

# Fronts II: Review Fisher (Unstable) Bi-stable

Recall:

Turing  $\rightarrow$   $\int$  NL reaction-diffusion system  
 $\{ \theta = \infty \} \rightarrow$  dynamical system.

Turing instability results from  
 $D_r \neq 1$  diffusion + perturbation  
about fixed point.

- if multiple fixed points, notion  
of a "front" linking differing  
domains  is naturally  
of interest.

- In MFE, fronts appear at avalanche  
modelling, transport barriers, etc.

Fronts come in two (at least) basic  
categories:

- unstable / 2<sup>nd</sup> order / Fisher
- bi-stable / 1<sup>st</sup> order / Fitzhugh-Nagumo

$$\partial_t u = D \partial_x^2 u + f(u)$$

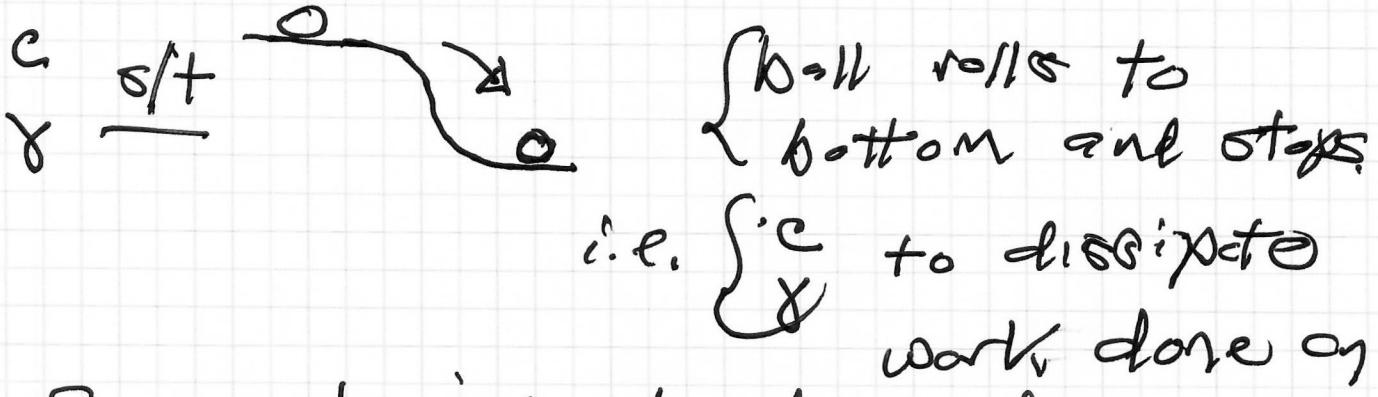
$$f(u) = \gamma(u - \alpha u^2)$$

- uni-stable  $\begin{cases} u=0 \text{ unstable} \\ u=\pm 1 \text{ stable} \end{cases}$
- Front prop.  $\rightarrow$  diffn +  $\gamma$   
 $\rightarrow$  will show  $\dot{u} \cdot c = 2\sqrt{\gamma D}$

- $u = F(x - ct)$  Key question  $\rightarrow$   
 what is speed  $c$   
 $\hookrightarrow$  travelling wave solution

$$-cF' = D F'' + F(F)$$

$$-c\dot{x} = M\ddot{x} - \partial V / \partial x$$



- For analysis: Leading edge



- treat front as exponential in moving frame

- accurate for front, not saturated state  $u$ .

$$u = A e^{-k(x-cf)}$$

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⇒ consistency of front solution is

$$c = 2 (\gamma D)^{1/2}$$

speed set the front is marginally stable in co-moving frame

i.e.  $\gamma \approx c \partial_x$

- Front is stable  $\rightarrow$  can extract speed from stability analysis
- Front: asymptotic support leading edge.

### Bi-stable Front

→ What of front which connects two stable fixed points?

→ In practice:

- Front, in effect, is a switch between 2 states.

