

Physics 216/116

Lecture V - Instabilities I (Life after spheres)

I.) \rightarrow Convection / Rayleigh-Benard

- convection: heat \rightarrow $\Delta T \rightarrow$ motion
highly relevant
- ideal physics - Schwarzschild criterion
- dissipation and Rayleigh, Prandtl number
- Rayleigh-Benard Equations
- Boundary conditions and Re. crit.

II.) \rightarrow Rotating Convection

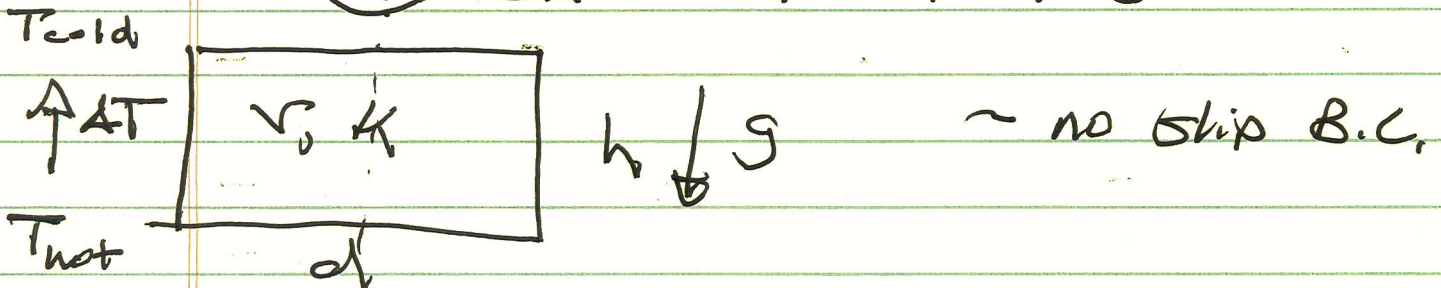
- Froude-in law with rotation
- Taylor-Prandtl Theorem, implications for cells
- rotating convection
- physics of inertial waves
- relation magneto-convection, etc.

Convection (Rayleigh-Bénard)

- ~ thousands papers
- ~ central to key problems of heat transport, general circulation

Prototype:

$\curvearrowright \Omega$ - box can rotate

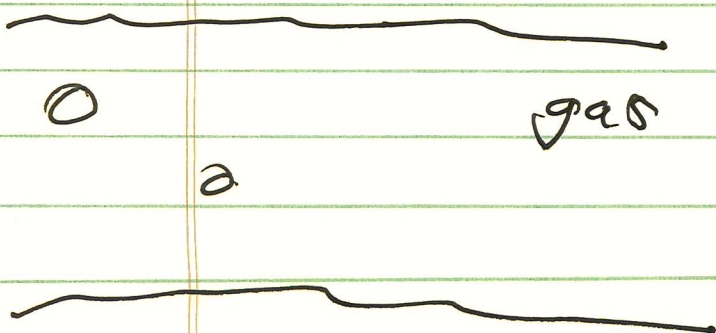


- critical ΔT or Ra for instability
- pattern structure
- effect rotation

i.) Heuristics - Ideal Fluid / Gas

i.e. stellar atmosphere

→ Schwarzschild Criterion (ideal)



$$\frac{dp}{dz} = -\rho g$$

(eqn \rightarrow hydrostatic)
($g > 0$)

