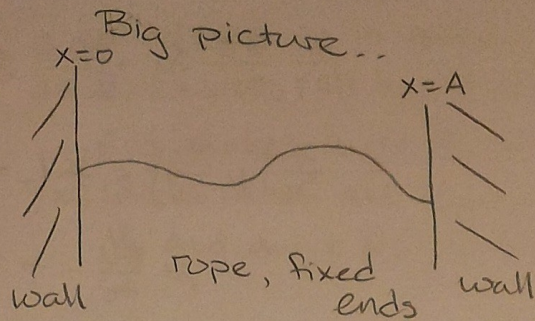


small section of rope.



$u(x=0) = u(x=A) = 0$  : fixed ends

a)  $ds^2 = du^2 + dx^2$

given  $T$  (tension) and mass density  $\mu$ .

For the small section:

The variable  $u(x,t)$  is the vertical displacement of the rope section.  $x$  and  $t$  are parameters.

$$KE = \frac{1}{2} (\mu dx) \left( \frac{\partial u}{\partial t} \right)^2 = \frac{1}{2} \mu \left( \frac{\partial u}{\partial t} \right)^2 dx$$

PE : change of tension from unperturbed to perturbed.  $dW = T ds - T dx$

$$PE = T(ds - dx) = T([du^2 + dx^2]^{1/2} - dx) = T\left(\left[\left(\frac{du}{dx}\right)^2 + 1\right]^{1/2} dx - dx\right) = T\left(\left[\left(\frac{du}{dx}\right)^2 + 1\right]^{1/2} - 1\right) dx$$

assume small changes in  $\frac{du}{dx}$  so we can Taylor expand  $\left[1 + \left(\frac{du}{dx}\right)^2\right]^{1/2} \approx 1 + \frac{1}{2}\left(\frac{du}{dx}\right)^2 - \dots$

$$PE = T\left(1 + \frac{1}{2}\left(\frac{du}{dx}\right)^2 - 1\right) dx = T \frac{1}{2} \left(\frac{du}{dx}\right)^2 dx \text{ and since } x \text{ and } t \text{ are independent}$$

$$\frac{du}{dx} = \frac{\partial u}{\partial x} \text{ so } PE = \frac{T}{2} \left(\frac{\partial u}{\partial x}\right)^2 dx$$

$$\mathcal{L} = KE - PE = \frac{\mu}{2} \left(\frac{\partial u}{\partial t}\right)^2 dx - \frac{T}{2} \left(\frac{\partial u}{\partial x}\right)^2 dx \quad \text{: Lagrangian density}$$

$$\text{so } L = \int_0^A \mathcal{L} dx = \int_0^A \left[ \frac{\mu}{2} \left(\frac{\partial u}{\partial t}\right)^2 - \frac{T}{2} \left(\frac{\partial u}{\partial x}\right)^2 \right] dx \quad \leftarrow \text{Lagrangian}$$

$$S = \int_{t_1}^{t_2} L dt = \int_{t_1}^{t_2} dt \int_0^A \mathcal{L} dx$$

$$\delta S = \int_{t_1}^{t_2} dt \int_0^A \left( \frac{\partial \mathcal{L}}{\partial u_t} \delta u_t + \frac{\partial \mathcal{L}}{\partial u_x} \delta u_x \right) dx \text{ and since the ends are fixed, } \delta S = 0$$

and for  $\delta S = 0$ , the inside of the integral is zero

meaning:  $\frac{\partial \mathcal{L}}{\partial u_t} \delta u_t + \frac{\partial \mathcal{L}}{\partial u_x} \delta u_x = 0$

