

→ Reduced Models

- Reduced MHD I
- Reduced MHD II
- Further applications - DW's.

For Posting:

Reduced Models

Reduced MHD → Simplifying the representation  
 → strong magnetization - anisotropy.  
 $\delta B_{||} \rightarrow 0; \delta B_{\perp} = \nabla A_{||} \times \hat{z}$   
 $\delta v_{\perp} = \nabla \phi \times \hat{z}$  It

Aside

→  $\gamma > \gamma_{MS}$

→ Reduced MHD → Reduced Representation  
 for strong @ straight  $B_0$   
 = eliminates fast mode

Note: ① full MHD : 3  $\underline{v}$  components  
 2  $\underline{B}$  " " ( $\nabla \cdot \underline{B} = 0$ )  
 $\rho, p$

⇒ 7 components

② if  $\nabla \cdot \underline{v} = 0$  ⇒ 4 components  
 ( $\rho = \text{const}$ ,  $p$  from  $\nabla \cdot \underline{v} = 0$ )

③ strongly magnetized system ⇒ Reduced MHD  
 ⇒ scalar equations for  $\phi, \psi$  (2 scalar fields)

Now:

- assume strong  $B_z$  (strong magnetization → gyrokinetics)

"strong" ⇔  $\rho v^2 \sim \rho \ll B_z^2 / 8\pi$  → later

so motion strongly anisotropic, and small scales generated in  $\perp$  direction only, as strong  $B_z$  inhibits line bending, (energy-to-perturb strong, high energy density field).

⇒ order :  $B_z \sim v_{\perp} \sim 1$   
 $B_{\parallel} \sim \alpha_z \sim O(\epsilon)$

Take  $\rho \sim 1$ , as  $\nabla \cdot \underline{v} = 0$  enforced by strong  $B_z$ .

$v_{\perp}^2 \sim \rho \sim B_{\perp}^2$  (i.e. equipartition of energy (springiness))

$\Rightarrow v_{\perp} \sim \epsilon, \rho \sim \epsilon^2, \partial_t \sim v_{\perp} \cdot \nabla_{\perp} \sim \epsilon$

and pressure balance ( $\nabla \cdot \underline{v} = 0$  / ~~in~~ incompressibility)

$\delta(B_z^2) \sim 2B_z \delta B_z \sim \rho$

$\Rightarrow \delta B_z \sim \epsilon^2$

(e2brn)  $\omega \ll k(\epsilon^2 + v_{\perp}^2)^{1/2}$   
[idea is to order out the first mode]

to lowest order  $\Rightarrow B_z = \text{const.}$

Now then:

$(\nabla \cdot \underline{B} = 0)$

$\underline{B} = \underline{z} \times \nabla \psi + B_z \underline{z}$   
 $= \nabla A_{\parallel} \times \underline{z} + B_z \underline{z}$

B rep. by single scalar potential

$\psi = -A_{\parallel}$

$\nabla \cdot \underline{B} = \partial_z B_z \approx \epsilon^3 \rightarrow 0$

parallel comp. of vector pot.

Similarly;

$\partial_z \rho \sim o(\epsilon^3)$   
 $\int_{\perp} B_{\perp} \sim \epsilon^3$

$\Rightarrow v_z \ll v_{\perp}$   
neglect  $v_z$ .

Now, 
$$\underline{E} = -\frac{1}{c} \frac{\partial \underline{A}}{\partial t} - \underline{\nabla} \phi = -\frac{\underline{v} \times \underline{B}}{c}$$

$$\Rightarrow +\frac{1}{c} \frac{\partial \underline{A}}{\partial t} = \frac{\underline{v} \times \underline{B}}{c} - \underline{\nabla} \phi \quad (*)$$

$$B_z = (\underline{\nabla} \times \underline{A}_\perp) \cdot \underline{z}$$

so  $\partial_t A_\perp \sim E^3$  (calc  $\partial_z B_z$ )

$\nabla_\perp \phi \approx \left( \frac{\underline{v} \times \underline{B}}{c} \right)_\perp$ , in  $(*)$   $\underline{v}_\perp \approx \nabla \phi$   
 Inductive piece, negligible.

$$\Rightarrow \underline{v}_\perp = \frac{c \underline{z} \times \underline{\nabla} \phi}{B_z}$$

$\perp$  velocity  
 $\rightarrow$  motion  $\perp$  is  $\underline{E} \times \underline{B}$

