

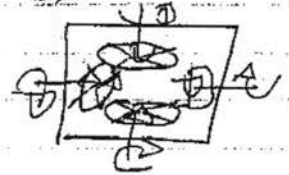
Turbulence Theory

192.

An Introduction

P. Diamond
i.e.

I.) Basis of Fluid Turbulence (30)



Characteristics of Fluid Turbulence:

"turbulent" vs "noise" → energy flux

- broad range of spatio-temporal scales excited
Ref. U. Frisch
"Turbulence - The legacy of A. N. Kolmogorov"
- decay of large scale energy → need input/stirring to maintain stationarity
- energy input dissipated as heat (to maintain stationarity) → viscosity
→ irreversibility
- irreversible mixing occurs → i.e. passive tracer
- intermittency manifested
i.e. spatial → coherent structures (i.e. vortices)
temporal → bursts probe trace
- self-similarity/scale-similarity:
turbulence looks the same on all scales, except the very largest (stirring) and the very smallest (dissipation)
Caveat: Intermittency - memory of large scales on small.

(c) Navier Stokes Equation - Describes Fluid

$$\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} = -\frac{\nabla p}{\rho} + \nu \nabla^2 \underline{v}$$

$\frac{\partial \underline{v}}{\partial t}$ → advection/straining → nonlinearity
 $\frac{\nabla p}{\rho}$ → pressure
 $\nu \nabla^2 \underline{v}$ → viscous diffusion of momentum

$\rho = 1$
here after

$$\nabla \cdot \underline{v} = 0 \quad \text{incompressibility}$$

Note: Pressure determined from incompressibility

c.e.

$$\nabla \cdot \left[\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right] = -\nabla^2 p + \nu \nabla^2 (\nabla \cdot \underline{v})$$

$$\nabla^2 p = -\nabla \cdot \left[\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right]$$

$$p = -\nabla^{-2} \left[\nabla \cdot \left[\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right] \right]$$

$$= -\frac{1}{4\pi D} \int \frac{d^3 x' \nabla_i \cdot \left[\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right]_i}{|\underline{x} - \underline{x}'|}$$

More generally, can eliminate p

$$\partial_t v_i + (\partial_{ij} - \delta_{ij} \nabla^2) \partial_j (v_j v_e) = \nu \nabla^2 v_i$$

Key Parameter: Reynolds #

$$Re = \frac{|\underline{v} \cdot \nabla \underline{v}|}{\nu \nabla^2 \underline{v}}$$

$$\sim \frac{V(L) L}{\nu}$$

\sim nonlinearity
collisional diffusion
measure of strength
of NL.

- Re usually referenced to largest scale

$$L = L_{max}$$

$$V(L) = \text{large scale velocity}$$

- Re always referenced to a particular scale

$$L_{max}, \lambda = \left[\frac{\langle (\partial_i v_j)^2 \rangle}{\langle v_i^2 \rangle} \right]^{-1/2}, \quad \lambda_{diss}, \quad (Re=1)$$

(Taylor Scale)

- $Re \gg 1$ in turbulent { pipe flow
atmosphere
etc

$$Re \sim 10^6 - 10^8, \text{ etc.}$$

i.e. planetary boundary layer: $h_{out} \sim 1 \text{ km}$
 $\sim 10^5 \text{ cm}$
 $h_{diss} \sim 1 \text{ cm}$

\Rightarrow 6 decades

- Re : measure of ratio of inertial
mixing of momentum to collisional
mixing.

(4)

ii) Experimental 'Laws' of Fully Developed Turbulence

► Much / most of turbulence theory is empirically motivated. Experimental info / results preceded sophisticated theoretical analyses....

The experimental facts:

i.) 2/3 Law (Mandane)

In a turbulent flow with $Re \gg 1$,
 $\langle \delta v(l)^2 \rangle$ (mean square velocity increment
 between two scales) separated by distance
 l) scales as $l^{2/3}$.

i.e.

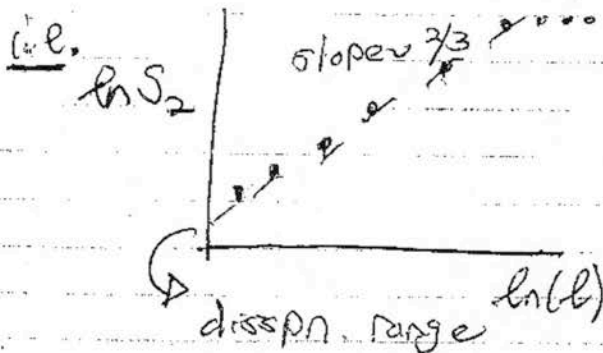
$$\delta v(l) = |v(x+l) - v(x)|$$

⇒ {a difference!}

$$S_2(l) = \langle \delta v(l)^2 \rangle \sim l^{2/3}$$

→ Fundamental scaling relation

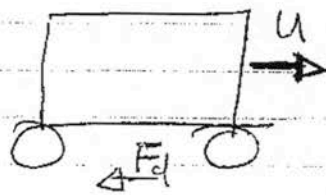
2nd order structure function



B) Law of Finite Energy Dissipation (Profound)

If in an experiment on turbulent flow, all the control parameters are kept the same, except the viscosity, which is lowered as much as possible, the energy dissipation per unit mass dE/dt behaves in a way consistent with a finite limit.

- What means 'Energy Dissipation Rate'?



