} \frac{\partial H_1}{\partial J} \\ &+ \frac{1}{2} \epsilon^2 \left(\frac{\partial S_1}{\partial \theta} \right)^2 \frac{\partial^2 H_0}{\partial J^2} \end{aligned}$$

matching term-by-term:

$$H_0 = K_0$$

$$K_1(J) = \frac{\partial S_1}{\partial \theta} \frac{\partial H_0}{\partial J} + H_1(J, \theta)$$

if
S

$$K_2(J) = \frac{1}{2} \left(\frac{\partial S_1}{\partial \theta} \right)^2 \frac{\partial^2 H_0}{\partial J^2} + \frac{\partial S_2}{\partial \theta} \frac{\partial H_0}{\partial J} + \frac{\partial S_1}{\partial \theta} \frac{\partial H_1}{\partial J} + H_2$$

etc.

For $\mathcal{O}(G)$:

$$K(J) = \frac{\partial S}{\partial \theta} \frac{\partial H_0}{\partial J} + H_1(J, \theta)$$

$$= \frac{\partial S}{\partial \theta} w_0(J) + H_1(J, \theta)$$

where understand : $J = \partial S / \partial \phi$
 $= I + \epsilon \frac{\partial S}{\partial \phi}$

and $\phi = \frac{\partial S}{\partial J} = \theta + \epsilon \frac{\partial S}{\partial J}$

$$\left\{ \begin{array}{l} \theta = \phi - \epsilon \frac{\partial S}{\partial J} \\ I = J + \epsilon \frac{\partial S}{\partial \phi} \end{array} \right.$$

Now, if define:

$$H_1 = \langle H_1 \rangle + \tilde{H}_1$$

$$\langle H_1 \rangle = \int_0^{2\pi} \frac{d\theta}{2\pi} H_1$$

Can average :

$$\Rightarrow \boxed{K_1(J) = \langle H_1 \rangle}$$

but need $S_1 \leftrightarrow$ obtain from solvability

$$W_0(J) \frac{\partial S_1}{\partial \theta} = K_1(J) - \tilde{H}_1 \\ = K_1(J) - \langle H_1 \rangle - \tilde{H}_1$$

$$\therefore \boxed{W_0(J) \frac{\partial S_1}{\partial \theta} = -\tilde{H}_1}$$

$$\text{Now, } \tilde{H}_1 = \sum_{n=1}^{\infty} H_n(J) e^{cn\theta}$$

$$S_1 = \sum_{n=1}^{\infty} S_n e^{cn\theta}$$

$$\text{so } S = J\theta + S_1$$

$$S_1 = \sum_n -\frac{H_n(J)}{i n W_0(J)} e^{cn\theta}$$

so finally can write full solution to O(E):

$$\phi = \theta + \epsilon \frac{\partial S_1(J, \theta)}{\partial J}$$

$$J = I - \epsilon \frac{\partial S_1(J, \theta)}{\partial \theta}$$

$$\omega = \omega_0(J) + \epsilon \frac{\partial K_1(J)}{\partial J}$$

where: $K_1 = \langle H_1 \rangle_0$

$$S_1 = \sum_n \frac{\sin \theta_n(J)}{n \omega_0(J)} e^{in\theta}$$

Now:

- if multi-degrees freedom

$$\theta \rightarrow \underline{\theta}$$

$$n \omega_0(J) = n \cdot \underline{\omega_0(J)}$$

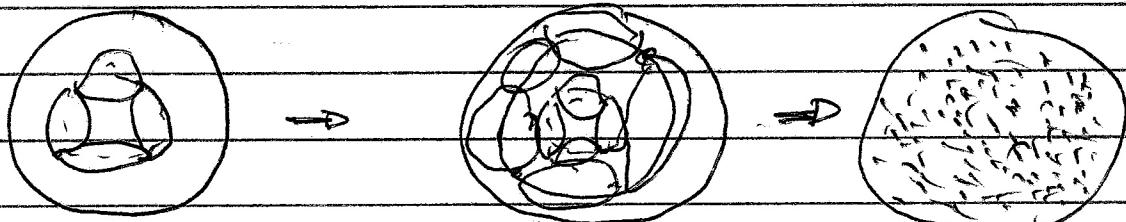
'small denominators' (at) resonant tori
 what happens to tori?

\Rightarrow presents strong question re: convergence
 of perturbation expansion.

- Resolution:

- KAM theorem: '(Most) surfaces preserved. Destruction limited to $O(\epsilon)$ volume.'
- Chaos ('seeded') at resonant/rational force, where islands form. Island overlap \Rightarrow Volume filling chaos

i.e.



(1)

Some examples:

i.) Trivial \rightarrow Pendulum (yet again)

For simple pendulum,

$$H_p = \frac{1}{2} G p^2 - F \cos \phi = E$$

(M.E.)

expanding: $H_p = \frac{1}{2} G p^2 - \cancel{F} + \frac{1}{2} F \phi^2 - \frac{F \phi^4}{4}$

can take $E \rightarrow 1$
at end.

$$\therefore H = H_0 + \epsilon H_1$$

$\stackrel{\circ}{\text{S}}$
next order term

$$H_0 = \frac{1}{2} G p^2 + \frac{1}{2} F \phi^2$$

$$H_1 = -\frac{F \phi^4}{4!}$$

I) Canonical Form

Know: $H_0 = I \omega$ $(I = E/\omega)$

use canonical transformation:

$$q = (2I/R)^{1/2} \sin \theta$$

$$R = (F/G)^{1/2}$$

$$p = (2IR)^{1/2} \cos \theta$$

$$\omega = (FG)^{1/2}$$

(2)

$$\textcircled{a} \quad H = \omega_0 J = \frac{\epsilon G J^2}{6} \sin^4 \theta$$

$$H_1 = -\frac{G J^2}{48} (3 - 4 \cos 2\theta + \cos 4\theta)$$

seek ?

- correction to Hamiltonian and frequency
- generating function

For new Hamiltonian \bar{H} :

$$\bar{H} = H_0(J) + \epsilon \langle H_1(J, \bar{\theta}) \rangle$$

$$\langle \rangle = \frac{1}{2\pi} \int_0^{2\pi}$$

$$\bar{H} = \omega_0 J - \frac{\epsilon G J^2}{16}$$

upon averaging

$$\omega = \frac{\partial \bar{H}}{\partial J} = \omega_0 - \frac{\epsilon G J}{8}$$

N.B. Perturbation
lowers freq.

$$\text{and } \omega \frac{\partial S_1}{\partial \bar{\theta}} = -(H_1 - \langle H_1 \rangle)$$

$$\Rightarrow \left[S_1 = -\frac{G J^2}{192 \omega} (8 \sin 2\theta - \sin 4\theta) \right]$$

(3)

(c) Explicit Time Dependence

i.e. Consider: $H = H_0(\underline{J}) + \epsilon H_1(\underline{J}, \theta, t)$

$$\therefore \rightarrow H_1 = \sum_{e, m} H_{1, e, m}(\underline{J}) e^{i(l\theta + m\omega t)}$$

{expand in space
time harmonics}

\Rightarrow now must use C.T.

expression:

$$\begin{aligned} \bar{H} &= H + \frac{\partial F}{\partial t} \\ &= H + \epsilon \frac{\partial S}{\partial t}, \end{aligned}$$

{time derivative of
generating function
enters transformation
of F in H }

$$\text{Now, } S' = J\theta + \epsilon S, (\underline{J}, \theta, t)$$

$$\bar{H}(\underline{J}, \theta, t) = H(\underline{J}, \theta, t) + \frac{\epsilon \partial S}{\partial t}$$

$$\Rightarrow \bar{H}_0 = H_0(\underline{J})$$

$$\bar{H}_1 = \frac{\partial S}{\partial t} + \omega \frac{\partial S}{\partial \theta} + H_1, \quad (\text{out})$$

- Now... must choose S , to eliminate
oscillating part of H_1 , i.e.