Now, taking parallel component of  $(*)$ .  
 (units!)

$$\Rightarrow \frac{\partial \psi}{\partial t} + \underline{v} \cdot \underline{\nabla} \psi = \frac{B_z}{z} \partial_z \phi$$

so have (vector potential) (flux) equation:

$\underline{v} \cdot \underline{\nabla} \psi$  from

$$\frac{\partial \psi}{\partial t} + \underline{v} \cdot \underline{\nabla} \psi = B_z \partial_z \phi$$

$\underline{B} \cdot \underline{\nabla} \phi \rightarrow$

$B_z \partial_z \phi + \nabla \psi \times \underline{z} \cdot \underline{\nabla} \phi$

equation of evolution of magnetic flux.



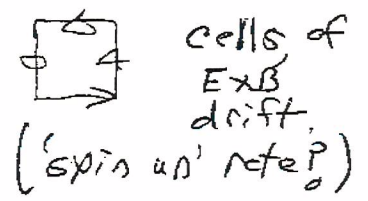
$$= B_z \underline{\hat{z}} + \underline{\hat{z}} \times \underline{\nabla} \psi$$

or, alternatively,  $\frac{\partial \psi}{\partial t} - \underline{B} \cdot \underline{\nabla} \phi = 0$  94

Finally, for  $\phi$ , write:

⊥ motion

$$\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \underline{\nabla} \underline{v} = -\frac{\underline{\nabla} \rho}{\rho_0} + \frac{\underline{J} \times \underline{B}}{c}$$



$(\underline{\nabla} \times) \cdot \underline{\hat{z}} \Rightarrow$  vorticity component ( $\parallel \underline{\hat{z}}$ )

Dynamics in  $\perp$  plane, evolution.

$$\frac{\partial}{\partial t} \omega_z + \underline{v}_\perp \cdot \underline{\nabla} \omega_z = -\frac{\underline{\nabla} \times \underline{\nabla} \rho}{\rho_0} + \underline{\hat{z}} \cdot \underline{\nabla} \times \left( \frac{\underline{J} \times \underline{B}}{c} \right)$$

$$= \underline{B} \cdot \underline{\nabla} J_z - \frac{\underline{J} \cdot \underline{\nabla} B_z}{c} \quad \text{for } B_z \sim \epsilon^3$$
$$\approx \underline{B} \cdot \underline{\nabla} J_z$$

$$\frac{\partial}{\partial t} \omega_z + \underline{v} \cdot \underline{\nabla} \omega_z = \underline{B} \cdot \underline{\nabla} J_z$$

but:

$$\omega_z = \underline{\hat{z}} \cdot \underline{\nabla} \times \underline{v} = \nabla^2 \phi$$

$$J_z = \underline{\hat{z}} \cdot (\underline{\nabla} \times \underline{B}) \frac{c}{4\pi} = \nabla^2 \psi$$

So → Waves → time scales → Reduced MHD

6.

75.

so finally have:

$$\frac{\partial}{\partial t} \nabla^2 \phi + \underline{v} \cdot \underline{\nabla} \nabla^2 \phi = B_z \frac{\partial}{\partial z} \nabla^2 \psi + \underline{\tilde{B}} \cdot \underline{\nabla} \nabla^2 \psi$$

Finally have reduced MHD equation:

$$B = B_0 \hat{e}_z$$

$$\frac{\partial \psi}{\partial t} + \underline{v} \cdot \underline{\nabla} \psi = B_z \partial_z \phi + \eta \nabla^2 \psi$$
$$\frac{\partial}{\partial t} \nabla^2 \phi + \underline{v} \cdot \underline{\nabla} \nabla^2 \phi - \nu \nabla^2 \nabla^2 \phi = \underline{\tilde{B}} \cdot \underline{\nabla} \nabla^2 \psi + B_z \frac{\partial}{\partial z} \nabla^2 \psi$$

$$E_{||} = \eta J_{||}$$

vorticity  
in  
plane  $\perp \hat{e}_z$

- note have reduced MHD to 2 scalar evolution equations

- does this look familiar?

- 2D dynamics + shear Alfvén wave.

- nonlinearity → 2D dynamics.

even stronger

$B_z \partial_z \rightarrow 0$  75.  
 $\partial_z \psi = 0$   
 $\partial_z \phi = 0$  p. 0. +  $\alpha v z$ .

