

Wave Kinetics

$N(k, x, t)$ → effective distribution function
of waves.

Why? →

"A wave is never found alone, but is mingled with as many other waves as there are uneven places in the object where said waves are produced. At one and the same time there will be moving over the greatest wave of a sea innumerable other waves proceeding in different directions."

- Leonardo da Vinci

Codice Atlantico, c. 1500.

⇒ Waves come in packets, spectra, etc.!

Wave Adiabatic Theory / Wave Kinetics

- frequently encounter problems with slowly varying parameters \Rightarrow adiabatic theory

\Rightarrow

- wave kinetic equation (consequence of Liouville Thm.)

$$\partial_t N + (\underline{v}_r + \underline{v}) \cdot \nabla N = - \partial_x (\omega + \underline{k} \cdot \underline{v}) \cdot \partial_y N$$

$= C(N)$; obvious analogy to Boltzmann Eqn.

$$N \equiv \frac{\Sigma}{\omega_k} \equiv \text{wave action density / wave energy density}$$

$$\Sigma = \frac{\partial (\omega g_n)}{\partial \omega} \Big| \frac{|E_n|^2}{\omega_n} \frac{1}{8\pi}, \text{ for e.s.}$$

characteristics:

refraction by shear

$$\frac{dx}{dt} = \frac{\partial \omega}{\partial k} \hat{h} + \underline{v}, \quad \frac{dk}{dt} = - \frac{\partial (\omega + \underline{k} \cdot \underline{v})}{\partial x}$$

refraction
by parametric
variation

- need:

$$\omega \ll \frac{d\lambda}{dt}$$

λ = parameter

space and time
scale separation

$$\frac{1}{N} (\underline{v}_r \cdot \nabla N) \ll \omega \Rightarrow \underline{z} \cdot \underline{v}_r \ll \omega$$

$C(N) \rightarrow$ interactions with comparable scale.

Examples :

- linear theory of Langmuir turbulence
i.e. when will phonon grow?
- QL theory of Langmuir turbulence
i.e. determine evolution of plasma
energy \rightarrow net impact?
- drift waves and sheared flow.

Fundamentals of Wave Kinetics

\rightarrow where does conservation of action
emerge from?

\rightarrow answer: phase symmetry underlies
of wave train)
wave kinetics

\rightarrow approach via Variational principle.

c.f. Whitham: "Linear and Nonlinear Waves"
Chapt. 14.

→ Derivation

Consider a system, like ideal MHD, which can be described in terms of displacement $\underline{\Sigma}$:

i.e. $\underline{\Sigma} = \text{re}\{A e^{i\phi} + A^* e^{-i\phi}\}$

then wave equation arises from:

$$\delta S' = \int dt \int dx \mathcal{L}(\underline{\Sigma})$$

Envisioning a wave train, with slowly varying amplitude, so eikonal approach optimal
i.e. fast variation in phase, slow WKB:



$$S = \int dt \int dx \mathcal{L}(\omega, \underline{k}, a)$$

$\frac{\partial}{\partial t}$
amplitude

$$\underline{k} = \underline{\nabla} \phi$$

$$\omega = -\frac{d\phi}{dt}$$

$$= \int dt \int dx \mathcal{L}(-\dot{\phi}_t, \phi_x, a)$$

neglect all corrections to eikonal theory.

\Rightarrow here L corresponds to period-averaged Lagrangian

- ϕ undetermined to const \rightarrow phase symmetry!

\therefore to vary:

$$\delta S / \delta q = 0$$

$$\delta S / \delta \dot{\phi} = 0$$

Now, in linear theory:

$$[G(k, \omega) \equiv \frac{\partial G}{\partial \omega}]$$

$$L = G(\omega, k) \dot{\epsilon}^2$$

as for MHD, as in wave section:

$$L = \frac{1}{2} \rho \dot{\epsilon}^2 - \frac{1}{2} \rho [D(k, x, t)]^2 \dot{\epsilon}^2$$

concrete form
of Lagrangian

\hookrightarrow eikonal form of
stiffness matrix
(\rightarrow potential energy)

$$\Rightarrow \underline{\epsilon} \cdot \underline{M} \cdot \underline{\epsilon}$$

$$\text{If: } \underline{\epsilon} = A e^{i\phi} + A^* e^{-i\phi}$$

$M(k, \omega, \phi)$, as for
linear waves

$$\stackrel{S}{=} G(\omega, k) = \frac{1}{2} \rho \left[\left(\frac{\partial \phi}{\partial t} \right)^2 - [D(\partial \phi, x, t)]^2 \right]$$