Consider a car experiencing atmospheric drag

$$F_d = \frac{1}{2} C_D \rho S U^2$$

↓
face surface area

c.i.e. $\frac{\Delta p}{\Delta t}$

$$p = \rho S (U^2) U$$

→ momentum in air of slug:
 $M = \rho S U^2 \rightarrow$ mass

if assume air momentum $V = U$
completely transferred to car

$$\frac{dp}{dt}_{car} = F_d = \rho S U^2$$

$\frac{C_D}{2}(Re) \equiv$ drag coefficient (slowly varying function of Re , depends on shape, etc.)

$$\therefore \bar{F}_d = \frac{C_D}{2} \rho S U^2$$

Now, power dissipated by drag force

$$P_d = \bar{F}_d U$$

$$\Rightarrow \rho_d = \frac{C_D}{2} \rho S U^3$$

Energy dissipation rate $E = P_d / \text{Mass}$
(per volume)

$$= \frac{C_D}{2} \frac{U^3}{L}$$

also NS $\Rightarrow \partial_t \langle v^2 \rangle \sim - \langle \underline{v} \cdot \nabla v^2 \rangle \sim U^3/L$

\rightarrow Why should we care?

Note, energy budget:

$$\frac{\partial v_i}{\partial t} + v_j \partial_j v_i - \nu \nabla^2 v_i = -\partial_i p$$

$$\partial_t \frac{V_i^2}{2} + \partial_j \frac{V_j V_i^2}{2} - \nu \nabla_i \nabla^2 V_i = -V_i \partial_i p$$

$\langle \rangle \equiv$ ensemble (fast space-time avg.)

$$\partial_t \left\langle \frac{V_i^2}{2} \right\rangle + \left\langle \partial_j \frac{V_j V_i^2}{2} \right\rangle - \nu \left\langle \nabla_i \nabla^2 V_i \right\rangle$$

$\xrightarrow{\text{surface terms}} = \left\langle \cancel{\partial_i V_i p} \right\rangle$
 upon IBP

$$\Rightarrow \partial_t \left\langle \frac{V_i^2}{2} \right\rangle = -\nu \left\langle |\nabla V|^2 \right\rangle$$

but $\epsilon = -\partial_t \left\langle \frac{V_i^2}{2} \right\rangle$! (- dissipation rate)

$$\epsilon = \nu \left\langle |\nabla V|^2 \right\rangle \quad !$$

\rightarrow experiments suggest that $\epsilon \rightarrow$ finite as $\nu \rightarrow 0$! ! ! \leftrightarrow pre-markable

\rightarrow suggests that extremely large ∇V forms as $\nu \rightarrow 0$, singular vortex sheets

\Rightarrow singular velocity gradients formed in limit of weak viscosity ! !

Heart of turbulence problem is grappling with singularity (especially its degree) of velocity gradients.

No. B. : { Dissipation Law
Singularity formation is at the
heart of why turbulence is
a "hard" problem.

Re: Dissipation Law:

$$\epsilon \sim \frac{U^3}{L} \sim U^2 / (L/U)$$

$$\sim \frac{\text{K.E. per Mass}}{\text{circulation Time}}$$

i.e. \rightarrow in 1 macro circulation time, a
finite fraction of (macro) kinetic
energy is dissipated by viscosity.

\rightarrow dissipation time scale is (L/U) .

V. Kalmogorov's Hypotheses and their Predictions/
Implications. \rightarrow K41 Theory of Turbulence

1.1: In the limit of $Re \rightarrow \infty$, all possible
symmetries of the Navier-Stokes
equation, usually broken by the
mechanisms producing the turbulent
flow, are restored in a statistical
sense at small scales and away from
boundaries.

lose memory

What means?

- "small scales": $l \ll l_0$

integral scale \rightarrow characteristic of production.

- symmetries

First, symmetries of Navier-Stokes Eqn.!

a.) space translations $\underline{r} \rightarrow \underline{r} + \underline{a}$
(no explicit \underline{r} dep.)

b.) time translation $t \rightarrow t + \tau$
(no t dep.)

* c.) Galilean boosts $\begin{cases} \underline{r} \rightarrow \underline{r} + \underline{u}t \\ \underline{v} \rightarrow \underline{v} + \underline{u} \end{cases} \quad \underline{v} = \underline{u} + \underline{v}(\underline{r} - \underline{u}t)$
(no frame dep.)

i.e. $\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} = -\nabla p + \nu \nabla^2 \underline{v}$

insert \Rightarrow

$$= \underline{u} \cdot \nabla \underline{v} + \underline{u} \cdot \nabla \underline{v} + \frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} = -\nabla p + \nu \nabla^2 \underline{v}$$

d.) Parity (no preferred direction) left-right $\underline{x} \rightarrow -\underline{x}, \underline{v} \rightarrow -\underline{v}$

e.) Rotation (no preferred direction) $\begin{cases} \underline{r} \rightarrow R \underline{r} \\ \underline{v} \rightarrow R \underline{v} \end{cases}$

* e.) Scaling (for $\nu \rightarrow 0$) \Rightarrow critical: scale elimination; hand passing

$$\underline{\Gamma}, \underline{v}, t \rightarrow \lambda \underline{\Gamma}, \lambda^a \underline{v}, \lambda^b t$$

i.e. $\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} = -\nabla p$

$$\begin{aligned} \underline{v} &\rightarrow \lambda^a \underline{v} \\ t &\rightarrow \lambda^b t \end{aligned}$$

$$\frac{\lambda^a \partial \underline{v}}{\lambda^b \partial t} + \frac{\lambda^{2a}}{\lambda} \underline{v} \cdot \nabla \underline{v} = -\nabla p$$