→ in practice, such systems will have 2 stable, 1 unstable roots

Classic example: EN system

(Toy version of H-H model of neuron signals)

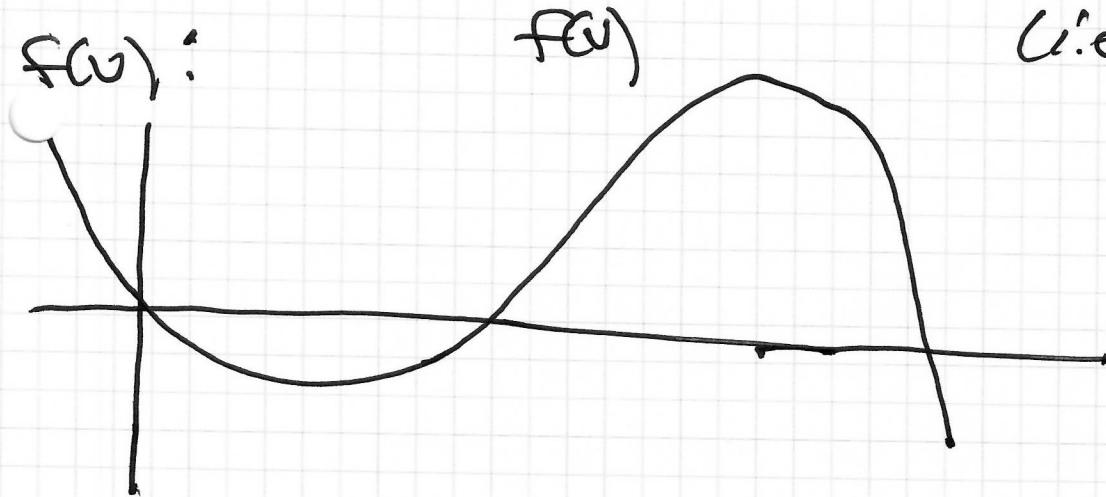
$$\frac{\partial V}{\partial t} = f(V) - w + I_a + D \frac{\partial^2 V}{\partial x^2}$$

Unstable

$$\frac{\partial w}{\partial t} = bV - \gamma w$$

fast  
(i.e. sodium)

slow  
(i.e. calcium)

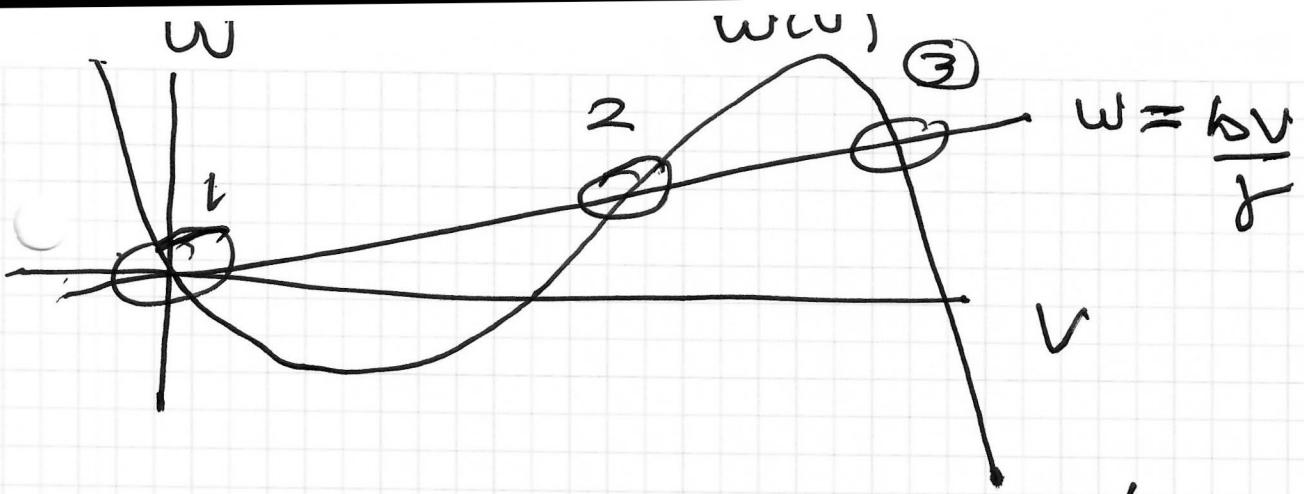


so (ion I)

$$w = f(V) = w(V)$$

$$w = bV/\gamma$$

→ fixed pts  
of state of system



evident: ①, ③ stable:  $f' < 0$   
 ② unstable:  $f' > 0$ .