Now, 1) $\partial S / \partial q = 0$

$$\Rightarrow G(\omega, k) = 0$$

but

$$G(\omega, k) = \rho \left(\frac{\partial \phi}{\partial t} \right)^2 - [D(\partial \phi, x, t)]^2 \\ = \rho \omega^2 - D^2$$

\Rightarrow dispersion relation

2) $\partial S / \partial \phi = 0$

$$\partial S = \int dt \int d^3x \left\{ \frac{\partial L}{\partial (-\dot{\phi}_k)} \partial(-\dot{\phi}_k) + \frac{\partial L}{\partial (\phi_k)} \partial(\phi_k) \right\}$$

end pts fixed, i.e.

$$= \int dx \int d^3x \left\{ \partial_x \left(\frac{\partial L}{\partial (-\dot{\phi}_k)} \right) - \frac{\partial}{\partial x} \cdot \left(\frac{\partial L}{\partial (\phi_k)} \right) \right\} \partial \phi$$

$$\partial \phi = 0 \Rightarrow$$

$$\partial_x \left(\frac{\partial L}{\partial (-\dot{\phi}_k)} \right) - D \cdot \left(\frac{\partial L}{\partial \phi_k} \right) = 0$$

Now, have: $\underline{G}(k, \omega) = 0$ (disp. reln.)

$$\underline{\Delta} + \left(\frac{\partial \underline{L}}{\partial \omega} \right) - D \cdot \left(\frac{\partial \underline{L}}{\partial \underline{k}} \right) = 0$$

$$d\underline{G} = 0 \Rightarrow \frac{\partial \underline{G}}{\partial \omega} d\omega + \frac{\partial \underline{G}}{\partial \underline{k}} d\underline{k} = 0$$

$$V_{gr} = \frac{d\omega}{d\underline{k}} = - \frac{\frac{\partial \underline{G}}{\partial \underline{k}}}{\frac{\partial \underline{G}}{\partial \omega}} \quad (\text{at } k \parallel \omega)$$

$$\underline{\Delta} + \left(\frac{\partial \underline{G}(\omega)}{\partial \omega} \alpha^2 \right) + D \cdot \left[- \frac{\frac{\partial \underline{G}}{\partial \underline{k}}}{\frac{\partial \underline{G}}{\partial \omega}} \quad \frac{\partial \underline{G}}{\partial \omega} \alpha^2 \right] = 0$$

and so $N \equiv \frac{\partial \underline{G}}{\partial \omega} \alpha^2$

$$\frac{\partial N}{\partial t} + D \cdot (V_{gr} N) = 0$$

(N not yet
action)

→ Also note energy is conserved \Leftrightarrow G covariant to time translations.

so, Noether then \Rightarrow there exists an ~~equation~~ energy conservation equation

have $L = G(h, \omega) a^2$

$$\frac{\partial L}{\partial a} = 0 \Rightarrow G(\omega, h) = 0$$

$$\frac{\partial}{\partial t} \left(\frac{\partial L}{\partial \dot{a}} \right) - D \cdot \left(\frac{\partial L}{\partial a} \right) = 0$$

and of course:

$$\underline{D} \times \underline{h} = 0, \text{ as } \underline{h} = \underline{D} \phi$$

$$\frac{\partial \underline{h}}{\partial t} = - \frac{\partial \omega}{\partial \underline{x}}, \text{ as } \partial_t \underline{D} \phi = - \underline{D} \left(- \frac{\partial \phi}{\partial t} \right)$$

Now, $L = 0$, as $G(h, \omega) = 0$

as expect $\frac{\partial L}{\partial \omega} \Rightarrow N$, $\omega \frac{\partial L}{\partial \omega} \Rightarrow E$
 $\frac{\partial}{\partial t} \circ$, ~~creatively~~

$$\Rightarrow \frac{\partial}{\partial t} \left(\omega \frac{\partial L}{\partial \omega} - L \right) + D \cdot \left[-\omega \frac{\partial L}{\partial h} \right] = 0$$