$d\rho/dz < 0, \quad \partial P/\partial z < 0.$

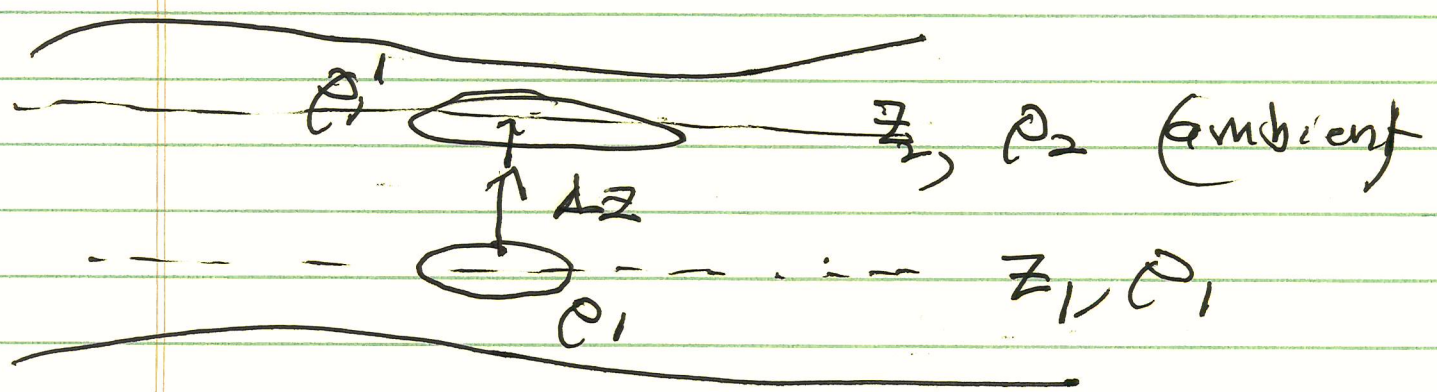
$\rho\rho^{-\gamma} \approx \text{const} \rightarrow \text{eqn. state (ideal gas)}$

Basic idea:

- virtual displacement of slug/blob ρ_1 upward to ρ_1' (after thermodynamic equilibration)

- $\rho_1' < \rho_2 \rightarrow$ blob buoyant, rises, unstable

- $\rho_1' > \rho_2 \rightarrow$ blob sinks, stable



For infinitesimal displacement:

Now, $\rho_2 = \rho_1 + \frac{d\rho}{dz} \Delta z$

What is ρ_1' \rightarrow density of $\left. \begin{matrix} \text{perturbed} \\ \text{displaced} \end{matrix} \right\}$ blob ρ_1 ?

Point:

- blob ρ_1 equilibrates pressure with surroundings $\rightarrow \rho_1$

- why? $\frac{\Delta z}{c_s} \ll T_{rise}$

i.e. rise time is long, slow
 \rightarrow "incompressible":

then

$$\rho_1^{-\gamma} = \text{const} = \rho_1' \rho_1'^{-\gamma}$$

but $\rho_1' = \rho_2 \rightarrow$ i.e. surroundings of test blob
 $(dp = 0)$

$$\rho_2 = \left(\rho_1 + \frac{d\rho}{dz} \Delta z \right) \rightarrow \text{incompressible}$$

so

$$P_1 \rho_1^{-\gamma} = \left(P_1 + \frac{dP_1}{dz} \Delta z \right) \rho_1'^{-\gamma}$$

$$\left(\frac{\rho_1'}{\rho_1} \right)^{\gamma} = \left(1 + \frac{\Delta z}{P_1} \frac{dP_1}{dz} \right)$$

$$\rho_1' = \rho_1 \left(1 + \frac{\Delta z}{P_1} \frac{dP_1}{dz} \right)^{1/\gamma}$$

$$= \left(1 + \frac{1}{\gamma} \frac{\Delta z}{P_1} \frac{dP_1}{dz} \right) \rho_1$$

$$\rho_2 = \left(1 + \frac{1}{\rho_1} \Delta z \frac{d\rho_1}{dz} \right) \rho_1$$

$$\rho_1' < \rho_2 \iff \frac{1}{\gamma} \frac{\Delta z}{P_1} \frac{dP_1}{dz} < \frac{\Delta z}{\rho_1} \frac{d\rho_1}{dz}$$

buoyancy

$$\frac{1}{\gamma} \frac{1}{P_1} \frac{dP_1}{dz} < \frac{1}{\rho_1} \frac{d\rho_1}{dz}$$

or, as both gradients negative

$$\left| \frac{-1}{\gamma} \frac{1}{\rho} \frac{d\rho}{dz} \right| > \left| \frac{1}{\rho} \frac{d\rho}{dz} \right|$$

Now, $S = C \ln P \rho^{-\gamma}$

$$\frac{dS}{dz} = C \left[\frac{1}{\rho} \frac{d\rho}{dz} - \frac{\gamma}{\rho} \frac{d\rho}{dz} \right]$$

knowing $\rightarrow \frac{dS}{dz} < 0 \rightarrow$ free energy available.