$\delta u_t = \frac{\partial}{\partial t} \delta u$  and  $\delta u_x = \frac{\partial}{\partial x} \delta u$  so then

$$\frac{\partial \mathcal{L}}{\partial u_t} \frac{\partial}{\partial t} \delta u + \frac{\partial \mathcal{L}}{\partial u_x} \frac{\partial}{\partial x} \delta u = 0$$

$$\frac{\partial}{\partial t} \frac{\partial \mathcal{L}}{\partial u_t} \delta u + \frac{\partial \mathcal{L}}{\partial u_x} \frac{\partial}{\partial x} \delta u = 0$$

$$\frac{\partial}{\partial t} \left( \mu \frac{\partial u}{\partial t} \right) + \frac{\partial}{\partial x} \left( -T \frac{\partial u}{\partial x} \right) = 0$$

$$\mu \frac{\partial^2 u}{\partial t^2} = T \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\mu}{T} \frac{\partial^2 u}{\partial t^2} = \frac{\partial^2 u}{\partial x^2} \quad \text{--- LEOM}$$

let  $\frac{\mu}{T} = \frac{1}{c^2}$  so then

$$\frac{1}{c^2} \left( \frac{\partial^2 u}{\partial t^2} \right) = \frac{\partial^2 u}{\partial x^2} = \text{wave equation with assumption of } \frac{\partial u}{\partial x} \text{ is small.}$$

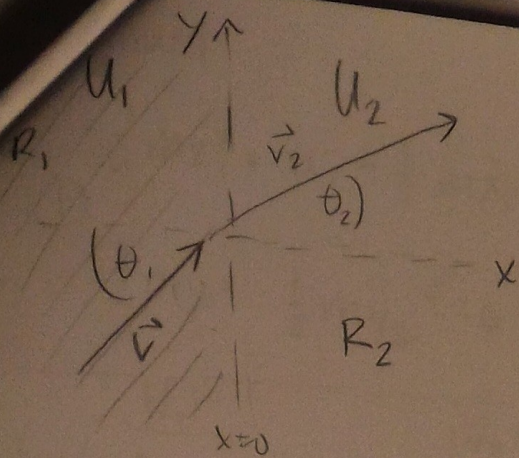
b)  $\mathcal{H} = P_i \dot{q}_i - \mathcal{L}$  where  $P_i$  is a conjugate momentum  $P_i = \frac{\partial \mathcal{L}}{\partial \dot{q}_i}$  for each generalized velocity. In this problem we only have one generalized velocity,  $\frac{\partial u}{\partial t}$

so  $P_t = \frac{\partial \mathcal{L}}{\partial u_t} = \mu u_t \rightarrow \mathcal{H} = \mu u_t^2 - \mathcal{L} = \mu u_t^2 - \frac{\mu}{2} u_t^2 + \frac{T}{2} u_x^2$   
 $= \frac{\mu}{2} u_t^2 + \frac{T}{2} u_x^2$

$$H = \int_0^A \left[ \frac{\mu}{2} \left( \frac{\partial u}{\partial t} \right)^2 + \frac{T}{2} \left( \frac{\partial u}{\partial x} \right)^2 \right] dx = \int_0^A \left[ \frac{P_t^2}{2\mu} + \frac{T}{2} \left( \frac{\partial u}{\partial x} \right)^2 \right] dx$$

$$\frac{\partial \mathcal{H}}{\partial P_t} = \frac{\partial u}{\partial t} = \frac{P_t}{\mu} \quad \dot{P}_t = - \frac{\partial H}{\partial u}$$

$\mu u_t = P_t$   
 $\uparrow$   
 what we found above



a.  $L = T - U$   $T_1 = \frac{1}{2} m |\vec{v}_1|^2$ ,  $T_2 = \frac{1}{2} m |\vec{v}_2|^2$

$v_1 = U_1$ ,  $v_2 = U_2$

$\therefore L = \frac{1}{2} m [\dot{x}^2 + \dot{y}^2] - U(x)$

where

$$U(x) = \begin{cases} U_1 & x < 0 \\ U_2 & x > 0 \end{cases}$$

x:  $\frac{\partial \mathcal{L}}{\partial x} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{x}}$