(4)

→ to eliminate, need average over space and time

i.e.

$$\bar{H} = H_0 + \epsilon \langle H_i \rangle_{\theta, t}, \quad \left\{ \begin{array}{l} \omega = \omega_0 + \epsilon \langle \dot{H}_i \rangle \\ \nabla \end{array} \right.$$

$$\frac{\partial S_i}{\partial t} + \omega \frac{\partial S_i}{\partial \theta} = -H_i \quad (\text{E out})$$

so

$$S_i = c \sum_{\ell, m \neq 0} \frac{H_i e_m \exp[i(\ell \bar{\theta} + m \bar{\Omega} t)]}{\ell \bar{\omega} + m \bar{\Omega}}$$

- all 2 deg freedom, have potentially singular denominator

i.e. $\underline{m} \cdot \underline{\omega} = 0$

here, $\ell \bar{\omega} + m \bar{\Omega} = 0 \Rightarrow m = -1$

$(H_i \sim E)$ wave-particle resonance!

→ General Properties of Motion in 5 dimensions.

system

Now, consider:

- 5 degrees of freedom (arbitrary)
- separable H-J. equation

$$S = \sum_{i=1}^5 S_i(E) \quad (\text{i.e. integrable})$$

∴ can define 5 action variables I_i

$$I_i = \int \frac{p_i d\varphi_i}{(2\pi)}$$

and $\dot{\varphi}_i = \partial S_0 / \partial I_i$ angle variables

so

$$\dot{I}_i = 0$$

$$\dot{\varphi}_i = \omega_i(E) + f_i$$

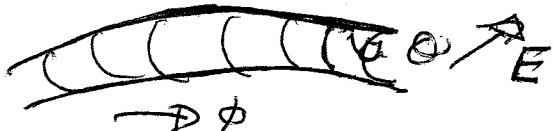
$$\omega_i(E) = \partial E / \partial I_i$$

i.e. for $S = 2$

$$\dot{I}_1 = \dot{I}_2 = 0$$

$$\omega_1 = \partial F / \partial I_1$$

$$\dot{\varphi}_1 = \omega_1(E) t + f_1$$



∴ phase space is 2 torus. Fixed $E \Rightarrow$
motion on toroidal surface.

[In general, phase space is S -torus.]

$$\begin{aligned}\theta &= \omega_1(E)t \\ \phi &= \omega_2(E)t\end{aligned}\quad \begin{aligned}\theta &= \frac{\omega_1(E)}{\omega_2(E)}\phi\end{aligned}$$

→ Now, for any $F(\underline{E}, \underline{\phi})$, can write:

$$F = \sum_{l_1} \sum_{l_2} \dots \sum_{l_s} A_{l_1, l_2, \dots, l_s} \exp \left[i(l_1 \theta_1 + l_2 \theta_2 + \dots + l_s \theta_s) \right]$$

l_1, l_2, \dots, l_s integ. $\in \mathbb{R}$.

equivalently:

$$F = \sum_{l_1} \sum_{l_2} \dots \sum_{l_s} A_{l_1, l_2, \dots, l_s} \exp \left[it \left(\underline{l} \cdot \frac{\partial \underline{E}}{\partial \underline{I}} \right) \right]$$

$$\underline{l} \cdot \frac{\partial \underline{E}}{\partial \underline{I}} = l_1 \frac{\partial E}{\partial I_1} + l_2 \frac{\partial E}{\partial I_2} + \dots + l_s \frac{\partial E}{\partial I_s}$$

Now, in general:

→ frequencies not commensurate, so F not periodic i.e. $\frac{\partial \dot{E}}{\partial I}$ irrational

→ indeed, system generally not periodic in any coordinate (except for special E).

but for sufficient time, system will come arbitrarily close to starting point.

→ Poincaré Recurrence Thm.



sufficient windings

∴ motion is "conditionally" periodic.

But; degeneracy happens!

- degeneracy $\wedge \omega_i = m\omega_j$

- all I 's commensurate \Rightarrow complete degeneracy.

So, as in Kepler problem, \Rightarrow degeneracy implies reduction in number of independent I_i . Why?

Commensurate frequencies \Rightarrow

$$\gamma, \omega_1 = n_2 \omega_2$$

$$\text{then } \frac{\partial E}{\partial I_1} = n_2 \frac{\partial E}{\partial I_2}$$

$$\text{so } E = E(n_2 I_1 + n_1 I_2)$$

i.e. - energy depends on sum of action variables

\Rightarrow

- degeneracy

\Rightarrow

- can make canonical transformation

$$\text{so } E = E(I'), \text{ only.}$$

\Rightarrow i.e. in degenerate motion, there is an increase in the number of one-valued integrals of the motion, relative to non-degenerate case.

C.e. non-degenerate motion - s degs freedom

$$2s-1 \rightarrow \text{IOM's.}$$

$\int s$ values $I_i \rightarrow$ single valued I_i

$\{s-1\}$ values at $\partial_i \partial E / \partial I_k - \partial_k \partial E / \partial I_i$

note: $S-1$ values \rightarrow phases (i.e.'s) of angle variables.

\rightarrow not single valued.

but if degeneracy, note though

$\rightarrow n_1\theta_1 - n_2\theta_2$ not single valued

\Leftrightarrow to addition of 2π

so

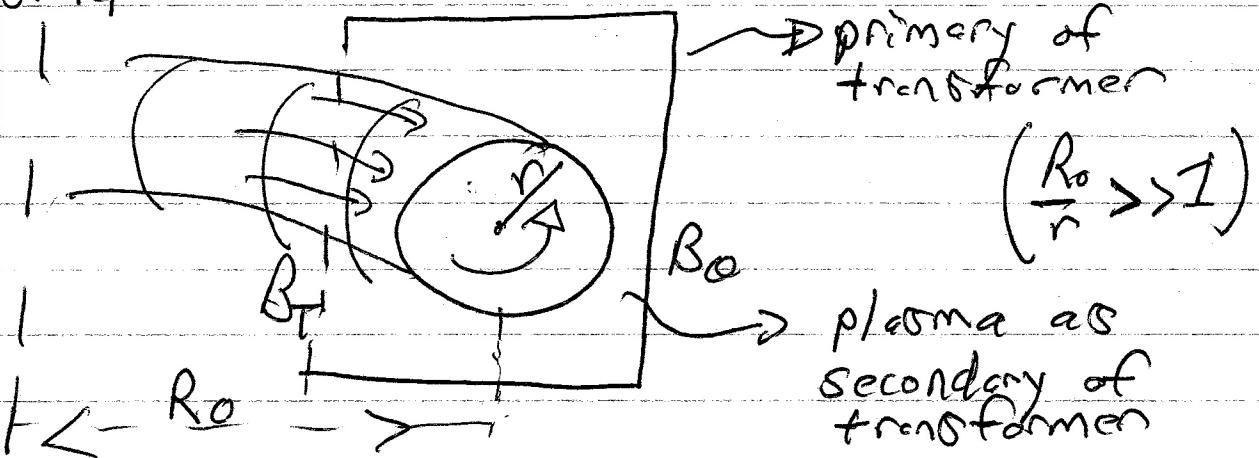
$\rightarrow \sin(n_1\theta_1 - n_2\theta_2)$ etc single valued,

(Case Study)

→ side: Magnetic Field Lines on a Tokamak:
A Practical Example of Phase Space
Evolution on Tori

→ What is a Tokamak?