\hookrightarrow From $\nabla \cdot \underline{v} = 0$

$$\lambda^{2a-1} = \lambda^{a-b}$$

$$b = 1-a$$

$$\Rightarrow \lambda^{-(a-1)} = \lambda^b$$

\therefore scalings $\underline{\Gamma} \rightarrow \lambda \underline{\Gamma}, \underline{v} \rightarrow \lambda^a \underline{v}, t \rightarrow \lambda^b t$

Now, turbulence onset \Rightarrow symmetry breaking!

i.e. ① KH: shear breaks $\left\{ \begin{array}{l} \text{translational} \\ \text{rotational} \end{array} \right.$ invariance

②



rigid body boundary flow, etc

③ flushing toilet $\left\{ \begin{array}{l} \text{space} \\ \text{time} \end{array} \right.$

etc.

* However, fully developed turbulence tends to restore symmetry, except near boundaries, on small scale.

b.c. \leftrightarrow boundary conditions

i.e. if $\delta v(r, l) = v(r+l) - v(r)$
 \Rightarrow

$$\delta v(r+l) = \delta v(r)$$

similarly: isotropy, parity ...

(Facilitates scaling approach)

H2 For $Re \rightarrow \infty$ turbulence, at small scales and away from boundaries, the flow is self-similar at small scales

i.e. possesses a unique scaling exponent h s/t

$$\delta v(r, \lambda l) \rightarrow \lambda^h \delta v(r, l)$$

(\rightarrow addresses 2/3 Law)

H3 With assumptions similar to H1, the turbulent flow has a finite, nonvanishing mean rate of dissipation ϵ per unit mass.

$Re \rightarrow \infty \Rightarrow r \rightarrow 0$ with $v_0 = v_{rms}$ fixed

$$\epsilon = v_0^3 / l_0$$

Alternative (not necessary): Kolmogorov's 'Second' Universality Assumption: In the limit of infinite Reynolds number, all the small-scale statistical properties are uniquely and universally determined by the scale l and the mean energy dissipation rate ϵ .

(First: $\frac{4\epsilon l}{5} = \langle u^3 \rangle$)

i.e. Implications:

$$-\langle \partial v(\ell)^2 \rangle = S_2 \quad ?$$

$$S_2 \sim L^2/T^2, \text{ dimensionally}$$

$$\text{Now } \epsilon \sim L^2/T^3$$

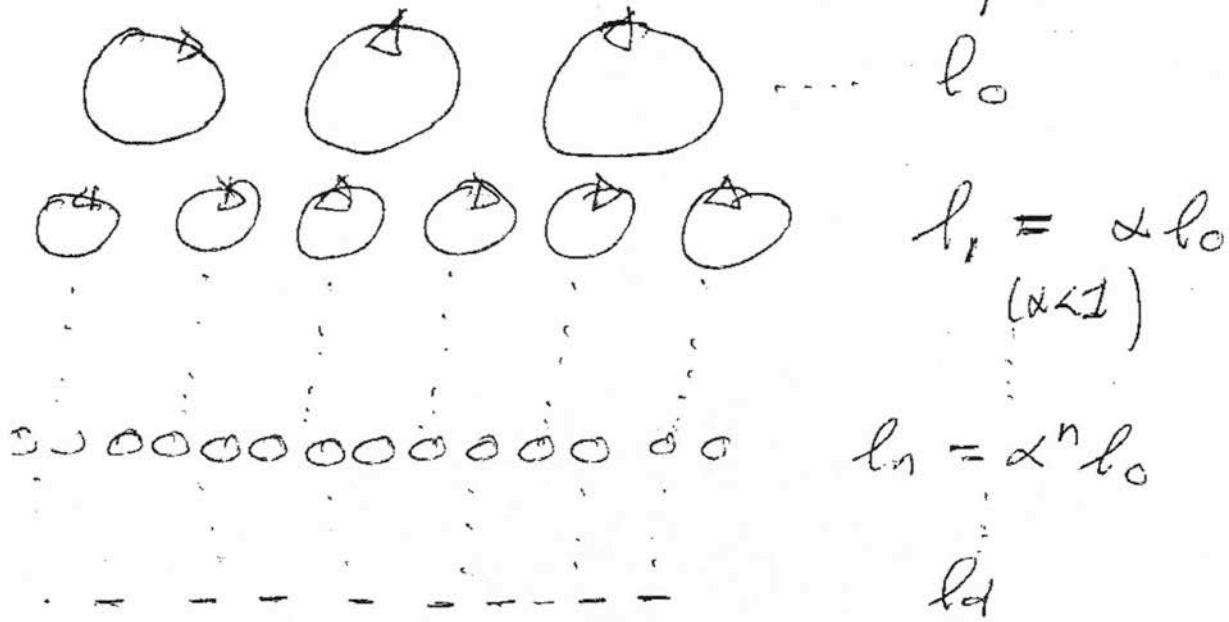
$$\Rightarrow \langle \partial v(\ell)^2 \rangle \sim \epsilon^{2/3} \ell^{2/3} \Rightarrow \text{recovers } 2/3 \text{ Law.}$$

also, implies $h = 1/3 \Rightarrow$ scaling exponent, etc.