$\frac{dS}{dz} < 0$ $\frac{dS}{dz} = 0$ $\frac{dS}{dz} > 0$
 superadiabatically adiabatically stratified
 subadiabatically

$$\frac{dS}{dz} < 0 \rightarrow \frac{1}{\rho} \frac{d\rho}{dz} < \frac{\gamma}{\rho} \frac{d\rho}{dz}$$

$$P = k_B \rho T$$

$$\frac{1}{T} \frac{dT}{dz} < \frac{(\gamma-1)}{\gamma} \frac{d\rho}{dz}$$

γ captures essential thermal properties

$\gamma-1$ specifies how steep DT must be relative to density.

(iv) Scales

- "Incompressibility"

$$\frac{\partial \rho}{\partial t} + \underline{\nabla} \cdot (\rho \underline{v}) = 0$$

$$\frac{\partial \tilde{\rho}}{\partial t} + v_z \frac{d\rho/dz}{dz} + \rho_0 \underline{\nabla} \cdot \tilde{\underline{v}} = 0$$

$$\frac{\tilde{\rho}}{\rho_0} \sim \frac{\tilde{v}_z}{L_0}, \quad \frac{\tilde{v}_z}{L_0}, \quad k_z \tilde{v}_z$$

$$\tilde{T} \gg (L_0 c_s)^{-1}$$

(i.e.

$$\frac{\tilde{\rho}}{\rho_0} \sim \frac{\tilde{v}_z}{c_s}$$

→ time long relative to
sound transit time

[incompressible - no density
perturbation]
drop ①

$$L_0 \sim L_s > k_z^{-1} \rightarrow \text{drop } \textcircled{2}$$

$$\underline{\nabla} \cdot \underline{v} \approx 0$$

for { wavelength \ll scale
height
 $|\tilde{v}| \ll c_s$
 $\tilde{T} \gg \lambda/c_s$

→ simplest subsonic extension,

$\nabla \cdot (\rho \underline{v}) = 0 \rightarrow$ incompressible mass flow, (anelastic).

$\underline{\nabla} \cdot \underline{v} + \frac{\tilde{v}_z}{\bar{\rho}} \frac{d\rho}{dz} = 0$ → decouples sound wave
→ retains finite scale height

→ modifies freezing-in law.

To identify scalar, convenient to work with S , in full analysis (as in ideal fluid):

$\partial_t S + \underline{v} \cdot \nabla S = 0$

$S' = \underbrace{\langle S \rangle}_{\text{mean}} + S''$
↳ fluctuation

$\frac{\partial \langle S \rangle}{\partial t} + \tilde{v} \frac{d \langle S \rangle}{dz} = 0$

$S'' \sim \ln(P_0^{-\sigma}) \sim \ln(T_0^{-(\sigma-1)})$

$$\frac{\delta \rho}{\rho_0} = \left[\frac{\delta T}{T_0} - (\gamma - 1) \frac{\delta p}{\rho_0} \right]$$

Now, $\nabla \cdot \underline{v} \approx 0$, so $d\rho = 0$.

$$\left[\frac{\partial \underline{v}}{\partial t} = - \frac{\nabla p}{\rho} + \underline{g} \right]$$

$$\partial_t \nabla \cdot \underline{v} = - \frac{\nabla^2 p}{\rho_0} + \nabla \cdot \underline{g}$$

(scaled)

$$\left[\begin{aligned} \nabla \cdot \underline{v} \approx 0 &\Rightarrow \nabla^2 \tilde{p} = 0 \\ k^2 \tilde{p} &= 0 \\ \partial^2 \tilde{p} &= - \frac{\delta T}{T_0} \end{aligned} \right]$$

$$\partial^2 \tilde{p} = - \frac{\delta T}{T_0}$$

$$\frac{\delta \rho}{\rho_0} = \gamma \frac{\delta T}{T_0}$$

→ entropy perturbation tied to temperature perturbation, alone.