~~Up to~~ Σ

$\frac{-\partial E/\partial h}{\partial E/\partial \omega} \frac{\partial \omega}{\partial h}$

$$\partial_t (\omega \mathcal{L}_\omega + \mathcal{L}) + D \cdot \left(-\omega \frac{\partial \mathcal{L}}{\partial \underline{u}} \right) = 0$$

check:

$$(\partial_t \omega) \mathcal{L}_\omega + \omega \partial_t (\mathcal{L}_\omega) - \frac{\partial \mathcal{L}}{\partial t}$$

$$+ D \cdot \left(-\omega \frac{\partial \mathcal{L}}{\partial \underline{u}} \right) = 0$$

but $\partial_t \mathcal{L}_\omega = D \cdot (\mathcal{L}_{\underline{u}})$

$$(\mathcal{L}_\omega) (\partial_t \omega) + \omega D \cdot (\mathcal{L}_{\underline{u}}) - \omega (D \cdot \mathcal{L}_{\underline{u}})$$

$$- \left(\frac{\partial \mathcal{L}}{\partial \underline{u}} \right) \cdot D \omega - \frac{\partial \mathcal{L}}{\partial t}$$

but $\partial_t \underline{u} = - D \omega$

$$(\partial_t \omega) (\mathcal{L}_\omega) + (\partial_t \underline{u}) \cdot \frac{\partial \mathcal{L}}{\partial \underline{u}} - \frac{\partial \mathcal{L}}{\partial t} = 0 \quad \checkmark$$

(identity)

\Rightarrow $\partial_t \left\{ \omega \frac{\partial \mathcal{L}}{\partial \omega} - \mathcal{L} \right\} + D \cdot \left(-\omega \frac{\partial \mathcal{L}}{\partial \underline{u}} \right) = 0$

But $G(\omega, k) = 0 \Rightarrow L = 0$

$$\partial_t \left\{ \omega \frac{\partial L}{\partial \omega} \right\} + D \cdot \left(-\omega \frac{\partial L}{\partial k} \right) = 0$$

so

$$\mathcal{E} = \omega \frac{\partial L}{\partial \dot{\omega}} \rightarrow \text{energy density}$$

$$\text{so } \frac{\partial L}{\partial \omega} = \mathcal{E}/\omega \Rightarrow \text{action density } \mathcal{L} \\ = N$$

so have:

$$\boxed{\partial_t (N) + D \cdot (\nabla_x \cdot N) = 0}$$

wave - kinetic

To demonstrate equivalence,

$$\underline{\frac{\partial N}{\partial t}} + \nabla_x \cdot \underline{D} N - \underline{\frac{\partial \omega}{\partial x}} \cdot D_N N = 0$$

and Liouville Thm:

$$\partial_t N + D \cdot (\nabla_x N) + D_N \left(-\frac{\partial \omega}{\partial x} N \right) = 0$$

$\int dk$, and assume narrow spread on k
(i.e. wave packet) \Rightarrow

$$\frac{\partial N}{\partial t} + D \cdot [v_{gp} N] = 0$$

Observe:

\rightarrow Vlasov-like equation in eikonal phase space (x, k)

$$\frac{\partial N}{\partial t} + v_{gp} \cdot \frac{\partial N}{\partial x} - \frac{\partial \omega}{\partial x} \cdot \frac{\partial N}{\partial k} = 0$$

and

\rightarrow continuity-type equation on x spec
for packet

$$\frac{\partial N}{\partial t} + D \cdot (v_{gp} N) = 0$$

Also observe:

\rightarrow seeming issue re:

$$\frac{\partial k}{\partial t} = -\frac{\partial \omega}{\partial x} \quad \text{vs} \quad \frac{dk}{dt} = -\frac{\partial \omega}{\partial x}$$

Now $\frac{\partial \underline{h}}{\partial t} = -\frac{\partial \omega}{\partial \underline{x}}$ is (Eulerian)
(partical) relation in \underline{x} +

$\frac{dh}{dt} = -\frac{\partial \omega}{\partial x}$ is (Lagrangian)
(total) relation following
packet
(here $\omega = D(h, \underline{x}, t)$, as $G=0$)

$$\frac{dh}{dt} = \frac{\partial h}{\partial t} + v_n \cdot \nabla h$$

$$= -\frac{\partial \omega}{\partial x} + \frac{\partial \omega}{\partial h} \cdot \frac{\partial h}{\partial x}$$

$$\frac{\partial h}{\partial t} = -\frac{\partial \omega}{\partial x} \quad \text{agreed.}$$

→ Now can convert from N to E

$$\text{i.e. } N = E/\omega$$

$$\frac{dN}{dt} \Big|_{\text{reyo}} = \frac{d}{dt} (E/\omega) = 0$$

$$\left| \frac{1}{\omega} \frac{d\epsilon}{dt} \right| - \left| \frac{1}{\omega} \epsilon \frac{d\omega}{dt} \right| = 0$$

ray

ray

$$\text{Now } \frac{d\omega}{dt} = \partial_t \omega + \frac{\partial \omega}{\partial x} \frac{dx}{dt} + \frac{\partial \omega}{\partial y} \frac{dy}{dt}$$