H1, H2, H3 (2nd Universality Assumption) \Rightarrow KH phenomenology.

K41 Phenomenology

Picture: (Richardson) Cascade / Eddy Mitosis



Key Idea: ^① Flux of energy in 'scale space',
 from l_0 (integral scale) to l_d ,
 (dissipation scale)

- ② → energy flux is self-similar
- ③ symmetry restoration.

Flux \rightarrow ^④ energy dissipation → finite limit as $n \rightarrow \infty$
 (i.e. endpoint re-adjustment)

self-similarity \rightarrow 2/3 Law

$$S_2 = C (l/l_0)^{2/3}$$

$l_0 \rightarrow \alpha l_0$, $C \rightarrow C \alpha^2$
 etc.

Ingredients in K41 Phenomenology:

→ l : scale parameter : eddy scale

→ $v(l)$: $\tilde{v}(l) \sim \langle \delta v_{ii}(l)^2 \rangle^{1/2}$

↓
eddy
velocity

$$\delta v_{ii} \sim \left(\underline{v}(l+\underline{l}) - \underline{v}(l) \right) \cdot \frac{\underline{l}}{l}$$

≡ longitudinal velocity increment

→ v_0 : rms velocity fluctuation
(large scale dominates)

$$v(l_0) \sim v_0$$

→ $\tau(l)$: eddy lifetime / turn-over rate
↓
characteristic rate of transfer thru
scale l .

self-similarity : energy thru-put rate is
scale l energy scale invariant

⇒

$$\epsilon = \frac{v(l)^2}{\tau(l)}$$

↓
dissipation
rate

energy balance / thru-put
eqn.

↳ scale l
life-time

now, $\tau(l)$?

compare $\tau(l)$ with $\tau_{2D}(l)$

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$\tau(l) \rightarrow$ 'lifetime' of structure of scale l
 \rightarrow i.e. time for structure to be distorted out of existence

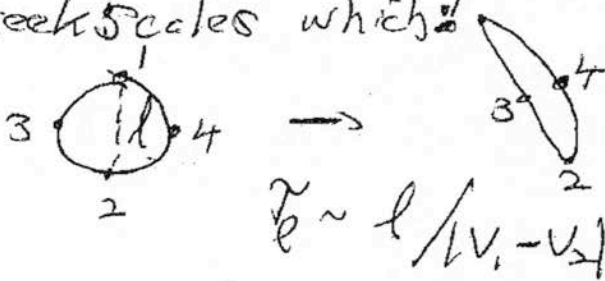
scales $l' \gg l$:

\rightarrow advect eddy \rightarrow apply Galilean boost, but don't affect life-time.
 irrelevant? \rightarrow symmetry under random Galilean transformations
 \rightarrow would also violate symmetry restoration.

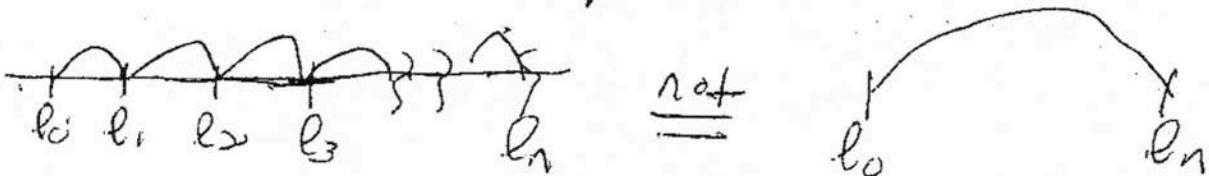
scales $l \ll l'$:

\rightarrow irrelevant as very little energy/shear in such eddies/scales

seek scales which



$\rightarrow \tau(l) \sim \frac{l}{\sigma(l)}$: cascade local in scale space.



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$$\epsilon = \frac{v(\ell)^3}{\lambda}$$

$$\Rightarrow v(\ell) \sim (\epsilon \ell)^{1/3} \quad ; \quad \text{K41 scaling relation}$$

$$\boxed{v(\ell)^3 \sim \epsilon^{2/3} \ell^{2/3}}$$

- verifies $2/3$ Law

- for spectrum:

$$\text{if } E(k) = \dots \quad |v(k)|^2$$

$$\text{s/t } E = \int dk E(k)$$

{ i.e. absorbs density of states

$$\text{then } v(\ell) = \int_{k_{\ell}^{n-1}}^{k_{\ell}^n} dk E(k)$$

$$v(\ell)^3 \sim \epsilon^{2/3} \ell^{2/3} = \epsilon^{2/3} k_{\ell}^{-2/3}$$

$$\Rightarrow \boxed{E(k) = \epsilon^{2/3} k^{-5/3}} \quad ; \quad \text{Kolmogorov Spectrum}$$

at l_0 :

$$v_0 \sim \epsilon^{1/3} l_0 \Rightarrow \frac{v_0^3}{l_0} = \epsilon$$

For dissipation scale:

l_d occurs in l -space when cascade terminated
 over viscosity asserts itself $\rightarrow Re(l) \rightarrow 1$