- toroidal confinement device for magnetized plasma



$$I = I_0 \Rightarrow B(T) = \frac{2I_0}{r} \rightarrow \text{toroidal field (external)}$$

$$B_T \gg B_0 \quad B_0(r) = \int_0^r \frac{8\pi r' J_T(r')}{c} dr' \rightarrow \text{poloidal field (plasma current)}$$

- $B_0(r)$ → shorts out charge separation due to DB drift
→ stability, confinement
→ heating (Ohmic)

more info: "Tokamak Plasma, A Complex Physical System"
B.B. Kadomtsev

~ Minimal Model: The "Toroidal Cow" for Toroidal Field Configurations

- tokamak as periodic cylinder with:

$$\left. \begin{array}{l} 0 < r < a \\ L = 2\pi R_0 \end{array} \right\} \left. \begin{array}{l} B_z = B_T \quad (\text{uniform external}) \\ B_\theta(r) \end{array} \right\}$$

$$\langle \underline{B} \rangle = B_\theta(r) \hat{\theta} + B_z \hat{z}$$

$$\underline{B} = \langle \underline{B} \rangle + \tilde{\underline{B}}_\perp$$

- field line: $\frac{dz}{B_T} = \frac{rd\theta}{B_\theta(r) + \tilde{B}_\theta} = \frac{dr}{\tilde{B}_r}$

$$\frac{d\theta}{dz} = \pm \frac{B_\theta(r) + \tilde{B}_\theta}{B_z} \approx \pm \frac{1}{r} \frac{B_\theta(r)}{B_z} \quad \tilde{B}_\theta \ll B_\theta(r)$$

$$\frac{dr}{dz} = \frac{\tilde{B}_r}{B_z}$$

For un-perturbed field configuration:

$$\frac{d\theta}{dz} = \frac{1}{r} \frac{B_\theta(r)}{B_z} = \frac{1}{R q(r)} ; \quad q(r) \equiv B_z r / R B_\theta(r)$$

↓
Safety factor

$$\frac{dr}{dz} = 0 \quad (\text{no radial wandering})$$

$\tilde{z}(r) \equiv$ winding rate (c.c. rotational transform)
 (# poloidal circuits per toroidal)

→ Relation to Hamiltonian Dynamics \vec{P} ,
 $\frac{dx}{dt} = \tilde{B}_x, \frac{dy}{dt} = \tilde{B}_y \quad \vec{B} \cdot \vec{B} = 0 \Rightarrow H_m$.

Useful to observe similarity between:

a) Hamiltonian System with:

$$H = H(x, y) \text{ so } \begin{cases} \dot{x} = -\partial H / \partial y \\ \dot{y} = \partial H / \partial x \end{cases} \quad (\nabla \cdot \vec{V}_H = 0)$$

so Liouville Eqn. for $f(t, x, y)$ is:

$$\frac{\partial f}{\partial t} + \dot{x} \frac{\partial f}{\partial x} + \dot{y} \frac{\partial f}{\partial y} = 0$$

$$\therefore \frac{\partial f}{\partial t} - \frac{\partial H}{\partial y} \frac{\partial f}{\partial x} + \frac{\partial H}{\partial x} \frac{\partial f}{\partial y} = 0$$

Can further specialize: $H = H_0(x) + \tilde{H}(x, y)$

$$\Rightarrow \begin{cases} \dot{x} = -\partial \tilde{H} / \partial y \\ \dot{y} = \frac{\partial H_0}{\partial x} + \frac{\partial \tilde{H}}{\partial x} \end{cases}$$

and

$$\frac{\partial f}{\partial t} + \frac{\partial H_0}{\partial x} \frac{\partial f}{\partial y} - \frac{\partial \tilde{H}}{\partial y} \frac{\partial f}{\partial x} + \frac{\partial \tilde{H}}{\partial x} \frac{\partial f}{\partial y} = 0$$

$$\Rightarrow \frac{\partial f}{\partial t} + v_y(x) \frac{\partial f}{\partial y} + \{\tilde{H}, f\} = 0$$

e.g. $\begin{cases} H = \phi(r, \theta) \\ G.C. plasma \end{cases}$

b) Equation for Magnetic Flux
 $\psi(r, \theta)$

$$\underline{B} = B_0 \hat{z} + \nabla \psi \times \hat{z} \rightarrow \underline{B} \text{ field} \quad \psi = A_z(r, \theta)$$

$$\psi = \langle \psi(r) \rangle + \tilde{\psi}(r, \theta) \rightarrow \text{Magnetic flux function}$$

then, by definition:

$$\underline{B} \cdot \nabla \psi = 0$$

(Flux constant along magnetic field lines)



$$\left(B_0 \frac{\partial}{\partial z} + \frac{B_0(r)}{r} \frac{\partial}{\partial \theta} + \tilde{B}_z \cdot \nabla_z \right) \psi = 0$$

$r \rightarrow$

$$\left(\frac{\partial}{\partial z} + \frac{1}{R_E(r)} \frac{\partial}{\partial \theta} + \frac{\tilde{B}_z \cdot \nabla_z}{B_0} \right) \psi = 0$$

, can read off analogy: (isomorphism)

$$\left\{ \begin{array}{l} z \leftrightarrow t, r \mapsto x, rd\theta \mapsto y \end{array} \right.$$

$$\left\{ \begin{array}{l} 1/R_E(r) \leftrightarrow V_y(x) \leftrightarrow \omega(I) \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{\partial \omega(I)}{\partial I} \neq 0 \Rightarrow z'(r) \neq 0 \text{ "shear"} \\ (\text{winding rate varies with radius}) \end{array} \right.$$

$$\left\{ \begin{array}{l} \langle V_y(x) \rangle \mapsto B_0(r) \end{array} \right.$$

$$\left\{ \begin{array}{l} \tilde{B}_\perp \mapsto \nabla \tilde{H} \times \hat{z} \end{array} \right.$$

$$\left\{ \begin{array}{l} \tilde{D}_\perp \cdot \tilde{B}_\perp = 0 \\ \nabla \cdot (\tilde{D} \tilde{H} \times \hat{z}) = 0 \end{array} \right.$$

Liouville Thm.