For estimation:

$$\frac{\partial \tilde{v}_z}{\partial t} = - \frac{\partial_z \tilde{p}}{\rho_0} - g \frac{\tilde{\rho}}{\rho_0} \tilde{z}$$

$\tilde{p} \rightarrow 0$

$$\approx g \frac{\tilde{\rho}}{\rho_0} \tilde{z}$$

$$\gamma \frac{\partial \tilde{T}/T_0}{\partial t} = - \tilde{v}_z \frac{dS_0}{dz}$$

$$\frac{\rho_0}{T_0} \tilde{T} \sim \frac{1}{\gamma} \tilde{\rho} \tilde{v}_z \frac{dS_0}{dz}$$

$$\frac{1}{\tau_b} \sim \frac{g}{\gamma} \frac{dS_0}{dz}$$

→ buoyancy time scale.

Now, consider dissipation:

viscosity:

$$\partial_t \rightarrow \partial_t - \nu \nabla^2, \quad 1/\tau_\nu \sim \frac{\nu}{l^2}$$

thermal:

$$\partial_t \rightarrow \partial_t - K \nabla^2, \quad 1/\tau_K \sim K/l^2$$

→ Diffusion effects will smear out heat parcel if:

$$1/Tr \tau_H \approx 1/\tau_b^2$$

i.e. parcel needs free energy sufficient to overcome dissipation

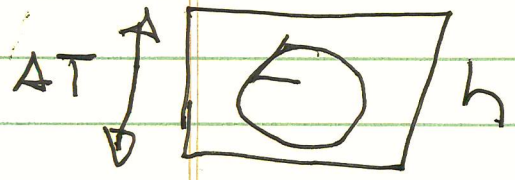
$$\frac{Tr \tau_H}{\tau_b^2} \sim \frac{g \Delta \rho \Delta z}{\rho \nu} l^4 / \nu K$$

$$Ra = \frac{g \Delta \rho \Delta z}{\rho \nu} l^4 / \nu K$$

Rayleigh #

For fluid in box:

key dimensionless number in fluid mechanics.



$$\rho \equiv \text{const}$$
$$\rho \beta = -\alpha \rho \Delta T$$

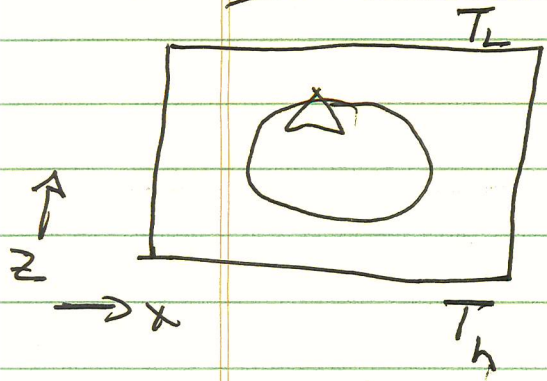
↓
coeff of thermal expansion

$$Ra = \frac{g \Delta T \alpha h^3}{\nu K}$$

clearly need $Ra > Ra_{crit}$ for convective instability.

- free energy
- sufficient to overcome damping

cd) Calculation



- consider vorticity \perp to x, z
 $\Rightarrow \omega_y$

- $\underline{v} = \nabla \phi \times \hat{y}$

$\omega_y = -\partial_x^2 \phi - \partial_z^2 \phi$

esthm: hydro ρ_0 const
 $\nabla T = 0$ + h.c.

Now, $\rho = \rho_0 + \tilde{\rho}$

where $\tilde{\rho} = -\rho_0 \alpha \tilde{T}$

$= -\frac{1}{\rho_0} \left(\frac{\partial \rho}{\partial T} \right)_p \equiv$ coeff thermal expansion

$\rho_0 = -\rho_0 g z$ (hydrostatics)
 $= -\rho_0 g z$

N.B. incompressibility:

$$\Delta P \sim \rho g h$$

$$P = \rho c_s^2 \quad \hookrightarrow h \tau$$

$$\frac{\Delta P}{P} \sim \frac{\Delta \rho}{\rho} \sim \frac{g h}{c_s^2}$$

need $\frac{\Delta \rho}{\rho} \ll 1$ for validity of $\left\{ \begin{array}{l} \rho = \text{const} \\ \text{hydrostatics} \end{array} \right.$

$$\text{so } \frac{\Delta \rho}{\rho} \ll 1 \rightarrow \frac{g h}{c_s^2} \ll 1 \quad \text{and} \quad \frac{g h}{c_s^2} \ll \alpha \Delta T$$

(thermally induced strat.)