$$1/Re(l) \sim 1/Re = \nu/l^2$$

$$\Rightarrow \epsilon^{1/3} l^{-2/3} = \frac{\nu}{l^2}$$

$$l^{4/3} = \nu/\epsilon^{1/3} \Rightarrow$$

$$l_d = \nu^{3/4} / \epsilon^{1/4}$$

$$l_d \equiv \lambda, \text{ in Frisch}$$

Recall: $\epsilon = \nu \langle (\nabla v)^2 \rangle$

$\Rightarrow \nu \rightarrow 0 \Rightarrow \langle (\nabla v)^2 \rangle$ divergent

$$\langle (\nabla v)^2 \rangle = \int_{k_0}^{k_d} dk k^2 \epsilon^{2/3} k^{-5/3}$$

$$= \int_{k_0}^{k_d} dk k^{1/3} \epsilon^{2/3}$$

$$= k_d^{4/3} \epsilon^{2/3}$$

$$= \frac{\epsilon^{1/3}}{\nu} \epsilon^{2/3} = \epsilon/\nu$$

\downarrow
 $\langle (\nabla v)^2 \rangle$ divergent
 $\nu \rightarrow 0$

Counting Degrees of Freedom

How big is the inertial range?

$$\begin{aligned} \frac{\Lambda}{l_d} &\sim \frac{l_0}{l_d} \sim \frac{l_0}{(\nu^3/\epsilon)^{1/4}} \\ \# \text{ ed's} &\sim \frac{l_0 (\nu^3/l_0)^{1/4}}{\nu^{3/4}} \sim \left(\frac{\nu l_0}{\nu}\right)^{3/4} \\ &\sim Re^{3/4} \end{aligned}$$

∴ number of degrees of freedom for 3D turbulence is;

$$N \sim Re^{9/4} \quad ; \quad \begin{array}{l} \text{would be (minimum)} \\ \text{\# grid points to resolve} \\ \text{range of scales in numerical} \\ \text{simulation} \end{array}$$

Now, i.e. atmospheric boundary layer:

$$l_0 \sim 1 \text{ km}$$

$$l_d \sim 1 \text{ mm}$$

$$n \sim 10^6 \Rightarrow \left\{ \begin{array}{l} N \sim 10^{18} \\ Re \sim 10^8 - 10^9 \end{array} \right. \quad \begin{array}{l} | \\ 0 \end{array}$$

⇒ subgrid scale modelling ...

B. : Sometimes able to exploit reduced degrees of freedom models, i.e. when some class of scales slaved to others.

Exercises:

→ Consider passive scalar, with concentration C :

$$\frac{\partial C}{\partial t} + \underline{v} \cdot \underline{\nabla} C - \kappa \nabla^2 C = \hat{f}_C$$

C dissipation rate in $\kappa \nabla^2 C \equiv \alpha$

i.e. $\alpha = \overline{C_0^2} \frac{v_0}{l_0}$

- ⇒ a) Calculate $\kappa \nabla^2 C$ spectrum for C ,
 Discuss
 b) What if $\mu \ll \nu$?
 \gg

→ Consider incompressible turbulence with $M \equiv \frac{v_0}{c_s} \ll 1$.

Show: $\frac{l_d}{l_{\text{max}}} \sim M^{-1} Re^{1/4}$

⇒ validity of continuum hydrodynamics gets better at high Re .

Particle Separation / Richardson Law

Consider 2 particles (test) in K41 turbulence.
Rate of separation?



- larger eddys advect both
- smaller eddys do @ nothing

⇒ divergence controlled by eddys of scale $l \sim |x_1 - x_2|$.

∴ if $\lambda \equiv |x_1 - x_2|$

$$\Rightarrow \frac{d\lambda}{dt} = v(\lambda) = \epsilon^{1/3} \lambda^{1/3}$$

$$\lambda^{2/3} = \epsilon^{1/3} t$$

$$\therefore \boxed{\lambda \sim \epsilon^{1/2} t^{3/2}}$$

Richardson's 3/2 Law

N.B.: Non-diffusive!

$$\lambda^2 \sim \epsilon t^3 \Rightarrow \boxed{\tau_{sep.} \sim \lambda^{2/3} / \epsilon^{1/3}}$$

N.B.:

→ process is self-accelerating ⇒ large eddys move faster

non-diffusive.

→ [Momentum] Flux Driven
Turbulence

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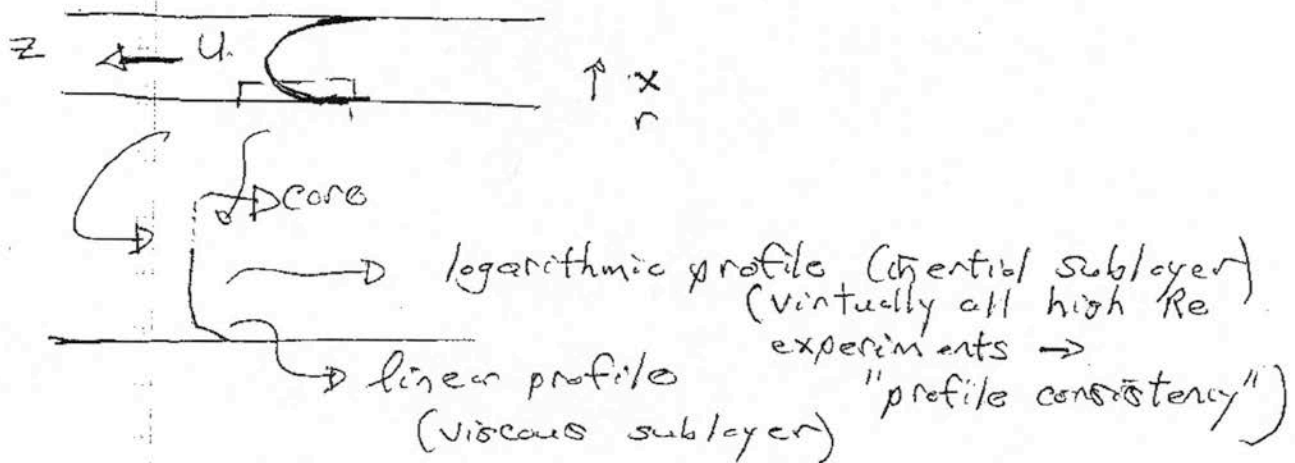
↳ Turbulent Pipe Flow