∴ → front can catch/follow transition  
 between 2 stable fixed pts.

→ unstable part ('pawer')  
 front motion (akin Fisher)

### Simple/Basic Bistable Problem

$$\frac{\partial u}{\partial t} = f(u) + D \partial^2 u$$

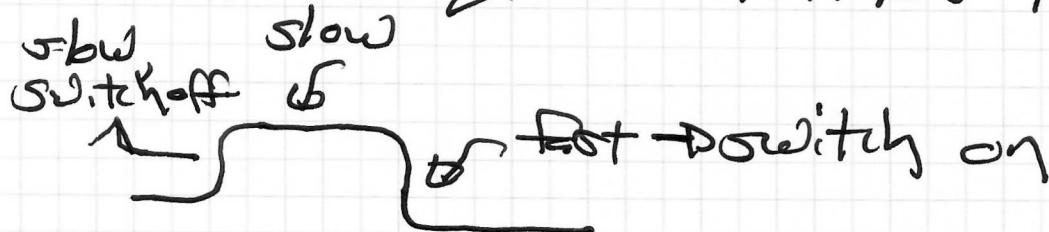
$$f(u) = A(u - u_1)(u_2 - u)(u - u_3)$$

- counter-part of Fisher
- but bistable, i.e.  $f'(u_1) < 0$   
 $\rightarrow$  stable
- $f'(u_2) > 0$   
 $\rightarrow$  unstable

## Aaside:

- aim of FN system is to describe pulses in excitable media

- Pulses require multiple time scale



Idea of FN:

switchoff flat top  $\sigma_{switch off}$

$$\Rightarrow = C_2 \int \cdot \overline{\quad} \quad \quad \quad C_1'$$

To maintain identity/coherence of pulse, need:  $C_1 = C_2$

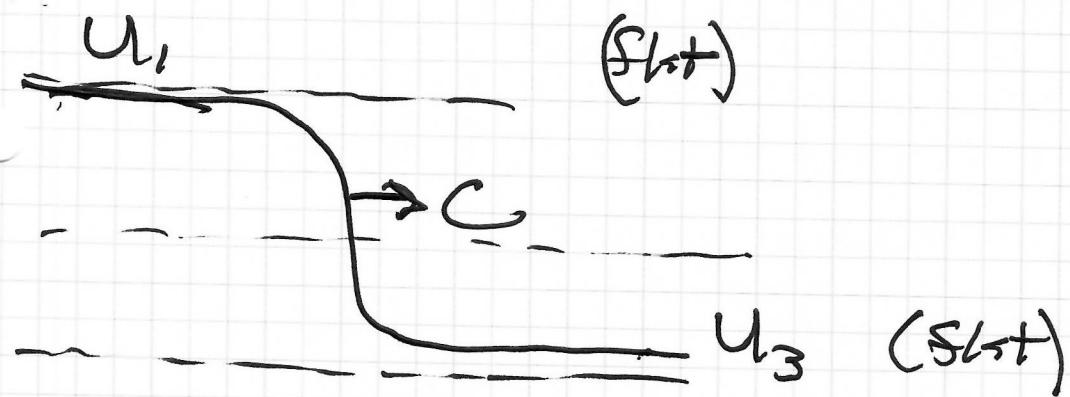
- key element: switch-on/off front.

- Switch-on starts from  $V \rightarrow 0$

$$\Rightarrow \boxed{\partial_t u = D \partial_x^2 u + f(u)}$$

simple system  
above.