$\rightarrow m \ddot{x} = - \frac{\partial U}{\partial x} \rightarrow \boxed{m \ddot{x} + \frac{\partial U}{\partial x} = 0}$

$\left. \begin{aligned} p &= m \dot{x} \\ \dot{x} &= \frac{p}{m} = \frac{dx}{dt} \end{aligned} \right\}$

$-\frac{\partial U}{\partial x} = \frac{d}{dt} (m \dot{x}) = m \ddot{x}$

\* need to get into terms of  $p_x$  &  $q_x$

$m \ddot{x} = \frac{d}{dt} \underbrace{(m \dot{x})}_p = \frac{dp_x}{dt} = \frac{dp_x}{dx} \cdot \frac{dx}{dt} = \frac{p_x}{m} \frac{dp_x}{dx}$

$0 = \frac{d}{dt} (m \dot{y}) = \boxed{m \ddot{y} = 0}$

NOW:  $\left( \frac{p_x}{m} \cdot \frac{dp_x}{dx} + \frac{dU}{dx} \right) dx = 0 \cdot dx$

$$\int_{R_1}^{R_2} \frac{p_x}{m} \frac{dp_x}{dx} dx + \int_{U_1}^{U_2} \frac{dU}{dx} dx = \int_{P_1}^{P_2} \frac{p_x}{m} dp_x + \int_{U_1}^{U_2} U(x) dx = \left[ \frac{p_{x2}^2}{2m} - \frac{p_{x1}^2}{2m} \right] + U_2 - U_1 = 0$$

so we get conservation of Energy!

$\frac{1}{2} m \dot{x}_1^2 + U_1 = \frac{1}{2} m \dot{x}_2^2 + U_2$

$\frac{1}{2} \frac{(m \dot{x})^2}{2m} = \frac{1}{2} m \dot{x}^2$

time for y:  $m \ddot{y} = 0 \therefore m \dot{y} = \text{constant!}$  Momentum in y direction = constant

$m \dot{y}_1 = m \dot{y}_2$  ✓ in terms of  $p_y$  &  $q_y$

Energy is the same as well:

$\int_{R_1}^{R_2} \frac{p_y}{m} \frac{dp_y}{dy} dy = 0 \Rightarrow \int_{P_{y1}}^{P_{y2}} \frac{p_y}{m} dp_y \Rightarrow \frac{p_{y2}^2}{2m} - \frac{p_{y1}^2}{2m} = 0$  ✓

$\left. \begin{aligned} \frac{1}{2} m \dot{y}_1^2 &= \frac{1}{2} m \dot{y}_2^2 \end{aligned} \right\}$

continued

$$\oplus \quad \frac{1}{2} m \dot{x}_1^2 + U_1 - \frac{1}{2} m \dot{x}_2^2 - U_2 = 0$$

$$y: \quad \frac{1}{2} m \dot{y}_1^2 - \frac{1}{2} m \dot{y}_2^2 = 0$$

$$\frac{1}{2} m (\dot{x}_1^2 + \dot{y}_1^2) - \frac{1}{2} m (\dot{x}_2^2 + \dot{y}_2^2) + U_1 - U_2 = 0$$

Region 1  $\rightarrow$  Region 2

$$\frac{1}{2} m |\vec{v}_1|^2 + U_1 = \frac{1}{2} m |\vec{v}_2|^2 + U_2$$

note:

$$\dot{x} = v \cos \theta$$

$$\dot{y} = v \sin \theta$$

Recall from y  $m \dot{y}_1 = m \dot{y}_2 \Rightarrow m v_1 \sin \theta_1 = m v_2 \sin \theta_2$

$$\therefore \frac{v_1}{v_2} = \frac{\sin \theta_2}{\sin \theta_1} \rightarrow v_2 = \frac{\sin \theta_1}{\sin \theta_2} v_1$$