($\underline{D} \cdot \underline{B} = 0$ underlies Hamiltonian structure)

Thus, Hamiltonian trajectory on 2-torus in phase space (for 2 degs. freedom) equivalent to trajectory of magnetic field line on torus of radius (minor) = r in space!

$$\left\{ \begin{array}{l} p \mapsto I \end{array} \right.$$

$$\left\{ \begin{array}{l} 1/R_E(r) \leftrightarrow \omega(I) \end{array} \right.$$

$$\left\{ \begin{array}{l} \theta \mapsto \phi \quad (\text{angle variable}) \end{array} \right.$$

An Observation

Consider solution of flux equation perturbatively
i.e.

$$\underline{B} = \underline{B}_0 + \tilde{\underline{B}} \quad \underline{B}_0 = B_0 \hat{z} + B_0 \hat{\theta}$$

$$\psi = \langle \psi(r) \rangle + \tilde{\psi}$$

$$\underline{B} \cdot \nabla \psi = 0 \Rightarrow$$

$$(\underline{B}_0 \cdot \nabla) \tilde{\psi} = - \tilde{B}_r \frac{\partial}{\partial r} \langle \psi(r) \rangle$$

expand $\tilde{\psi}, \tilde{B}_r$ as:

$$\tilde{B}_r = \sum_{m,n} \tilde{B}_{r,n} e^{im\theta - n\phi}$$

$$z \rightarrow R\phi$$

\Rightarrow

$$\left(-\frac{in}{R} B_0 + \frac{im}{R} B_0 \right) \tilde{\psi}_m = - \tilde{B}_{r,m} \frac{\partial \langle \psi(r) \rangle}{\partial r}$$

$$\tilde{\psi}_{m,n}(r) = \frac{- \tilde{B}_{r,m}(r) \partial \langle \psi(r) \rangle / \partial r}{-\frac{i}{R} \frac{B_0}{R} (n - \frac{m}{Z(r)})}$$

$$\sim \tilde{\psi}_{m,n}(r) = i R \underbrace{\left(\frac{\tilde{B}_n^m(r)/B_0}{n} \right)}_{\left(1 - \frac{m}{z(r)} \right)} \partial \langle \psi(r) \rangle / \partial r$$

\Rightarrow perturbative solution diverges at
 $z(r) = m/n$ \Rightarrow defines resonant surface
 (special tori)

c.e. radius where pitch of field line ($z(r)$)
resonates with pitch of perturbation
 (m/n)

\Rightarrow linear solution to Liouville Egn. fails here.

$$\underline{n} \cdot \underline{\omega} = 0$$

(resonances)

- Consequences of Phase Space Structure of Integrable Systems : Discussion and Examples

- consider integrable system with n degs. of freedom

then:

- can identify dimensions (generic)

$$1) \text{ phase space} : d_p = 2n$$

$$2) \text{ energy shell} : d_E = 2n - 1$$

$$3) \text{ torus} : d_T = n$$

and

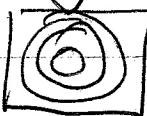
n	1	1	2	3	etc
d_p	2	1	4	6	
d_E	1		3	5	
d_T	1	1	2	3	
\dots			.	.	

For 1D, energy shell and tori have $d=1$

\Rightarrow tori fill energy shell

\therefore 1D systems ergodic (fill allowed pieces of Γ^T)

⇒ $n=2$; 2D tori embedded in 3D energy shell

∴ integrable system \Rightarrow tori fill energy shell
 {nested}

non-integrable system \Rightarrow gaps between
 {nested tori}

\Leftrightarrow trajectory in gap can't escape

→ $n=3$, can escape \Rightarrow Arnold diffusion.

- Motion on Tori

→ can generalize tokamak field-line representation to write

$$\begin{aligned} z_i(t) &= \sum_{k_1=-\infty}^{+\infty} \dots \sum_{k_n=-\infty}^{+\infty} a_{k_1, \dots, k_n}^{(i)} e^{i(k_1 \omega_1 + \dots + k_n \omega_n)} \\ &= \sum_{k_1} \dots \sum_{k_n} a_{k_1, \dots, k_n}^{(i)} e^{i(k_1 \omega_1 + k_2 \omega_2 + \dots + k_n \omega_n)} e^{i\phi} \end{aligned}$$

$\stackrel{\text{def}}{=}$ $k_1, \dots, k_n \rightarrow$ quantum #'s for periodic motion
 (i.e. $k_i = 1, 2, \dots$)

$$\tilde{x}_k^i(T) = \int_0^{2\pi} d\theta_1 \dots \int_0^{2\pi} d\theta_n q_i e^{i(k_1 \theta_1 + \dots + k_n \theta_n)}$$

in A^2 variables

thus, $q_i(t)$ on torus is:

- multiply periodic
- $\sum_k k_x \omega_x \neq 2\pi \Rightarrow$ quasi-periodic orbit
 (not on resonant surface) \Rightarrow orbit fills surface of torus ergodically

i.e. for $n=2$; $\omega_1/\omega_2 = m/n$ rational
 $\left\{ \begin{array}{l} \text{closed orbit} \\ (\text{small denominator}) \end{array} \right.$
 \Rightarrow line does not fill 2-torus, rather closed on self.

but $\omega_1/\omega_2 = \text{irrational}$
 \Rightarrow open orbit, so line ergodic on 2-torus

Observe: Since rationals are set with $M=0$
 \approx on real ~~#~~, tori with open trajectories (ergodically covering tori)
 vastly outnumber resonant tori with closed orbits.

2. Secular Perturbation Theory

- strategy is to remove resonances via transformation to frame co-rotating with resonant variables
- akin removing resonance by frame change as in 1D particle motion
- limitation is removal one fast variable, only possible,

Observe:

$$H = H_0(\underline{I}) + \epsilon H_1(\underline{I}, \underline{\theta})$$

then if $r\omega_1 - s\omega_2 = 0$ (resonance)

$$\Rightarrow \dot{\underline{\theta}} = r\underline{\theta}_1 - s\underline{\theta}_2$$

i.e. "slow" variable

$$\text{c.e. } \left(\underline{\omega} \cdot \frac{\partial}{\partial \underline{\theta}} \right) f(\underline{\theta}) = \left(\omega_1 \frac{\partial}{\partial \theta_1} + \omega_2 \frac{\partial}{\partial \theta_2} \right) f(r\theta_1 - s\theta_2)$$

$$= (r\omega_1 - s\omega_2) \frac{\partial f}{\partial \underline{\theta}} = 0$$

↗ near reson. $\underline{\theta}$

\Rightarrow f dependence on $\underline{\theta}$ is higher order
c.e. slow.

thus, in simplest case, canonical P.T. \Rightarrow

$$\text{C.-T. : } \underline{I}, \underline{\theta} \rightarrow \underline{\tilde{J}}, \underline{\phi}$$

here, canonical transform from 2 variables
(both 'fast') to 1 slow, 1 fast variable

i.e.

$$\begin{cases} I_1, \theta_1 \\ I_2, \theta_2 \end{cases} \Rightarrow \begin{cases} r\theta_1 - s\theta_2, \tilde{J}_1 \\ \theta_2, \tilde{J}_2 \end{cases} \quad (\text{hence} \rightarrow \text{2 variables})$$

i.e. same generic form as before, but
eliminates 1 'fast' motion.

$$\begin{aligned} \text{i.e. } F &= S(\text{old positions, new momenta}) \\ &= S(\theta_1, \theta_2; \tilde{J}_1, \tilde{J}_2) \end{aligned}$$