As usual:



As usual, look for speed \$c\$ via traveling wave:

$$u = u(x - ct)$$

$$-cu' = \partial u'' + f(u)$$

$$u' \left[ -cu' = \partial u'' + f(u) \right]$$

so

$$-c \int_{x(u_3)}^{x(u_1)} u'^2 dx = \int_{x(u_3)}^{x(u_1)} u'' u''' dx + \int_{x(u_3)}^{x(u_1)} u f(u) dy.$$

(1)                          (2)                          (3)

$$\int_{x(u_3)}^{x(u_1)} u u''' dx = \int_{x(u_3)}^{x(u_1)} \frac{d}{dx} \left( \frac{u^2}{2} \right) dx$$

$$= 0, \quad \text{as } u' = 0 \text{ on both sides front.}$$

$$\textcircled{2} \quad \int_{x(u_3)}^{x(u_1)} dx \int f(u) = \int_{x(u_3)}^{x(u_1)} du f(u)$$

$$= \int_{u_3}^{u_1} du f(u)$$

$$\textcircled{3} = -c \int_{-\infty}^{+\infty} u^2 dx$$

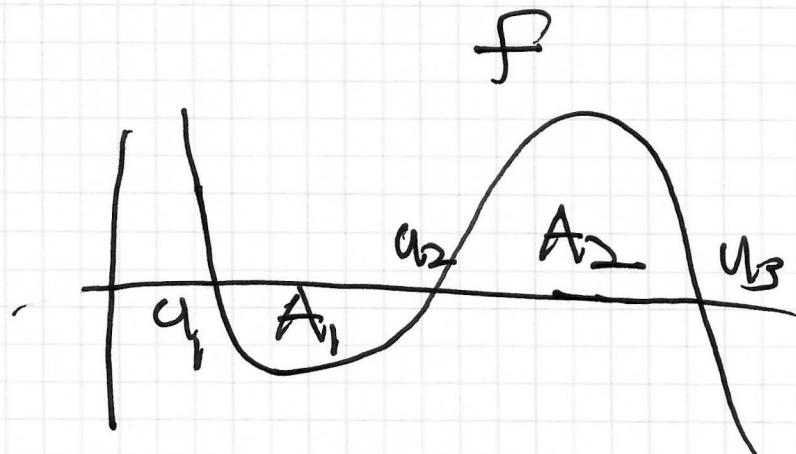
non zero

$$\textcircled{4} \quad C = - \int_{-u_3}^{u_1} f(u) du / \int_{-\infty}^{+\infty} u^2 dx$$

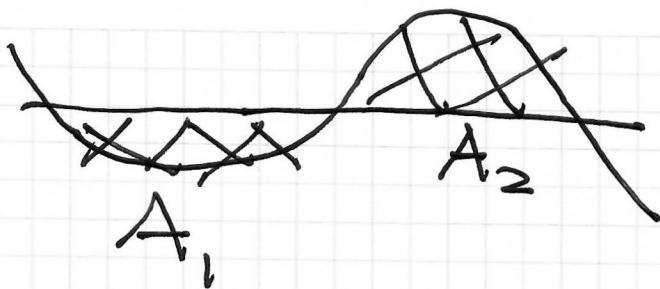
front speed.

$$C \sim - \int_{u_3}^{u_1} f(u) du$$

$$= \int_{u_1}^{u_3} du f(u)$$



i.e.  $C$  linked to area under  $f \rightarrow$  curve with 3 zero-crossings.

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$A_2 > A_1 \rightarrow C > 0$  - front advances

toward  $x > 0$

$A_1 < A_2 \rightarrow C < 0$  - front advances

toward  $x < 0$

$A_1 = A_2 \rightarrow C = 0$  - front stationary

- co-existence

→ Area rule is akin to Maxwell construction in thermodynamics.

Equal areas  $\Leftrightarrow$  co-existence of phases.

→ Bistable dynamics is much richer than simple Bel-McK dynamics of Fisher.

$$\begin{aligned}
 L(u) &= D \left( a(u-u_1)(u-u_3) \right)^1 + \\
 &\quad + \left[ C a (u-u_1) (u-u_3) \right. \\
 &\quad \left. + A (u-u_1) (u_2-u) (u-u_3) \right] \\
 &= Da \left( u (u-u_3) + \cancel{a} (u-u_1) \cancel{u} \right) \\
 &\quad + \left[ \quad \right] \\
 &= Da \left[ a (u-u_1) (u-u_3) (u-u_3) \right. \\
 &\quad \left. + a (u-u_1)^2 (u-u_3) \right] \\
 &\quad + \left[ \quad \right] = 0
 \end{aligned}$$

re-grouping:

$$\begin{aligned}
 L(u) &= (u-u_1) (u-u_3) \left[ (2Da^2 - A) u \right. \\
 &\quad \left. - (Da^2(u_1+u_3) - Ca - Au_3) \right]
 \end{aligned}$$