We know that  $v_2$  also equals:

$$v_2 = \sqrt{\frac{\frac{1}{2} m v_1^2 + (U_1 - U_2)}{\frac{1}{2} m}} \left( \frac{v_1}{v_1} \right) = \sqrt{\frac{\frac{1}{2} m v_1^2 + (U_1 - U_2)}{\frac{1}{2} m v_1^2}} v_1$$

$$v_2 = \sqrt{1 + \frac{(U_1 - U_2)}{T_1}} v_1$$

solving for  $\theta_2$ :

$$\sin \theta_2 = \sin \theta_1 \frac{v_1}{v_2} \Rightarrow \theta_2 = \sin^{-1} \left[ \left( \sqrt{1 + \frac{(U_1 - U_2)}{T_1}} \right)^{-1} \sin \theta_1 \right]$$

ratio of times; diff mass same  $u$

masses are on the same path  $\rightarrow$  conservation of energy

- Potential energy is the same  $\rightarrow$  kinetic energy must be constant

let  $m \rightarrow bm$   $t \rightarrow ct$ , where  $c \neq b$  are constants

$$\frac{1}{2} m_1 v_1^2 = \frac{1}{2} m_1 \frac{x^2}{t_1^2} = \frac{1}{2} b m_1 \frac{x^2}{c t_1^2} = \frac{1}{2} b m_2 \frac{x^2}{c t_2^2}$$

\* note

$$\frac{1}{2} m_1 v_1^2 + U = \frac{1}{2} m_2 v_2^2 + U$$

equal  
& constant

$$\frac{m_1}{t_1^2} = \frac{m_2}{c t_2^2}$$

$$\frac{t_1^2}{t_2^2} = \frac{m_1}{m_2} \Rightarrow \frac{t_1}{t_2} = \sqrt{\frac{m_1}{m_2}}$$

OR

$$\frac{t_2}{t_1} = \sqrt{\frac{m_2}{m_1}}$$

(c) Same mass diff  $u, \neq U_2$  ratio of times

given:  $\frac{U_2}{U_1} = k$

$U_2 \rightarrow k U_1$   
 $t \rightarrow c t$

Kinetic energy = constant  $\forall c$   
total energy is still constant

$$\frac{1}{2} m v^2 = \frac{1}{2} m \frac{x^2}{t^2} = \frac{1}{2} m \frac{x^2}{c^2 t^2} \rightarrow \frac{1}{2} m \frac{x^2}{c^2 t_1^2} + U_1 = \frac{1}{2} m \frac{x^2}{c^2 t_2^2} + U_1 k$$

$$\frac{1}{2} m \frac{x^2}{c^2 t_1^2} = \frac{1}{2} m \frac{x^2}{c^2 t_2^2} + U_1 (k-1)$$

$\propto k U$   $k < 1$   $c \propto \frac{1}{\sqrt{k}} \propto \sqrt{\frac{U_1}{U_2}}$

so  $\frac{t_2}{t_1} = \left(\frac{U_2}{U_1}\right)^{-1/2}$

F.W. 6.4. 10

$$L = -mc^2 (1 - v^2/c^2)^{1/2} - V(\vec{r})$$

$$\vec{v} = \dot{\vec{r}}$$

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \vec{v}} \right) = \frac{\partial L}{\partial \vec{r}}$$

$$\frac{d}{dt} \left[ \frac{mc^2 \vec{v}}{c^2 \sqrt{1 - v^2/c^2}} \right] = -\frac{\partial V}{\partial \vec{r}}$$

$$m \underbrace{\frac{d}{dt} \left[ \frac{\vec{v}}{\sqrt{1 - v^2/c^2}} \right]}_{\text{acceleration}} = -\frac{\partial V}{\partial \vec{r}} \rightarrow \vec{F}(\vec{r}) = -\frac{\partial V}{\partial \vec{r}}$$

If  $v \ll c$ ,  $\vec{F}(\vec{r}) = m \frac{d}{dt}(\vec{v}) = m\vec{a}$ .  
For the non-relativistic case, we recover the classical equation.