\Rightarrow type 2, with:

$$S = (r\theta_1 - s\theta_2)\tilde{J}_1 + \theta_2\tilde{J}_2 + \epsilon S'$$

$$I_1 = \partial S / \partial \theta_1 = r\tilde{J}_1 + \epsilon \frac{\partial S'}{\partial \theta_1}$$

$$I_2 = \partial S / \partial \theta_2 = (\tilde{J}_2 - s\tilde{J}_1) + \epsilon \frac{\partial S'}{\partial \theta_2}$$

$$\phi_1 = \partial S / \partial \tilde{J}_1 = r\theta_1 - s\theta_2 + O(\epsilon)$$

$$\phi_2 = \partial S / \partial \tilde{J}_2 = \theta_2 + O(\epsilon)$$

$$H = H_0(\underline{I}) + \epsilon H_1(\underline{I}, \underline{\theta})$$

$$H_1 = \sum_{\ell, m} H_{\ell, m}(\underline{I}) e^{i(\ell \theta_1 + m \theta_2)}$$

take $\ell, m \neq 0$

$$\text{but know, } \phi_1 = r \theta_1 - s \theta_2$$

$$\phi_2 = \theta_2$$

$$\therefore \begin{cases} \theta_1 = (\phi_1 + s\phi_2)/r \\ \theta_2 = r\phi_2/r \end{cases}$$

\Rightarrow re-writing H_1 :

$$H_1 = \sum_{\ell, m} H_{\ell, m}(\hat{\underline{I}}) \exp \left[i \frac{\ell}{r} (\phi_1 + s\phi_2) + i m \phi_2 \right]$$

$$= \sum_{\ell, m} H_{\ell, m}(\hat{\underline{I}}) \exp \left[i \left(\frac{\ell}{r} \phi_1 + \frac{(\ell s + m r)}{r} \phi_2 \right) \right]$$

Now, $\phi_2 \rightarrow$ fast dependence

$\phi_1 \rightarrow$ slow dependence

\therefore average out ϕ_2 dependence. CRITICAL
 to note averaging only valid near resonance (distinguishing fast, slow dependence)
 enabled near resonance, only.

thus, here:

$$k_1 = k_1(\hat{J}, \phi_1) = \langle H_1 \rangle_{\phi_2} \quad \begin{array}{l} \text{slow} \\ \downarrow \\ \text{i.e. avg.} \\ \text{out fast} \\ \text{dependence} \end{array}$$

$$= \left\langle \sum_{l,m} H_{l,m}(\hat{J}) \exp \left[i \frac{l}{r} \phi_1 + i \frac{l}{r} (ls + mr) \phi_2 \right] \right\rangle_{\phi_2}$$

$\therefore ls = -mr$ selected by avgd. sum

$$\Rightarrow \frac{l}{m} = -\frac{r}{s} = \frac{\omega_2}{\omega_1} \Rightarrow \text{resonance}$$

$$\langle H_1 \rangle_{\phi_2} = \sum_{p=0}^{\infty} H_1 e^{(p\phi_2 + ps)} e^{-i p \phi_1}$$

$$= \sum_{p=0}^{\infty} H_1 e^{-ip\phi_1} \quad ; \quad \begin{cases} \text{i.e. sum over} \\ \text{all harmonics} \\ \text{of resonant pair} \end{cases}$$

so averaged Hamiltonian:

$$\langle H \rangle = H_0(\hat{J}) + \epsilon \sum_{p=0}^{\infty} H_{-pr}^{(1)} e^{-ip\phi_1}$$

Now

$$\frac{\partial \langle H \rangle}{\partial \phi_2} = 0 \Rightarrow \frac{d \hat{J}_2}{dt} = 0$$

but from C-T_i rules:

$$I_1 = r \hat{J}_1$$

$$I_i = \frac{\partial S}{\partial \phi_i}$$

$$I_2 = \hat{J}_2 - s \hat{J}_1$$

$$\Rightarrow \hat{J}_2 = I_2 + \frac{s}{r} I_1$$

} have identified modified (adiabatic) in variant $\hat{J}_2 = I_2 + \frac{s}{r} I_1$ via

transformation

↳ invariant of avg. Hamiltonian

$$\Rightarrow \frac{d \hat{J}_2}{dt} = 0 \Rightarrow \frac{d \hat{\phi}_2}{dt} = \frac{\partial \langle H \rangle}{\partial \hat{J}_2} = \omega(\hat{J}_2)$$

$$\text{Now } \langle H \rangle = \langle H(\hat{J}_1, \phi_1; \hat{J}_2, \phi_2) \rangle$$

For full solution, need understand \hat{J}_1, ϕ_1
not ion.

Now; can, without loss of generality, simplify remaining calculation by:

- assuming $\rho = \phi_0 \pm i\bar{J}_0$ harmonics only contribute to ϕ_i, \bar{J}_i evolution \Rightarrow

$$\begin{aligned} \text{i.e. } \langle H \rangle &= H_0(\bar{J}) + \epsilon H_{0,0}(\bar{J}) \\ &\quad + 2\epsilon H_{0,-8}(\bar{J}) \cos \phi_i, \\ &= H_0(\bar{J}) + \epsilon H_{0,0}(\bar{J}) + 2\epsilon H_{0,-8}(\bar{J}) \cos \phi_i \end{aligned}$$

($H_{-n,s} = H_{n,-s}$; many problems feature 1 relevant harmonic, only).

- seek fixed points, frequency motion about fixed pts. (i.e. $\langle H \rangle$ is effectively that of oscillator/pendulum), $H = \frac{1}{2} I \dot{\phi}^2 + mgl(1 - \cos \phi)$

[General procedure: Fixed pts.
and proximal (linear) stability]

fixed pts:

$$\frac{\partial \langle H \rangle}{\partial \phi_i} = 0 \Rightarrow \dot{\bar{J}}_i = 0 \quad (\dot{\bar{J}}_2 = 0 \text{ already})$$

$$\frac{\partial \langle H \rangle}{\partial \bar{J}_i} = 0 \Rightarrow \dot{\phi}_i = 0$$

these define $\begin{cases} \bar{J}_{1,0} \\ \dot{\phi}_{1,0} \end{cases} \left. \right\} \begin{cases} \text{Fixed pts.} \\ \text{not motion} \end{cases}$

\vec{t} ,

$$\frac{\partial \langle H \rangle}{\partial J_1} = 0 \Rightarrow \frac{\partial H_0(\vec{I})}{\partial J_1} + \epsilon \frac{\partial H_{0,0}(\vec{J})}{\partial J_1}$$

$$+ 2\epsilon \frac{\partial H_{0,-s}^{(1)}}{\partial J_1} \cos \phi_1 = 0$$

$$\frac{\partial \langle H \rangle}{\partial J_2} = 0 \Rightarrow -2\epsilon H_{0,-s}^{(1)} \sin \phi_1 = 0$$

$$\phi_1 = 0, \pm\pi, \dots$$

Now,

$$\begin{aligned} \frac{\partial}{\partial J_1} &= \frac{d I_1}{d \vec{J}_1} \frac{\partial}{\partial I_1} + \frac{d I_2}{d \vec{J}_1} \frac{\partial}{\partial I_2} \\ &= r \frac{\partial}{\partial I_1} - s \frac{\partial}{\partial I_2} \end{aligned}$$