- for 2D MHD:

$$\left[ \begin{aligned} \frac{\partial \nabla^2 \phi}{\partial t} + \underline{v} \cdot \underline{\nabla} \nabla^2 \phi &= \underline{B} \cdot \underline{\nabla} \nabla^2 \psi + \nu \nabla^2 \nabla^2 \phi \\ \frac{\partial \psi}{\partial t} + \underline{v} \cdot \underline{\nabla} \psi &= \eta \nabla^2 \psi \end{aligned} \right]$$

00 Conservation Laws, etc. (HW)

$\frac{d}{dt} E = 0$  (to  $\eta, \nu$ ),  $E = \int d^3x \left[ \frac{(\nabla \phi)^2}{2} + \frac{(\nabla \psi)^2}{2} \right]$

②  $H = \underline{A} \cdot \underline{B} \cong B_z \psi$   $\int d^2x A^2 = MSMP$   
const. (2D)

$\Rightarrow H = \int d^3x B_z \psi$ ,  $\frac{dH}{dt} = 0$ , to  $O(\eta)$

Ohm's Law (flux advection) is simple statement

? of helicity conservation. form  $\Gamma \psi$  s/t  $\begin{cases} H \text{ conserved} \\ EM \text{ dissipated} \end{cases}$

③  $K = \int d^3x \underline{v} \cdot \underline{B} = \int d^3x (\nabla \phi \cdot \nabla \psi)$

also conserved, to dissipation.

Alfvén wave  $\mu$ -perturbation cube key.

# Reduced MHD - Brief

See Strauss, '76 for full details  
(P. 205)

- the points - strong  $\langle B \rangle$ ,  $\odot$  straight
- low frequency ( $\omega < \omega_{MS}$ )
- $\langle B \rangle \odot$  unperturbed
- $\nabla \cdot \underline{V} = 0$

$\nabla \cdot \underline{V} = 0 \Rightarrow$  2 component  $\underline{V}$

$\underline{V} \cdot \underline{B} = 0 \Rightarrow$  2 component  $\underline{B}$

$\underline{E} + \frac{\underline{V} \times \underline{B}}{c} = 0 \Rightarrow \underline{V}_\perp = + \frac{c}{B} \underline{E}_\perp \times \underline{z}^1$

$\underline{E}_\perp = - \frac{\nabla_\perp \phi}{c} - \frac{d}{dt} \frac{\underline{A}_\perp}{c}$

$\underline{V}_\perp = - \frac{c}{B} \nabla_\perp \phi \times \underline{z}^1$

$\nabla \times \underline{A} = 0$

$\underline{E}_\perp = \nabla A_\parallel \times \underline{z}^1$

$\underline{B}_\perp = \nabla A_\parallel \times \underline{z}^1$



Then,

$$\underline{E} = -\frac{1}{c} \frac{\partial \underline{A}}{\partial t} - \underline{\nabla} \phi = \underline{\mu J}$$

$$E_{||} = -\frac{1}{c} \frac{\partial A_{||}}{\partial t} - \nabla_{||} \phi = \mu J_{||}$$

$$\underline{B} = B_0 \underline{\hat{z}} + \underline{B}_1$$

$\Rightarrow$

$$\frac{-1}{c} \frac{\partial A_{||}}{\partial t} - \frac{(B_0 \underline{\hat{z}} + \underline{B}_1) \cdot \underline{\nabla} \phi}{|B_0 \underline{\hat{z}} + \underline{B}_1|} = \mu J_{||}$$

$$\therefore -\frac{1}{c} \frac{\partial A_{||}}{\partial t} - \partial_z \phi - \underline{B}_1 \cdot \underline{\nabla} \phi = \mu J_{||}$$

and

$$\frac{-1}{c} \frac{\partial A_{||}}{\partial t} - \partial_z \phi - \underline{\nabla} A_{||} \times \underline{\hat{z}} \cdot \underline{\nabla} \phi = \mu J_{||}$$

$$\underline{\nabla} \psi + \underline{v} \cdot \underline{\nabla} \psi = \partial_z \phi + \mu \sigma^2 \psi$$