(cf. Landau, Lifshitz "Fluid Mechanics")

Full flow → homogeneous flow in a periodic box
→ cascade in scale space (Kolmogorov)

Now → inhomogeneous flow in a pipe
→ momentum transport in a turbulent boundary layer (Prandtl)

Consider turbulent pipe flow:



Common features of pipe flow:

- linear → logarithmic $U(x)$ profile
- logarithmic profile persists over a broad range of Re

$$(Re = 2Ua/\nu)$$

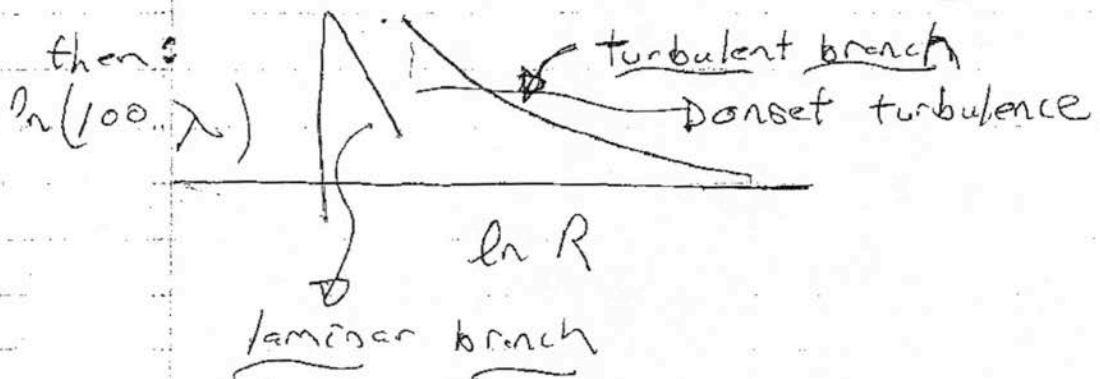
• logarithmic profile "universal" (Prandtl "Law of the Wall")

- resistance ^{increases} with increasing Re ,
 dis continuously \rightarrow pressure drop/length

$$\lambda = 2a \Delta p / l$$

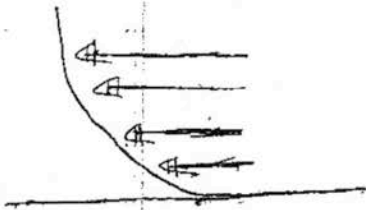
$$\frac{1}{2} \rho U^2$$

\hookrightarrow mean flow energy



- turbulent resistance curve universal.

• What is going on?



no slip boundary condition
 $u = u(x) \rightarrow 0$
 $x \rightarrow 0$

$\therefore u = u(x) \Rightarrow$ { momentum flux to wall }

→ momentum flux to wall \Rightarrow stress on the wall

→ wall stress must balance pressure drop, for steady flow

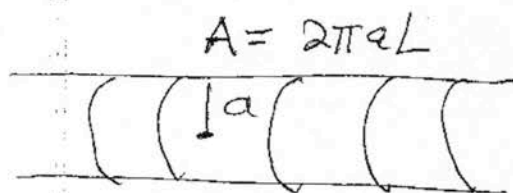
so wall stress $\propto U_*^2$
 $U_* \equiv$ friction velocity

i.e.

$$\frac{\rho U_*^2}{F \sim \rho U_*^2} = -\frac{\partial v}{\partial r} \sim \frac{\Delta p}{l}$$

$$\rho U_*^2 2\pi a l \sim \Delta p \pi a^2$$

$$\rho U_*^2 2\pi a l = \Delta p \pi a^2$$



Δ l

Δ Δp

δ
pressure drop

Force on wall \approx

$$\rho U_*^2 A_{\text{wall}}$$

(Pressure Drop) A_{flow}

$=$ Force on Fluid

friction force $\Rightarrow \rho U_*^2 (2\pi a l) = (\Delta p) \pi a^2$

$$U_* = \left[\frac{(\Delta p / 2\rho) (a)}{2l} \right]^{1/2}$$

Friction Velocity

$U_* \equiv$ friction velocity
 \equiv "typical" velocity of turbulence in turbulent pipe

Deriving the inertial sublayer profile:

i) dimensional reasoning

in pipe flow inertial sublayer, have

3 dimensional parameters ρ , τ_w , x

$\left. \begin{array}{l} \rho \\ \tau_w \end{array} \right\}$ density wall stress
 U_*