\Rightarrow have fixed pt. conditions:

$$0 = \left(r \frac{\partial}{\partial I_1} - s \frac{\partial}{\partial I_2} \right) H_0(\vec{I})$$

$$+ \epsilon \frac{\partial}{\partial J_1} H_{0,0} + 2\epsilon \frac{\partial H_{0,-s}^{(1)}}{\partial J_1} \cos \phi_1$$

$$= (r\omega_1 - s\omega_2) + \epsilon \left(\frac{\partial H_{0,0}}{\partial J_1} + \frac{\partial H_{0,-s}^{(1)}}{\partial J_1} \cos \phi_1 \right)$$

(Resonance! ~ 0)

note, to lowest order, \Rightarrow

$$\omega = r\omega_1 - s\omega_2 \Rightarrow \hat{J}_{1,0} \text{ defined by resonant surface condition}$$

ex. : - field lines on torus $\Rightarrow \varphi(r) = m/n$
 $r = \varphi^{-1}(m/n)$

\uparrow
resonant, rational torus rods

- wave-particle interaction

$$\frac{\omega}{k} = V.$$

and $-2eH_{j=0}^{(1)} \sin\phi_i = 0.$

Now, as seek simplified Hamiltonian in form of pendulum, convenient to expand H about $\hat{J}_{1,0}$, i.e. :

$$\begin{aligned} \langle H(\hat{J}_1, \phi_i) \rangle &= [H_0(\hat{J}_{1,0}) + \epsilon H_{0,0}^{(1)}(\hat{J}_{1,0})] \\ &\quad + \frac{\partial H_0}{\partial \hat{J}_1} \left[(\hat{J}_1 - \hat{J}_{1,0}) \right] + \frac{1}{2} (\hat{J}_1 - \hat{J}_{1,0})^2 \frac{\partial^2 H_0}{\partial \hat{J}_1^2} \Big|_{\hat{J}_{1,0}} \\ &\quad + \text{(defn. } \hat{J}_{1,0} \text{)} + 2eH_{j=0}^{(1)} \cos\phi_i \end{aligned}$$

$$\stackrel{H(\vec{\omega}, \phi)}{=} \frac{1}{2} (\vec{\omega} - \vec{\omega}_{1,0})^2 \frac{\partial^2 H_0}{\partial \vec{\omega}^2} \Big|_{\vec{\omega} = \vec{\omega}_{1,0}} - F \cos \phi,$$

$$= \frac{G}{2} (\vec{\omega} - \vec{\omega}_{1,0})^2 - F \cos \phi,$$

$$G = \frac{\partial^2 H_0}{\partial \vec{\omega}^2} \Big|_{\vec{\omega} = \vec{\omega}_{1,0}}, \quad F = -2G \dot{\omega}_{1,0}$$

Recall Pendulum: $L = \frac{m l^2 \dot{\theta}^2}{2} - mgl(1 - \cos \theta)$

$$H = p_\theta \dot{\theta} - L \quad p_\theta = m l^2 \dot{\theta}$$

$$= \frac{p_\theta^2}{2ml^2} - mgl \cos \theta + \phi$$

$$\therefore \langle H(\vec{\omega}, \phi) \rangle = \frac{G}{2} (\vec{\omega} - \vec{\omega}_{1,0})^2 - F \cos \phi,$$

$$H = \frac{p_\theta^2}{2ml^2} - mgl \cos \theta$$

$$\Rightarrow \langle H(\vec{\omega}, \phi) \rangle = \frac{G}{2} (\vec{\omega} - \vec{\omega}_{1,0})^2 - F \cos \phi,$$

the form of Hamiltonian near resonance

Note: Assumes $\frac{\partial^2 H_0}{\partial \vec{\omega}^2} = \frac{\partial \omega}{\partial \vec{\omega}} \neq 0$ $\left\{ \begin{array}{l} NL \\ \text{Shear} \end{array} \right.$

Corresponds to accidental resonance, $\partial^2 H_0 / \partial \vec{J}_1^2 = 0$
 (linear problem!) corresponds to intrinsic resonance.

→ Properties / Structure of Resonant Hamiltonian
 Standard

$$\langle H(\vec{J}_1, \phi_1) \rangle = \frac{\epsilon}{2} (\vec{J}_1 - \vec{J}_{1,0})^2 + F \cos \phi_1$$

↓ NL parameter ↓ perturbation
 ↓ amplitude
 $= \frac{\epsilon}{2} \Delta \vec{J}_1^2 - F \cos \phi_1$

and so

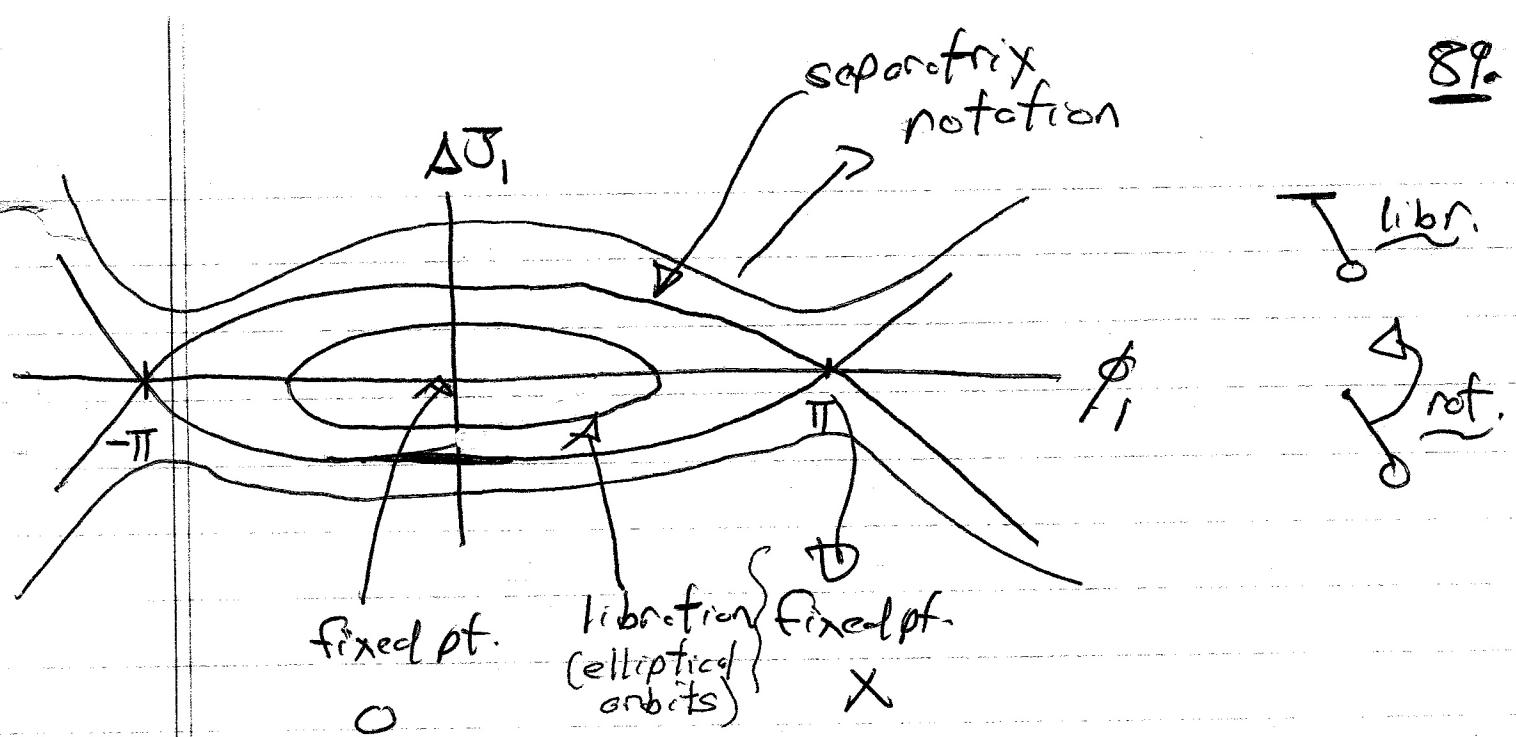
$$\left\{ \begin{array}{l} \dot{\Delta J} = -F \sin \phi_1, \quad \phi_1 = 0 + d\phi_1 \\ \dot{\phi}_1 = G \Delta J \end{array} \right. \Rightarrow \dot{\Delta J} + FG \Delta J = 0$$