Reduced Ohm's Law

Now,



strong field  $\phi$

+

$v_{\perp}$  only  $\rightarrow$  set by  $\phi$

so,  $\frac{B_0 \cdot \nabla \times \underline{v}}{4\pi B_0} = \underline{\hat{z}} \cdot \nabla \times \underline{v} \rightarrow$  is the key to dynamics

$$\text{Now, } \rho \left( \frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right) = -\nabla p + \frac{\underline{J} \times \underline{B}}{c}$$

$$\underline{v} \cdot \nabla \underline{v} = \nabla \frac{v^2}{2} - \underline{v} \times \underline{\omega}$$

$$\rho \left( \frac{\partial \underline{v}}{\partial t} \right) = -\nabla \left( p + \rho \frac{v^2}{2} \right) + \rho \underline{v} \times \underline{\omega} + \frac{\underline{J} \times \underline{B}}{c}$$

$\rho \equiv \rho_0$  (incomp/Boussinesq)

$$\frac{\partial \underline{v}}{\partial t} = -\nabla \left( \frac{p}{\rho_0} + \frac{v^2}{2} \right) + \underline{v} \times \underline{\omega} + \frac{\underline{J} \times \underline{B}}{c \rho_0}$$

$$= -\nabla \left( \frac{p}{\rho_0} + \frac{B^2}{8\pi \rho_0} + \frac{v^2}{2} \right) + \underline{v} \times \underline{\omega} + \frac{\underline{B} \cdot \nabla \underline{B}}{4\pi \rho_0}$$

$$= -\nabla \left( \frac{p}{\rho_0} + \frac{B^2}{8\pi \rho_0} + \frac{v^2}{2} \right) + \underline{v} \times \underline{\omega} + \frac{B_0 \partial_z \underline{B}_{\perp}}{4\pi \rho_0} + \underline{B}_{\perp} \cdot \nabla_{\perp} \underline{B}_{\perp}$$

(no  $B_0$   $\frac{\partial \underline{B}_{\perp}}{\partial t}$ )

so  $\nabla \times$

$$\frac{\partial \underline{\omega}}{\partial t} = \underline{\nabla} \times \underline{v} \times \underline{\omega} + \frac{B_0 \partial_z}{4\pi\alpha_0} \underline{\nabla} \times \underline{\tilde{R}}_1 + \frac{\underline{\tilde{R}}_1 \cdot \underline{\nabla}}{4\pi\alpha_0} (\underline{\nabla} \times \underline{\tilde{R}}_1)$$

$$= -\underline{v} \cdot \underline{\nabla} \underline{\omega} + \underline{\omega} \cdot \underline{\nabla} \underline{v} + \frac{B_0 \partial_z}{4\pi\alpha_0} \underline{\nabla} \times \underline{\tilde{R}}_1 + \frac{\underline{\tilde{R}}_1 \cdot \underline{\nabla}}{4\pi\alpha_0} (\underline{\nabla} \times \underline{\tilde{R}}_1)$$

$\hat{z} \cdot () \Rightarrow$

$$\frac{d \omega_z}{dt} = \underline{\omega} \cdot \underline{\nabla} \omega_z + \frac{B_0 \partial_z}{4\pi\alpha_0} \underline{\tilde{J}}_{R1} + \frac{\underline{\nabla} A_1 \cdot \underline{\tilde{R}}_1}{4\pi\alpha_0} \underline{\nabla} \cdot \underline{\tilde{J}}_{R1}$$

$$\omega_z \rightarrow \nabla^2 \phi$$

$$\frac{d \nabla^2 \phi}{dt} = \underline{\omega} \cdot \underline{\nabla} \nabla^2 \phi + \underline{v} \cdot \underline{\nabla} \nabla^2 \phi = \frac{B_0 \partial_z}{4\pi\alpha_0} \underline{\tilde{J}}_z + \frac{\underline{\tilde{R}}_1 \cdot \underline{\nabla}}{4\pi\alpha_0} \underline{\tilde{J}}_z$$

$\rightarrow$  vorticity eqn!



Alternative Approach:

①  $\nabla \cdot (\underline{E}_* = n \underline{J})$

→ as before!

②

$\nabla \rho + \nabla \cdot \underline{J} = 0$ , continuity!