From eikonal eqn:

$$= \partial_t \omega + \frac{\partial \omega}{\partial x} \cdot \cancel{\frac{\partial \omega}{\partial y}} - \cancel{\frac{\partial \omega}{\partial y}} \cdot \cancel{\frac{\partial \omega}{\partial x}}$$

$$\text{so if } \partial_t \omega = 0$$

$$\therefore \frac{dN}{dt} = 0 \Rightarrow \frac{d\epsilon}{dt} = 0$$

$$\text{so } \partial_t \epsilon + \underline{y_0} \cdot \underline{D} \epsilon - \frac{\partial \omega}{\partial x} \underline{D}_y \epsilon = 0$$

and exploiting Liouville Thm, etc \Rightarrow

$$\frac{d\epsilon}{dt} = \partial_t \epsilon + \underline{D} \cdot [\underline{y_0} \cdot \epsilon] = 0$$

so, for conservative case i.e. $\partial_t \mathbf{w} = 0$

$$\partial_t \mathbf{E} + \nabla \cdot [U_{gr} \mathbf{E}] = 0$$

If stationary, $\partial_t \mathbf{E} = 0$

$$\Rightarrow \nabla \cdot [U_{gr} \mathbf{E}] = 0$$

incompressible
wave energy
flux /

$\Rightarrow U_{gr}$ drops \Rightarrow
 $\mathbf{E} \uparrow \Rightarrow$ blocking,
breaking

Summary

14.

Recall:

→ Hamiltonian structure of eikonal theory, etc. \Rightarrow

$$\frac{\partial \rho(k, x, t)}{\partial t} + \underline{v}_n \cdot \nabla \rho(k, x, t) - \underline{\omega} \cdot \frac{\partial}{\partial x} \rho(k, x, t) = 0$$

→ Physical arguments suggest $\rho = \frac{\epsilon}{w} = N$
wave action
density

→ Variational Approach

$$S = \int dt \int d^3x \ L \quad , \quad L = G(\omega, k) a^2$$

$$\omega = -\frac{\partial \phi}{\partial t} = -\dot{\phi}$$

$$k = \frac{\partial \phi}{\partial x} = \phi_x$$

but two parameters varied

$$\frac{\delta S}{\delta a} = 0 \Rightarrow G(\omega, k) = 0 \rightarrow \text{dispersion relation}$$

$$\frac{\delta S}{\delta \phi} = 0 \Rightarrow \frac{\partial}{\partial t} \left(\frac{\partial L}{\partial \omega} \right) - \frac{\partial}{\partial x} \left(\frac{\partial L}{\partial k} \right) = 0$$

$$\Rightarrow \frac{\partial}{\partial t} \left(\frac{\partial G a^2}{\partial \omega} \right) - \frac{\partial}{\partial x} \left(\frac{\partial G a^2}{\partial k} \right) = 0$$

and time translation symmetry and $S=0 \Rightarrow$

$$\underline{\Sigma} = \omega \frac{\partial G}{\partial \omega} a^2 \Rightarrow N = \frac{\underline{\Sigma}}{\omega} = \frac{\partial G}{\partial \omega} a^2$$

and $\frac{\partial G}{\partial k} a^2 = V_{go} N$

→ Helpful reminder:

Result for electrostatic plasma waves

if $E(\omega, k) = 0 \Rightarrow$ dispersion relation

then $\underline{\Sigma}_k = \frac{\partial (\omega \epsilon)}{\partial \omega} \Big|_{\omega_k} \frac{|E_k|^2}{8\pi}$

$$= \omega_k \frac{\partial G}{\partial \omega} \Big|_{\omega_k} \frac{|E_k|^2}{8\pi} \rightarrow \text{wave energy density}$$

$$\therefore N_k = \frac{\partial G}{\partial \omega} \Big|_{\omega_k} \frac{|E_k|^2}{8\pi}$$

and $\underline{P}_u = - \frac{\partial G}{\partial u} \Big|_{\omega_k} \frac{|E_u|^2}{8\pi} \rightarrow \text{wave energy density flux}$

$$= V_{go} N_k$$

since $\underline{G}(h, \omega) = 0$, so along rays

$$d\underline{G} = d\omega \frac{\partial \underline{G}}{\partial \omega} + dh \cdot \frac{\partial \underline{G}}{\partial h} = 0$$

$$\frac{d\omega}{dh} = - \left(\frac{\partial \underline{G}/dh}{\partial \underline{G}/\partial \omega} \right)$$

etc.