$\Rightarrow FG > 0 \Rightarrow \phi_1 = 0$ fixed point
 (opt. elliptic pt.) stable

, , $\phi_1 = \pm \pi$ fixed point
 (x-pt. hyperbolic pt.) unstable

∴ can draw contours of constant H

i.e.



- separatrix 'separates' rotation from vibration (open from closed contours)

~ width of separatrix = "island width"

$$\begin{aligned}
 (\Delta J)_{\max} &\approx 2(F/G)^{1/2} \\
 &= 2(-2G H_{n-\alpha})^{1/2} / \left(\frac{\partial^2 H_0}{\partial J_1 \partial J_{1,\alpha}} \right)^{1/2}
 \end{aligned}$$

i.e. particle $(\Delta p)^2$ wave

$$H = \frac{(\vec{p} + m\vec{\omega}/k)^2}{2m} + \frac{1}{2} \vec{\phi}_0 \cos kx$$

$$\Delta p \approx (2\phi_0 m)^{1/2}$$

$$\Rightarrow \Delta V \approx (2\phi_0/m)^{1/2} \rightarrow \text{trapping width}$$

Summary of Secular Perturbation Theory

→ Purpose:

- a.) Ordinary canonical perturbation theory seeks to approximately integrate perturbed Hamiltonians by constructing canonical transformation $\underline{I}, \underline{\theta} \rightarrow \underline{J}, \underline{\phi}$ such that $\dot{J} = 0$, to some order in ϵ

$$\text{input: } H = H_0(\underline{I}) + \epsilon H_1(\underline{I}, \underline{\theta})$$

$$\text{output: } K = H_0(\underline{J}) + \epsilon \langle H_1(\underline{J}) \rangle_{\underline{\theta}} + \dots$$

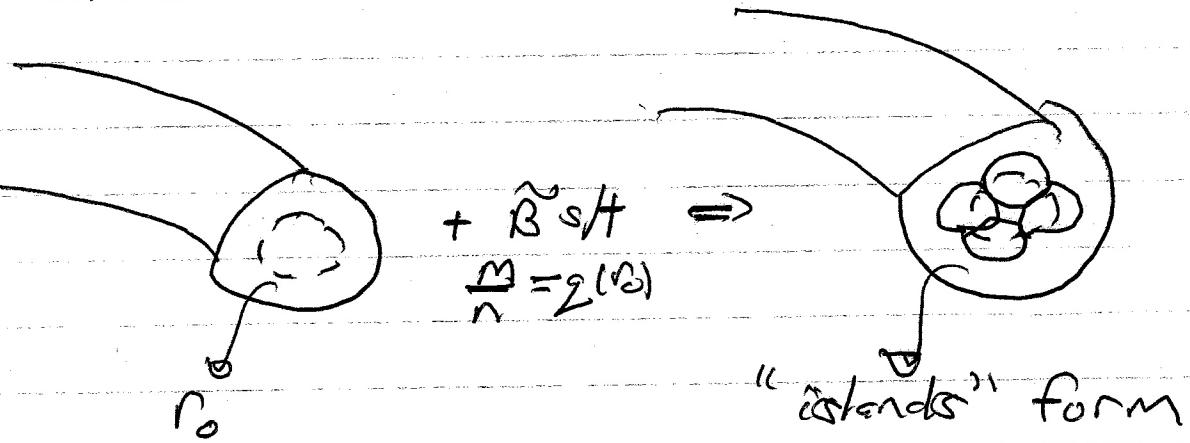
$$S = J \cdot \theta + \epsilon S_1, \quad S_1 = c \sum_m \tilde{H}_{1,m} e^{\frac{i}{m} \omega_0(\underline{J})}$$

- b.) Secular (canonical) perturbation theory seeks to solve the "small divisor" problem, arising when $m \cdot \omega_0(\underline{J}) \approx 0$, i.e. on resonance. Apart from its specific tailoring to resonance, secular perturbation theory is very close to canonical perturbation theory in approach and technique.

N.B.: The "Big Picture":

Resonant perturbations distort phase space tori, breaking symmetry and forming structure.

i.e.
tokamak:



seek calculate width, shape, etc. of tori distortions (i.e. islands) using secular perturbation theory,

⇒ Secular perturbation theory is important prelude/foundation for the study of Ham. Hori's chaos.

→ Set Up:

$$\textcircled{1} \text{ have: } H = H_0(\underline{I}) + \epsilon H_1(\underline{I}, \underline{\Theta})$$

with a resonant surface, i.e. \exists some \underline{I}_0 such that (for 2D Γ)

$$\omega_1(\underline{I}_0) - \omega_2(\underline{I}_0) = 0$$

② then specialize usual $I, \theta \rightarrow \underline{J}, \underline{\phi}$ by isolating slow, fast dependence:

$$\begin{cases} I_1, \theta_1 \\ I_2, \theta_2 \end{cases} \rightarrow \begin{cases} r\theta_1 - s\theta_2, \frac{1}{J_1} \\ \theta_2, \frac{1}{J_2} \end{cases} \quad \begin{matrix} \text{(slow)} \\ \text{fast} \end{matrix}$$

$$\therefore \underline{S} = (r\theta_1 - s\theta_2) \frac{1}{J_1} + \theta_2 \frac{1}{J_2} + G \underline{\phi}_1$$

Note: S.P.T. only works for 'one resonance at a time'.

$$\begin{array}{l} \textcircled{3} \text{ Now, since: } \underline{\phi}_1 = r\theta_1 - s\theta_2 + O(\zeta) \text{ (Slow)} \\ \qquad \qquad \qquad \underline{\phi}_2 = \theta_2 + O(\zeta) \text{ (Fast)} \end{array}$$

can re-write:

$$H_1 = \sum_{l, m} H_{l, m} (\underline{J}) \exp \left[i \left(\frac{l}{r} \underline{\phi}_1 + \frac{(ls+mr)}{r} \underline{\phi}_2 \right) \right]$$

Now, in standard CPT, eliminate all angle variable dependence by averaging. In SPT, resonant perturbations break angular symmetry, so we cannot remove all $\underline{\phi}$ dependence. However, averaging allows us to remove fast angular dependence., i.e. average over $\underline{\phi}_2$.

$$\Rightarrow k_1 = k_1(\bar{\underline{J}}, \phi_1) = \langle H_1 \rangle_{\phi_2}$$

H_1

$$ls = -mr \Rightarrow \frac{l}{m} = -\frac{r}{\bar{J}} = \frac{\omega_2}{\bar{J}}$$

perturbation pitch
must match frequency ratio



$$k_1(\bar{\underline{J}}, \phi_1) = H_0(\bar{\underline{J}}) + \epsilon \sum_{p=0}^{\infty} H_{-pr} e^{-ip\phi_1}$$

(sum over harmonics)

$$\frac{\partial k_1}{\partial \phi_2} = 0 \Rightarrow \frac{d \hat{J}_2}{dt} = 0$$

$$\Rightarrow \hat{J}_2 = I_2 + \frac{s}{r} I_1 \text{ is I.O.M.}$$

etc.