Now,

$$\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} = -\frac{1}{\rho} \nabla P + \nu \nabla^2 \underline{v} - g \hat{z}$$

$$\rho = \rho_0 + \rho^1$$

$$P = P_0 + P^1$$

$$\frac{\nabla P}{\rho} = \frac{\nabla P_0}{\rho_0} + \frac{\nabla P^1}{\rho_0} - \frac{\nabla P_0}{\rho_0^2} \tilde{\rho}$$

$$= -g \hat{z} + \frac{\nabla P^1}{\rho_0} - g \hat{z} \times \tilde{T}$$

$$\frac{\partial p}{\partial z} = -\rho \hat{z} + \frac{\partial}{\partial z} \left(\frac{\rho}{\rho_0} \right) - g \alpha T \hat{z}$$

↓ equilibrium ↓ $\nabla \cdot \underline{v} = 0$ ↓ buoyancy

Eq

$$\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} = -\frac{\partial p}{\partial z} - g \hat{z}$$

equilibrium

$$0 = -\frac{\partial p}{\partial z} - g \hat{z} = g \hat{z} - g \hat{z} = 0$$

pert

$$\frac{\partial \underline{v}}{\partial t} = -\nabla \left(\frac{p}{\rho_0} \right) + g \alpha T \hat{z}$$

$$\hat{y} \cdot \nabla \times \quad \text{and} \quad \underline{v} = \nabla \phi \times \hat{y}$$

$$-\frac{\partial}{\partial t} \nabla^2 \phi = g \alpha \frac{\partial}{\partial z} \left(\frac{T}{T_0} \right) - \nu \nabla^2 (-\nabla^2 \phi)$$

$$\rho \frac{dT}{T_0} = -\tilde{v}_z \frac{dT_0}{dz} + \kappa \nabla^2 T$$

$$\tilde{v}_z = \nabla \times \mathcal{A}$$

Now, universal notation:

$$\hat{v}_z \rightarrow w$$

$$\beta = -\frac{dT}{dz} = \frac{\Delta T}{h}$$

$$\frac{T}{T_0} \rightarrow \theta$$

$$\sigma \rho = -\alpha \rho T$$

$$\omega_z \rightarrow \omega$$

see Chandrasekhar

and $\vec{z} \cdot (\vec{D} \times \vec{D} \times \text{NSE}) \Rightarrow$

$$\frac{\partial}{\partial t} \vec{D}^2 W = g \alpha \left(\vec{D}_x^2 \Theta \right) + \nu \vec{D}^2 \vec{D}^2 W$$

$$\frac{\partial \Theta}{\partial t} = \beta W + K \vec{D}^2 \Theta$$

standard form.

For local theory: dispersion relation.

$$(-i\omega + \nu k^2) (-i\omega + K k^2)$$

$$= g \alpha \beta \frac{k_x^2}{K^2}$$

$$k^2 = k_x^2 + k_z^2$$

N.B. : $\begin{cases} \nabla_h^2 \rightarrow \partial_x^2 + \cancel{\partial_y^2} \\ \nabla^2 = \partial_x^2 + \partial_z^2 \end{cases}$

and : $\begin{cases} T_0 = T_b - \beta z \\ \beta = \Delta T/h \end{cases}$

can de-dimensionlize :

length $\rightarrow h$
 time $\rightarrow h^2/K$

$v \rightarrow h / (h^2/K) = K/h$

$K^2/h^2 \leftarrow \rho/\rho_0$

$T \leftarrow K \nu / \alpha g h^3$

\Rightarrow de-dim

$$\partial_t \nabla^2 W = P \nabla^4 W + \partial_x^2 \Theta$$

$$\partial_t \Theta = \nabla^2 \Theta + Ra W$$

2 param : $Ra = g \alpha \beta h^3 / \nu K \rightarrow$ Rayleigh #

$P = \nu / K \rightarrow$ Prandtl #
 relative strength dissipation

Game now becomes:

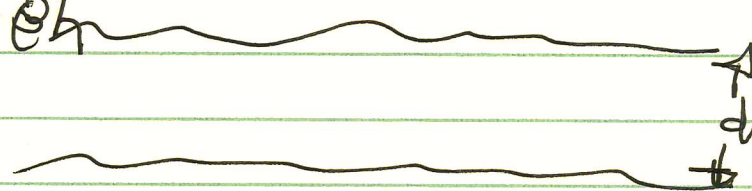
- take $Pr \sim 1$.
- usual Kx s/t
- Ra_{crit} for onset instability.