$$b) \vec{p} = \frac{\partial L}{\partial \vec{v}} = \frac{\partial L}{\partial \vec{v}} = \frac{m \vec{v}}{\sqrt{1 - v^2/c^2}}$$

To find  $\vec{v}$  in terms of  $\vec{p}$ :

$$m \vec{v} = \vec{p} \sqrt{1 - v^2/c^2}$$

$$m^2 v^2 = p^2 (1 - v^2/c^2) = p^2 - p^2 v^2/c^2$$

$$m^2 v^2 + p^2 v^2/c^2 = p^2$$

$$v^2 (m^2 + p^2/c^2) = p^2$$

$$v^2 = \frac{p^2}{m^2 + p^2/c^2}$$

$$\frac{v^2}{c^2} = \frac{p^2}{m^2 c^2 + p^2}$$

plug this in  $\rightarrow$

The Lagrangian is

$$L = -mc^2 (1 - v^2/c^2)^{1/2} - V(\vec{r})$$

This does not explicitly depend on time, therefore the Hamiltonian is a constant of motion.

To find the Hamiltonian:

$$H = \vec{p} \cdot \vec{v} - (-mc^2 (1 - v^2/c^2)^{1/2} - V(\vec{r}))$$

$$= \frac{mv^2}{(1 - v^2/c^2)^{1/2}} + mc^2 (1 - v^2/c^2)^{1/2} + V(\vec{r})$$

$$= \frac{mv^2}{(1 - v^2/c^2)^{1/2}} + \frac{mc^2 (1 - v^2/c^2)}{(1 - v^2/c^2)^{1/2}} + V(\vec{r})$$

$$= \frac{mv^2 + mc^2 - mv^2 c^2/c^2}{(1 - v^2/c^2)^{1/2}} + V(\vec{r})$$

$$= \frac{mc^2}{(1 - v^2/c^2)} + V(\vec{r})$$

$$= \frac{mc^2}{(1 - p^2/m^2 c^2 + p^2)^{1/2}} + V(\vec{r})$$

$$= \frac{mc^2 (m^2 c^2 + p^2)^{1/2}}{(m^2 c^2 + p^2 - p^2)^{1/2}} + V(\vec{r})$$

$$= \frac{mc^2 (m^2 c^2 + p^2)^{1/2}}{m c} + V(\vec{r})$$

$$= c (m^2 c^2 + p^2)^{1/2} + V(\vec{r})$$

$$H = (m^2 c^4 + p^2 c^2)^{1/2} + V(\vec{r})$$

continued.

$V \rightarrow V(r)$  for a spherically symmetric potential

$$\dot{\vec{p}} = -\vec{\nabla}V = -\frac{\partial}{\partial r}V(\vec{r}) \quad \text{and} \quad \vec{p} = \gamma m \dot{\vec{r}}$$

To check if  $\vec{r} \times \vec{p}$  is a constant of motion,  $\frac{d}{dt}(\vec{r} \times \vec{p}) \stackrel{!}{=} 0$ .

$$\frac{d}{dt}(\vec{r} \times \vec{p}) = \frac{d}{dt}\vec{r} \times \vec{p} + \vec{r} \times \frac{d}{dt}\vec{p}$$

$$= \dot{\vec{r}} \times \vec{p} + \vec{r} \times \dot{\vec{p}}$$

$$= \gamma m (\dot{\vec{r}} \times \vec{r}) + \vec{r} \times \left(-\frac{\partial}{\partial r}V(\vec{r})\right)$$

Cross product of // vectors = 0.

$$= \underline{0} \rightarrow \text{This means } \vec{r} \times \vec{p} \text{ is a constant of motion}$$

For this spherical symmetry,  $p_\theta = 0$ , so  $\theta = \frac{\pi}{2}$ .