$\rho = (n_i - n_e) e$

and  $\nabla \cdot \underline{J} = 0$

$\nabla \cdot \underline{J} = 0$

→ general!

advective

$\nabla_{\perp} \cdot \underline{J}_{\perp} = -\nabla_{\parallel} J_{\parallel}$

$n_0 m_e \frac{d \underline{v}_0}{dt} = n_0 \underline{E} - \nabla P + n_0 \underline{v}_0 \times \underline{B}_0$

$\sim O(\omega/\Omega)$  expansion low  $\beta$  ( $T_e$ ),  $\Omega$

$\underline{J} = (n_i \underline{v}_E - n_e \underline{v}_E) e + n_e e \underline{v}_{pol}$

Ex current, cancel

polarization current  $\rightarrow$  cons ( $m_e \gg m_e$ )

$\nabla_{\perp} \cdot (n_0 \underline{v}_{pol}) = -\frac{1}{\Omega} \nabla_{\parallel} J_{\parallel}$

$\rightarrow$  vort  $\omega_{ci}$

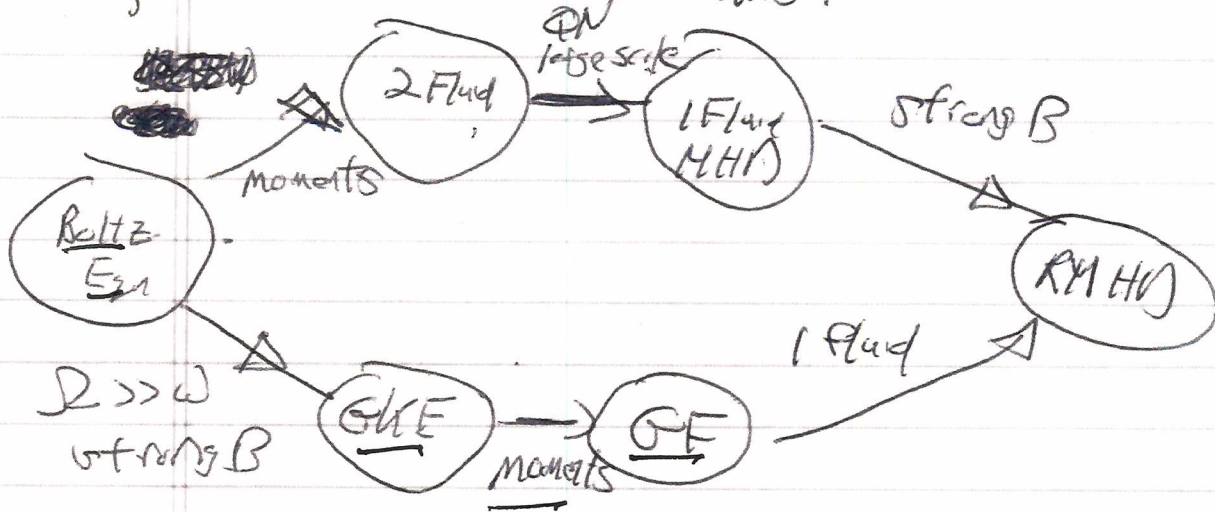
$= -\frac{1}{\Omega} (\partial_z \tilde{J}_{\parallel} + \tilde{B}_z \cdot \nabla_{\perp} \tilde{J}_{\parallel})$



and back to veracity eqn!

⇒ can extend to H-W, H-M, 3 field, ITG....

→ Now, can relate routes to RMHD:



[So can come to RMHD by different orders of strong field and fluid approx.

Now, extensions;

# Outline

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→ A) A Look Back and A Look Around: Basic Ideas of the Drift Wave-Zonal Flow System

*Drift Wave Models*

*Drift - A/Fuer.*

B) A Look Ahead: Current Applications to Selected Problems of Interest

# A) A Look Back and A Look Around

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## Basic Ideas of the Drift Wave – Zonal Flow System

- i) Physics of Zonal Flow Formation
- ii) Shearing Effects on Turbulence Transport
- iii) Closing the Feedback Loops: Predator(s) Meet Prey