\hookrightarrow distance from wall

Key Point: ~~Assumption~~
 at scale invariance

on scale $l_{vs} = \frac{y}{U_*} < x < a$

\rightarrow universality of logarithmic profile motivated scale invariance assumption

now, seek velocity gradient du/dx ,

$\frac{du}{dx} : U_*, x, \rho$

so simplest form for dU/dx is:

$$\frac{dU}{dx} = \frac{U_*}{x}$$

$$\Rightarrow \left\{ \begin{aligned} U &= \frac{U_*}{K} \ln(x/x_0) \\ &= \frac{U_*}{K} \ln x + \text{const.} \end{aligned} \right.$$

→ logarithmic profile (consequence of scale invariance in pipe flow)

→ $K \approx 4$ universal constant → von-Karman constant

→ $x_0 \leftrightarrow$ width of viscous sublayer $\sim \nu/U_*$

(ii) Physical Reasoning

stationary flow \Rightarrow

momentum flux to wall = pressure drop

$$\langle \tilde{v}_x \tilde{v}_z \rangle = U_x^2$$

↓
Reynolds stress

$$\rho \langle \tilde{v}_x \tilde{v}_z \rangle = \tau_p$$

↳ momentum flux

$$\tau_p / \rho = U_x^2$$

Now, to calculate $\langle \tilde{v}_x \tilde{v}_z \rangle$:

→ take velocity fluctuation as generated by mixing of $U(x)$, so

$$\Rightarrow v_z \sim l \frac{\partial U}{\partial x}$$

↓
"mixing length"

analogous to Chapman-Enskog expansion, i.e.

$$l \Leftrightarrow l_{\text{mix}}$$

$$U_x \Leftrightarrow U_{\text{th}}$$

here, scale invariance ~~is~~ $l \sim x$

mixing length set by
distance from wall

$$\begin{aligned} \text{so } \langle \overline{v_x v_x} \rangle &= \langle v_x l \rangle \frac{\partial U}{\partial x} \\ &\approx U_* x \frac{\partial U}{\partial x} \end{aligned}$$

$\nu_T = U_* x \rightarrow$ "eddy viscosity"
"turbulent viscosity" \rightarrow key concept.

\Rightarrow rate of turbulent transport
of momentum

then momentum balance \Rightarrow

$$U_* x \frac{\partial U}{\partial x} = U_*^2$$

$$\Rightarrow U = \frac{U_*}{K} \ln(x/x_0) \rightarrow \text{Logarithmic Profile}$$

\rightarrow Law of the Wall

Some comments:

→ as in k41, clear phenomenology critical to guiding the approximations → scale invariance

⇒ "Mixing length theory always works... provided you know the mixing length..."
- P. D.

⇒ why a single value of velocity, i.e. U_* ?

Consistent with mixing length hypothesis, velocity fluctuations generated by mixing of mean flow gradient, i.e.

$$\Rightarrow \tilde{v} \sim l \frac{\partial U}{\partial x} \sim x \frac{\partial U}{\partial x}$$

$$\sim \cancel{U_*} \frac{\cancel{U_*}}{\cancel{x}}$$

absence of preferred scale.

consistent. ⇒ Assumption consistent with:

- logarithmic profile
- scale invariance.

→ viscous sublayer / cut-off of inertial layer?

∴ when: $\nu_T < \nu$

{ molecular viscosity
dominates mixing

$$\Rightarrow u_* x \lesssim \nu$$

$$x \lesssim \nu / u_* \equiv x_0$$

{
viscous sublayer
scale.

In viscous sublayer, flow linear:

$$\nu \frac{\partial u}{\partial x} = u_*^2$$

$$\therefore u = \frac{u_*^2}{\nu} x$$

⇒ note effect of turbulence is to:

- flatten profile - { higher transport at fixed
wall stress
- reduce central velocity
- limit Q (quality factor)

- matching, far const:

$$x_0 = \nu / U_* \quad \text{so}$$

$$U = \frac{U_*}{K} \ln \left(\frac{U_* y}{\nu} \right)$$

Note: Flow in viscous sublayer is turbulent, but mixing there affected by dissipation range scales \Rightarrow linear profile

Now - turbulent dissipation ρ .

Consider NSE:

$$\begin{aligned} \frac{\partial \hat{U}}{\partial t} + \hat{U} \cdot \nabla \hat{U} + \langle \hat{U} \rangle \frac{\partial \hat{U}}{\partial z} + \hat{U}_x \frac{\partial \langle \hat{U}_z \rangle}{\partial x} \\ = -\nabla \hat{p} + \nu \nabla^2 \hat{U} \end{aligned}$$

\hat{U} and avg \Rightarrow

$$\frac{\partial \langle \hat{U}^2 \rangle}{\partial t} + \langle \hat{U} \cdot \hat{U} \cdot \nabla \hat{U} \rangle + \langle \hat{U}_z \rangle \langle \hat{U} \cdot \frac{\partial \hat{U}}{\partial z} \rangle$$

$$+ \langle \hat{U}_x \hat{U}_z \rangle \frac{\partial \langle \hat{U}_z \rangle}{\partial x} = - \langle \hat{U} \cdot \nabla \hat{p} \rangle - \nu \langle \nabla^2 \hat{U}^2 \rangle$$

i. b. p

input \rightarrow mean flow mixing 276

obviously: $\nu \langle (\nabla \cdot \vec{v})^2 \rangle = \nu_T \left(\frac{\partial U}{\partial x} \right)^2$

small scale
dissipation

and

$$\begin{aligned} E &= (U_T X) \left(\frac{U_T}{X} \right)^2 && \text{(ignoring } R) \\ &= \frac{U_T^3}{X} \end{aligned}$$