→ Understanding perturbed motion.

- no loss generality for $p=0, \pm 1 \Rightarrow$

$$\langle H \rangle = H_0(\bar{\underline{J}}) + \epsilon H_{0,0}(\bar{\underline{J}}) + 2\epsilon H_{0,-1}(\bar{\underline{J}}) \cos \phi_1$$

- for understanding motion need, at a' harmonic oscillator fixed point locations and effective "spring constants".

- Unsparking approach:

→ only \hat{J}_1, ϕ dependence non-trivial

→ $\dot{\hat{J}}_1 = 0 \Rightarrow \phi = n\pi$ (pendulum equilibria)

$\dot{\phi} = 0 \Rightarrow r\omega_1 - s\omega_2 = 0$ (resonance)

- Spiking:

$$\frac{\partial}{\partial \hat{J}_1} = \frac{dI_1}{d\hat{J}_1} \frac{\partial}{\partial I_1} + \frac{dI_2}{d\hat{J}_1} \frac{\partial}{\partial I_2}$$

$$= r \frac{\partial}{\partial I_1} - s \frac{\partial}{\partial I_2}, \text{ etc.}$$

$\hat{J}_{1,0}$ fixed points: on resonant torus
at $\phi = n\pi$

Then, can simplify K_1 to that of pendulum by expanding about $\hat{J}_{1,0}, \phi_{1,0}$:

$$K_1 = \left[H_0(\hat{J}_{1,0}) + \epsilon H_{1,0}^{(1)}(\hat{J}_{1,0}) \right] + \frac{\partial H_0}{\partial \hat{J}_1}(\hat{J}_1 - \hat{J}_{1,0}) + \frac{1}{2} (\hat{J}_1 - \hat{J}_{1,0})^2 \frac{\partial^2 H_0}{\partial \hat{J}_1^2} \Big|_{\hat{J}_{1,0}}$$

$$\xrightarrow{\text{resonance}} + 2\epsilon H_{1,0}^{(1)} \cos\phi$$

$$\approx \frac{1}{2} (\hat{J}_1 - \hat{J}_{1,0})^2 \frac{\partial^2 H_0}{\partial \hat{J}_1^2} + 2\epsilon H_{1,0}^{(1)} \cos\phi$$

→ Output:

$$\text{If } G = \partial^2 H_0 / \partial \tilde{J}_1^2 \Big|_{\tilde{J}_1=0}, F = -2G H_{G=0}^{(1)}(\tilde{J}_1, 0)$$

$$\Rightarrow \left\{ K_1 = \langle H(\tilde{J}_1, \phi_1) \rangle = \frac{G}{2} (\tilde{J}_1 - \tilde{J}_{1,0})^2 - F \cos \phi_1 \right\}$$

- form of H near resonances $\Im \omega_1 - S \omega_2 = 0$

- al/a' pendulum

- requires: $\partial^2 H_0 / \partial \tilde{J}_1^2 \Big|_{\tilde{J}_1=0} \neq 0$ (shear)

$$\langle H \rangle = \frac{G}{2} (\Delta \tilde{J}_1)^2 - F \cos \phi_1$$

$F G > 0 \Rightarrow \phi_1 = 0$; stable fixed point

o-pt.; elliptic

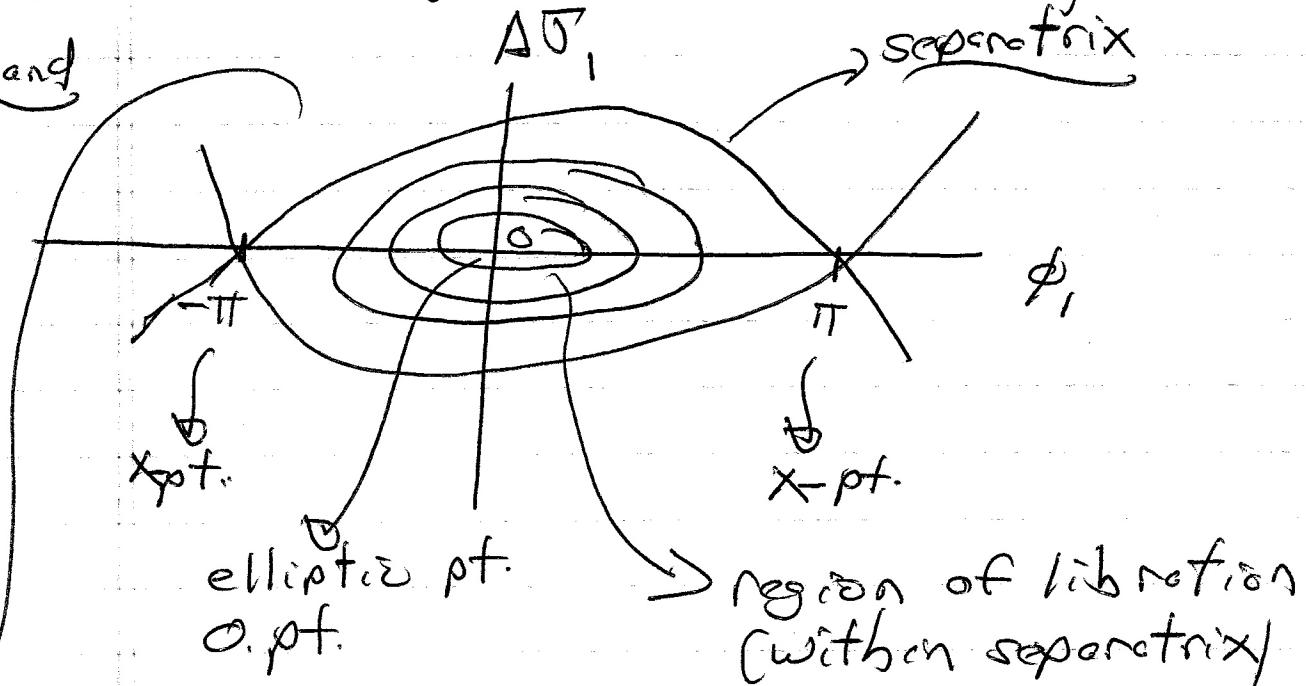
$\phi_1 = \pm \pi$ fixed point, unstable
x-pt.; hyperbolic

$$\Delta \tilde{J}_{\max} = 2 (F/G)^{1/2} \rightarrow \text{'island' width}$$

$$\sim (H_1)^{1/2}, \text{ generically}$$

→ The Picture (Const. H contours) :

Island



region of rotation
(outside separatrix),

i.e. resonant perturbations form island chains on resonant tori