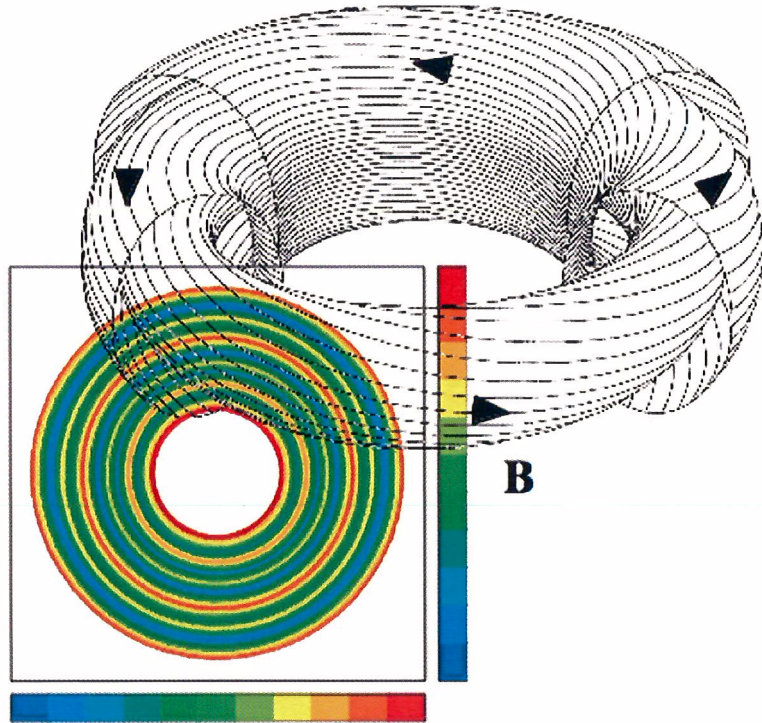
“The difference between an idea and a theory is that the first can generate a call to action and the second cannot.”

— Stanley Fish



# Preamble I

Tokamaks



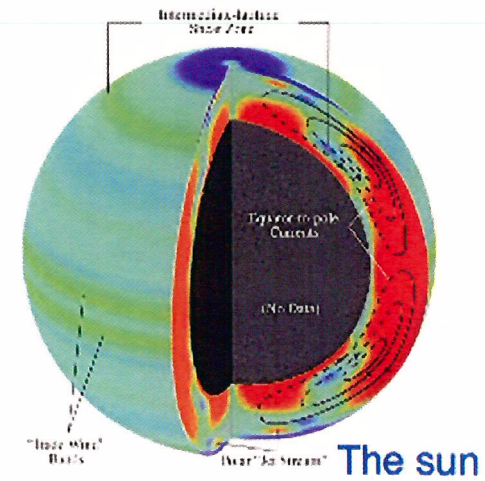
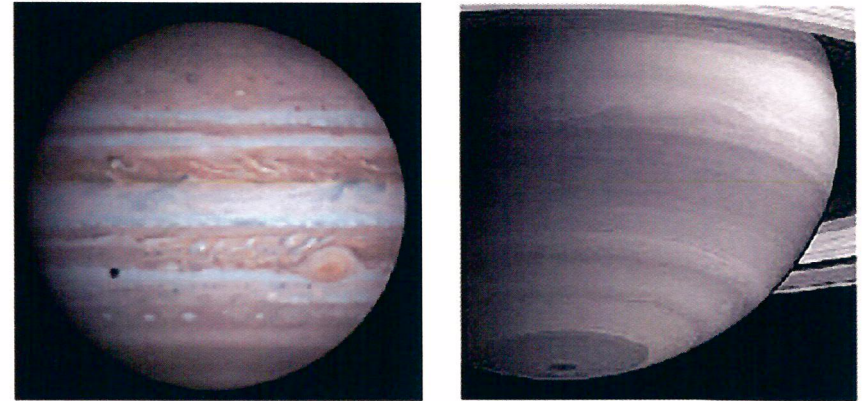
Zonal Flows:

$$m = n = 0$$

finite  $k_r$

potential fluctuations

planets



The sun



# Preamble II

→ Re:Plasma?

→ 2 Simple Models

a.) Hasegawa-Wakatani (collisional drift inst.)

b.) Hasegawa-Mima (DW)

a.) 
$$\mathbf{V} = \frac{c}{B} \hat{z} \times \nabla \phi + \mathbf{V}_{pol}$$

$$\rightarrow m_s$$

$$L > \lambda_D \rightarrow \nabla \cdot \mathbf{J} = 0 \rightarrow \nabla_{\perp} \cdot \mathbf{J}_{\perp} = -\nabla_{\parallel} J_{\parallel}$$

$$J_{\perp} = n |e| V_{pol}^{(i)}$$

$$J_{\parallel} : \eta J_{\parallel} = -\cancel{(1/c) \partial_t A_{\parallel}} - \nabla_{\parallel} \phi + \nabla_{\parallel} p_e$$

linear if conductivity dropped.  
n.b.