$$p^2 = p_r^2 + \frac{p_\theta^2}{r^2} + \frac{p_\phi^2}{r^2 \sin^2 \theta}$$

$$= p_r^2 + \frac{p_\phi^2}{r^2}$$

From part b,

$$H = (m^2 c^4 + p^2 c^2)^{1/2} + V(r)$$

$$= c(m^2 c^2 + p^2)^{1/2} + V(r)$$

$$= c \left( m^2 c^2 + p_r^2 + \frac{p_\phi^2}{r^2} \right)^{1/2} + V(r)$$

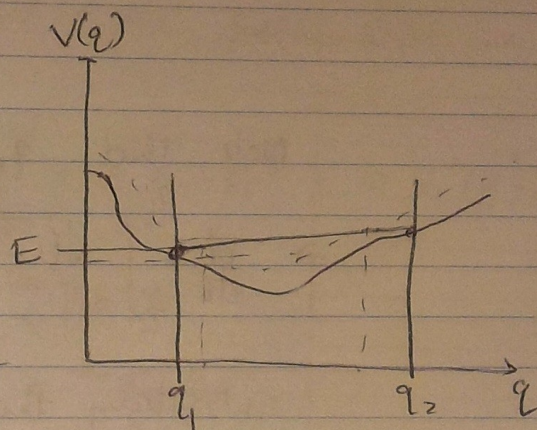
$$7. H(q, p) = \frac{p^2}{2m} + V(q)$$

$\therefore \partial_t H = 0$ , system is conservative.

let total energy of system be  $E$ .

$$\frac{p^2}{2m} + V(q) = E \rightarrow \textcircled{1}$$

$q_1$  &  $q_2$  are the limits of the motion, such that  $V(q_1) = V(q_2) = E$ .



So,  $q_1$  &  $q_2$  are function of  $E$  for given potential function.

The hamiltonian equations of motion are :

$$\dot{p} = -\frac{\partial V}{\partial q}, \quad \dot{q} = \frac{p}{m}$$

From  $\textcircled{1}$ ,  $p = \sqrt{2m(E-V)}$

$$\Rightarrow \frac{dq}{dt} = \sqrt{\frac{2}{m}} \sqrt{(E-V)}$$

$$\Rightarrow \frac{T}{2} = \int_{q_1}^{q_2} \frac{1}{\sqrt{\frac{2}{m}}} (\sqrt{(E-V)})^{-1} dq \quad \text{where } T \text{ is the}$$

time period of oscillation.

$$\Rightarrow T = \sqrt{2m} \int_{q_1}^{q_2} (\sqrt{(E-V)})^{-1} dq.$$

Now consider,

$$\frac{d}{dE} \int_{q_1}^{q_2} (\sqrt{(E-V)})^{-1} dq$$



Using Leibniz Integral rule,

$$\frac{d}{dt} \int_{q_1}^{q_2} (\sqrt{E-V}) dq = \int_{q_1}^{q_2} \frac{dq}{2\sqrt{E-V}} + \sqrt{E-V(q_2)} \frac{dq_2}{dt} - \sqrt{E-V(q_1)} \frac{dq_1}{dt}$$

Note that  $q_1$  &  $q_2$  are defined such that  $V(q_1) = V(q_2) = E$

$$\Rightarrow \frac{d}{dE} \int_{q_1}^{q_2} \sqrt{(E-V)} dq = \frac{1}{2} \int_{q_1}^{q_2} \frac{dq}{\sqrt{E-V}}$$

Substituting this into the expression for time period,

$$T = 2\sqrt{2m} \frac{d}{dE} \int_{q_1}^{q_2} dq \sqrt{E-V}$$

For some potential function  $V_0(q)$ ,

$$T_0(E) = 2\sqrt{2m} \frac{d}{dE} \int_{q_1^0}^{q_2^0} dq \sqrt{E-V_0}$$

$$V_0(q_1^0) = V_0(q_2^0) = 0.$$

We consider a small perturbation to  $V_0$ ,

$$V_0 \rightarrow V_0(q) + \epsilon V_1(q), \quad \epsilon \rightarrow 0$$

The limits of motion then change to,  $q_1$  &  $q_2$  st.