\rightarrow sets dissipation rate.

i.e. $E = \frac{V_0^3}{l}$ $V_0 \leftrightarrow U_T$
 $l \leftrightarrow X$

$\rightarrow E$ finite as $\nu \rightarrow 0$ (i.e. viscous sublayer gradient diverges then)

Additional references:

- S.B. Pope, "Turbulent Flows"
- H. Tennekes and J. Lumley, "A First Course in Turbulence"

For net energy budget:

$$\partial_t \mathcal{E} = - \underbrace{\langle \tilde{u}_x \tilde{v}_z \rangle}_{\substack{\downarrow \\ \text{input to fluctuations} \\ \text{by relaxation of} \\ \text{mean shear flow} \\ \text{(Reynolds work)}}} \frac{\partial \langle v_z \rangle}{\partial x} - \nu \underbrace{\langle (\tilde{u}^2)^2 \rangle}_{\substack{\downarrow \\ \text{dissipation} \\ \text{of fluctuations} \\ \text{energy by viscosity}}}$$

∴ can define:

$$\mathcal{E} = \underbrace{\langle \tilde{u}_x \tilde{v}_z \rangle}_{\substack{\downarrow \\ \text{turbulent} \\ \text{dissipation} \\ \text{rate}}} \frac{\partial U}{\partial x}$$

and using mixing length theory:

$$\langle \tilde{u}_x \tilde{v}_z \rangle = u_* x \frac{\partial U}{\partial x}$$

$$\Rightarrow \mathcal{E} = (u_* x) \left(\frac{\partial U}{\partial x} \right)^2 = \gamma_T \underbrace{\left(\frac{\partial U}{\partial x} \right)^2}_{\substack{\downarrow \\ \text{rate of "heating" by} \\ \text{turbulent relaxation} \\ \text{of mean flow.}}}$$



→ Now, interesting to tabulate comparison between Pipe Flow and K41 Problem

Pipe Flow (Prandtl)	K41 (Kolmogorov)
<u>scales</u> : $a, x, \nu/u_*$ <u>invariance</u> : $x \rightarrow \text{real space}$	l_0, l_n, l_d $l \rightarrow \text{scale space}$
inertial sublayer viscous sublayer	inertial range dissipation range
<u>balance</u> : $u_*^2 = \nu_T \frac{\partial u}{\partial x}$	$\epsilon = \frac{v(l)^3}{T(l)}$
<u>dynamics</u> : eddy viscosity $\nu_T = u_* x$	turn-over rate $1/T(l) = \frac{v(l)}{l}$
<u>result</u> : $u = \frac{u_*}{R} f(x)$	$v(l) = \epsilon^{1/3} l^{1/3}$
<u>universal profile</u>	<u>universal spectral scaling</u>
<u>dissipation</u> : $\nu = \nu_T$ $x_0 = \nu/u_*$	$v(l)/l = \nu/l^2$ $l_d = \nu^{3/4} / \epsilon^{1/4}$

→ Practical Issues

Resistance Law \leftrightarrow Pipe Flows.

have: $\frac{v}{U_*} < \chi < a$
 \downarrow
 radius

can push to $\chi \approx a$, with logarithmic accuracy.

$$U \approx \frac{U_*}{R} \ln \left(\frac{U_* a}{v} \right)$$

but

$$U_* = U_* = \left(\frac{a \Delta P}{\ell 2\rho} \right)^{1/2}$$

\Rightarrow can re-write:

$$U = \left(\frac{a \Delta P}{2\rho \ell R^2} \right)^{1/2} \ln \left(a \left(\frac{a \Delta P}{2\rho \ell} \right)^{1/2} / v \right)$$

Convenient to define:

$$\chi = \frac{2a \Delta P / \ell}{\frac{1}{2} \rho U^2}$$

\hookrightarrow flow KE

\rightarrow friction factor / resistance coefficient

⇒ taking $Re = 2aU/\nu$

can re-write friction law as:


$$\left\{ \begin{array}{l} 1/\sqrt{\lambda} = .88 \ln(Re\sqrt{\lambda}) - .80 \\ Re = 2aU/\nu \end{array} \right. \quad \begin{array}{l} \downarrow \\ \text{phenom.} \end{array}$$

$$\lambda = \frac{2a \Delta p / \ell}{\frac{1}{2} \rho U^2}$$

→ good fit to pipe flow data.

Problems:

1a.) A very strong explosion, with energy released ΔE , creates a spheroidal blast wave in an atmosphere of pressure P_0 , density ρ . Use dimensional analysis to derive the radius of the blast front as a function of time, i.e. $r(t)$? When does this scaling fail?

b.)  A hot surface produces thermal convection above it. Assuming the convection is turbulent, use scaling arguments to calculate the temperature profile above the plate, assuming the hot plate drives a surface heat flux Q . (See Chapter 5; Landau).

Wave Kinetics

2.

Why Wave "kinetics"?

" A wave is never found alone, but is mingled with as many other waves as there are uneven places in the object where the said wave is produced. At one and the same time there will be moving over the greatest wave of a sea innumerable other waves proceeding in different directions "

- Leonardo da Vinci
Codice Atlantico, c.1500.

From Asian art...

The great wave at Kanagawa Hokusai