⇒ Laborious;

What are boundary conditions?

⇒ B.C. set effect of dissipation and thus Ra_{crit} .

Assume $T_0 = \Theta h$
 wide tank
 (don't concern T_0 lateral)



\bar{T} fixed: $\tilde{\Theta} = 0$ at $z=0, h$

walls: $\tilde{W} = \tilde{V}_z = 0$ at $z=0, h$

but 6th order system (4 for w , 2 for Θ)

→ need 2 more.

Can envision two scenarios for two more b.c.'s:

① no-slip

② stress free (Rayleigh 1916, 2 free boundaries)

① No-slip (rigid)

$$\rightarrow \tilde{V}_h \Big|_{0,h} = 0 \quad \left. \begin{array}{l} \text{horizontal/tangential} \\ \text{velocity vanishes at} \\ \phantom{\text{velocity vanishes at}} \Big|_{0,h} \end{array} \right\}$$

but, work with w !

$$\nabla \cdot \underline{v} = 0$$

$$\nabla_h \tilde{V}_h + \partial_z \tilde{V}_z = 0$$

as all ∇_h of \tilde{V}_h vanish as \tilde{V}_h vanishes

$$\Leftrightarrow \left. \nabla_h \tilde{V}_h(z) \right|_{0,h} = 0 \quad \Leftrightarrow \left. \nabla_{\text{tan}} \tilde{V}_h(z) \right|_{0,h} = 0$$

$$\Rightarrow \nabla_h \tilde{V}_h = 0$$

σ

$$\partial_z W = 0$$

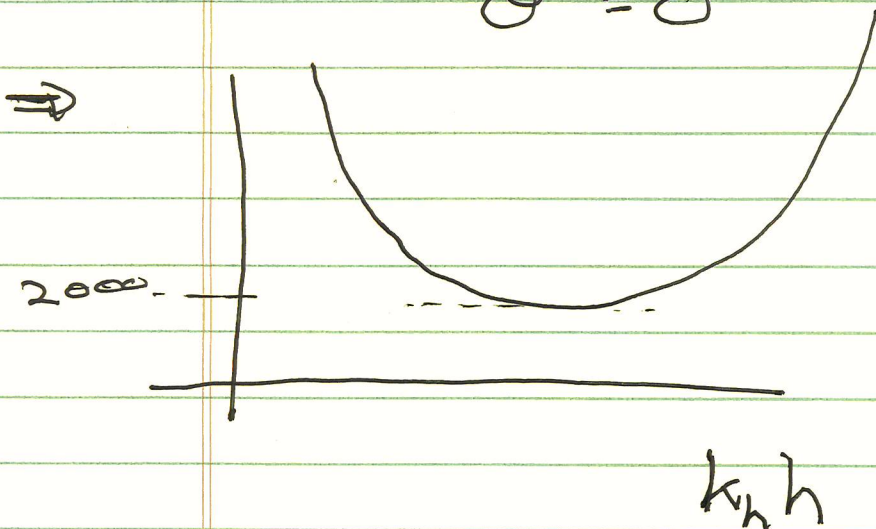
R.C.'s : $\partial_z W|_{z=0,h} = 0$

$z=0, h$

$w = 0$

$z=0, h$

$\theta = 0$



Chandra,
Fig. ~~38~~ 39

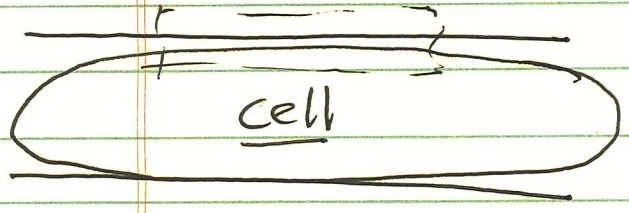
$Ra_{crit} \sim 2000$

- ~~Where~~ Where does the shape come from?