$$E = V_0(q_1) + \epsilon V_1(q_1) = V_0(q_2) + \epsilon V_1(q_2)$$

$$q_1 = q_1^0 + \delta q_1$$

$$q_2 = q_2^0 + \delta q_2$$

Then

$$V_0(q_1^0) = V_0(q_1 + \delta q_1) + \epsilon V_1(q_1 + \delta q_1)$$

Assuming the potentials are well behaved & the perturbation is not too large,

$$V_0(q_1^0) = V_0(q_1) + V_0'(q_1^0) \delta q_1 + \epsilon V_1(q_1^0) + \epsilon V_1'(q_1^0) \delta q_1$$

Then to a first order approximation,

$$\delta q_1 = \frac{-\epsilon V_1(q_1^0)}{V_0'(q_1^0)} = \frac{-\epsilon E}{V_0'(q_1^0)}$$

Similarly  $\delta q_2 = -\epsilon \frac{V_1(q_2^0)}{V_0'(q_2^0)} = \frac{-\epsilon E}{V_0'(q_2^0)}$

Now,

$$T(E) = 2\sqrt{2m} \frac{d}{dE} \int_{q_1}^{q_2} dq \sqrt{E - V_0 - \epsilon V_1}$$

$$\Rightarrow T(E) = 2\sqrt{2m} \frac{d}{dE} \left[ \int_{q_1}^{q_1^0} + \int_{q_1^0}^{q_2^0} + \int_{q_2^0}^{q_2} \right] dq \sqrt{E - V_0 - \epsilon V_1}$$

$\because \epsilon$  is small, the integrals can be reduced to

$$T(E) = 2\sqrt{2m} \frac{d}{dE} \left[ \int_{q_1^0}^{q_2^0} \left( \sqrt{E - V_0} + \frac{\epsilon E}{V_0'(q_1^0)} + \frac{\epsilon E}{V_0'(q_2^0)} \right) dq + \int_{q_1^0}^{q_2^0} dq \sqrt{E - V_0 - \epsilon V_1} \right]$$

$$\Rightarrow T(E) = 2\sqrt{2m} \frac{d}{dE} \left[ \left( \sqrt{-V_1(q_1^0)} \epsilon \right) \frac{E\epsilon}{V_0'(q_1^0)} - \frac{E\epsilon}{V_0'(q_2^0)} \sqrt{-\epsilon V_1(q_2^0)} + \int_{q_1^0}^{q_2^0} dq \sqrt{E - V_0 - \epsilon V_1} \right]$$

Note that the first two terms are of order  $\epsilon^{1.5}$ . So we neglect those terms to get

$$T = 2\sqrt{2m} \frac{d}{dE} \int_{q_1}^{q_2} dq \sqrt{E - V_0(q)} \left[ 1 - \frac{\epsilon V_1(q)}{\sqrt{E - V_0(q)}} \right]$$

$$\because \epsilon \text{ is small, } \left( 1 - \frac{\epsilon V_1}{\sqrt{E - V_0}} \right)^{1/2} \approx 1 - \frac{1}{2} \frac{\epsilon V_1}{\sqrt{E - V_0}}$$

$$\Rightarrow T = 2\sqrt{2m} \frac{d}{dE} \left[ \int_{q_1}^{q_2} dq \sqrt{E - V_0} - \frac{1}{2} \int_{q_1}^{q_2} \frac{\epsilon V_1(q)}{\sqrt{E - V_0}} dq \right]$$

$$\Rightarrow T = T_0 - \epsilon \sqrt{2m} \frac{d}{dE} \int_{q_1}^{q_2} \frac{V_1(q)}{\sqrt{E - V_0(q)}} dq$$

If  $T = T_0(E) + \epsilon T_1(E)$ . Then

$$T_1(E) = -\sqrt{2m} \frac{d}{dE} \int_{q_1}^{q_2} \frac{V_1(q)}{\sqrt{E - V_0(q)}} dq$$