$\approx$

$$L(u) = 0$$

$$\Rightarrow 2Da^2 = A$$

$$Da^2(u_1 + u_3) - 4u_2 - c\phi = 0$$

$$\underline{a} = (A/2D)^{1/2}$$

and

$$c = (A\delta/2)^{1/2}(u_1 - 2u_2 + u_3)$$

$$A \leftrightarrow \gamma \Rightarrow c \sim (D\delta)^{1/2}, \text{ as before}$$

$$\text{and } c \cong \sqrt{D\delta} c(u_1, u_2, u_3)$$

param in reaction.

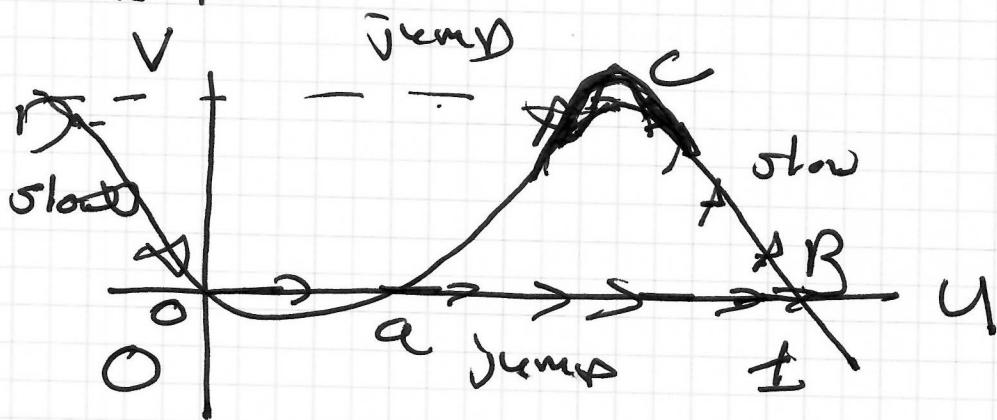
$$u_2 = (u_1 + u_3)/2 \rightarrow \text{stationary front.}$$

Thus, speed set by parameters in reaction function. Weighted balance between there is the key,

# Toward Pulses/Waves

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Consider:



ABCDC

$$\partial_t u = f(u) - v - D \partial_x^2 u$$

$$\partial_t v = bu - \gamma v$$

OKAYI

for slow eqn:

$$v_t = \epsilon(Lu - MV)$$

treat  $V$  as fixed  
for fast bifurcations

$$\text{if } V \approx 0 \quad \underline{\text{i.e.}}$$

$$= v_c$$

$$\partial_t u = Du_{xx} + f(u)$$

$$f(u) = u(a-u)(u-1)$$

→ leading edge  
set at  
 $v = 0$

at  $V$  time:

13.

$$U_t = D U_{xx} + f(U) - V_c$$

↓  
choose effective  
reaction function

so

$$C_- = \left(\frac{D}{\omega}\right)^{1/2} (U_c - 2U_p + U_0)$$

where  $U_c, U_p, U_0$  roots of

$$\underline{f(U) = V_c} \rightarrow \text{speed } s$$

function of  
amplitude of  $V$ .

then pulse conduction:

$$C_+ = C_-(V_c)$$

guarantees that pulse will not  
die  $\downarrow$   $s$   $\rightarrow$  i.e. forward and backward  
transitions propagate together

at same speed. This sets a  
critical amplitude  $V_c$  for

pulse to be excited.

Slow evolution links the up, back transitions.

" "

- The FN model is a simple model of pulse in excitable media,
- so constructed from Kuramoto element of bistable front.

If time  $\rightarrow$  space, etc.

In MFE - "Reaction is in the diffusion."

- More akin Cahn-Hilliard