- high k ? - $\nu k^2 = \nu(k_h^2 + k_v^2)$
 $\kappa k^2 = \kappa(k_h^2 + k_v^2)$

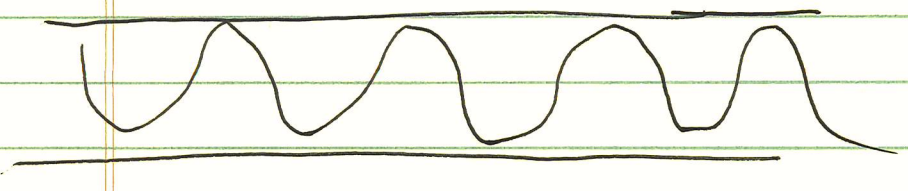
rising $k_h \rightarrow$ rising dissipation due to diffusion
 \rightarrow rising Ra_{crit} .

- low k ? \rightarrow top, bottom boundary layer due no slip.



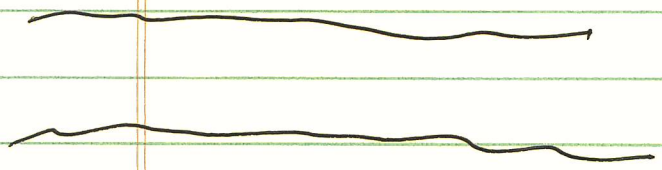
\rightarrow dissipation due viscous effects + $\nabla_h = 0$ condition at $0, h$.

v.e. compare:



\rightarrow greater curvature but less effect $\nabla_h = 0$.

② Stress free:



Free surface at top, bottom \rightarrow no stress.

τ = $- \eta \partial_z V_h$ ≡

\downarrow
shear stress delivered to surface.

so need, $\partial_z V_h |_{0, h} = 0$.

Have $\partial_h V_h = -\partial_z V_z$

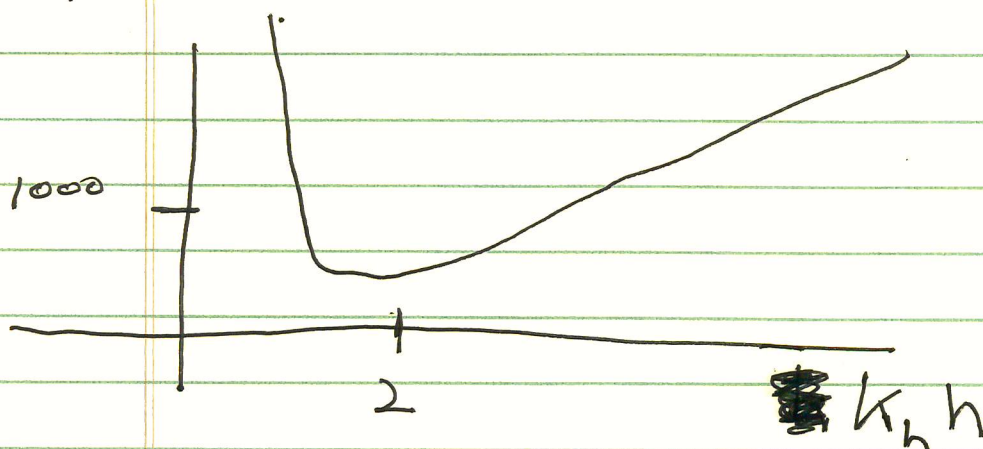
$$\partial_z \partial_h V_h = -\partial_z^2 V_z$$

$$\partial_h \partial_z V_h = 0 = -\partial_z^2 V_z$$

∞

$$\partial_z^2 W|_{z=h} = 0$$

and have:



$$Ra_{crit} \sim \frac{2\pi^4}{4}$$

for $k_h h \sim \frac{\pi}{\sqrt{2}}$
crit

→ substantially lower Ra_{crit} due
stress free b.c. → no longer
fighting no-slip condition,

- high $k \rightarrow$ increased dissipation

low $k \rightarrow$ effects layers at boundary.