- MHD:  $\partial_t A_{\parallel}$  v.s.  $\nabla_{\parallel} \phi$

- DW:  $\nabla_{\parallel} p_e$  v.s.  $\nabla_{\parallel} \phi$

can correct for drift A/BV

e.s.

b.) 
$$dn_e/dt = 0$$

$$\rightarrow \frac{dn_e}{dt} + \frac{\nabla_{\parallel} J_{\parallel}}{-n_0 |e|} = 0$$

$$\rightarrow \left[ \begin{aligned} \frac{\partial F}{\partial t} + v_{\parallel} \frac{\partial F}{\partial x_{\parallel}} - \frac{c}{B} \nabla_{\perp}^2 F \\ - \frac{q}{m} \nabla_{\parallel} \phi \frac{\partial F}{\partial v_{\parallel}} = C(F) \end{aligned} \right]$$

$J_{\parallel} \rightarrow$  electrons.

## Ohm's Law - From DKE

Ohm's law is key to metal zoology.

$\underline{v} \cdot \underline{\nabla} = 0$  is universal, Ohm's Law

Version

DKE: (for electrons)

$$\frac{\partial f}{\partial t} + v_{||} \nabla_{||} f - \frac{e}{B_0} \nabla \phi \times \hat{z} \cdot \nabla f$$

$$- \frac{ke}{m_e} E_{||} \frac{\partial f}{\partial v_{||}} = C(f_e)$$

$$\nabla_{||} = \partial_z + \frac{dB_{||}}{B_0} \cdot \underline{\nabla} \rightarrow \text{nonlinear operator}$$

$$E_{||} = -\frac{1}{c} \frac{\partial A_{||}}{\partial t} - \nabla_{||} \phi \rightarrow \text{nonlinear + induction}$$

$$\text{Ohm's Law: } \int v_{||} f \rightarrow \left. \begin{array}{l} \text{electron} \\ \text{momentum} \\ \text{equation} \end{array} \right\}$$

and  $\int (v_{\perp}^2 + v_{\parallel}^2) \rightarrow P_e$ .

So,  $v_{\parallel}$  moment:

current advection  $\rightarrow$  electron inertia  
 $m_e \left[ \frac{\partial J_{\parallel}}{\partial t} - \frac{c}{B} \nabla \varphi \times \hat{z} \cdot \nabla J_{\parallel} \right]$  usually neglected collisions

$+ \frac{1}{c} \frac{\partial A_{\parallel}}{\partial t} - \sigma_{\parallel} \left[ \frac{1}{T} \nabla \varphi - T \frac{\hat{n}}{n_0} \right] = n J_{\parallel}$

$\nabla_{\parallel} E_{\parallel}$

$\nabla_{\parallel} E_{\parallel}$

$\uparrow$   
 from  $\parallel$  pressure gradient  $(\nabla_{\parallel} P_e)$   
 (can include  $\hat{T}$ )

Point:

- electrostatics  $\rightarrow$  drop  $\partial A_{\parallel} / \partial t$
- MHD-like  $\rightarrow$  drop  $\sigma_{\parallel} P$
- Drift waves  $\rightarrow$  drop induction retain  $\parallel P$ .

MHD

$\nabla_{\parallel} \varphi$  vs  $\nabla_{\parallel} J_{\parallel}, \frac{1}{c} \frac{\partial A_{\parallel}}{\partial t}$

all  $\rightarrow$  drift A flux.

DW

$\nabla_{\parallel} \varphi$  vs  $T \nabla_{\parallel} n$

So H-W

$$D_{||} = \frac{v_{the}^2}{\gamma_e e}$$

$$\vec{\phi} \rightarrow \frac{e\hat{\phi}}{T}$$

$$\hat{n} \rightarrow \hat{n}/n_0$$

$$-D_{||} \phi = -D_{||} \hat{n} T$$

20.

|| diffn vs freq. +  $n \frac{\partial \phi}{\partial t}$

$$\rho_s^2 \frac{d}{dt} \nabla^2 \hat{\phi} = -D_{||} \nabla_{||}^2 (\hat{\phi} - \hat{n}/n_0) + \nu \nabla^2 \nabla^2 \hat{\phi}$$

from  $\nabla_{||} \Sigma_{||}$

$$\frac{d}{dt} n - D_0 \nabla^2 \hat{n} = -D_{||} \nabla_{||}^2 (\hat{\phi} - \hat{n}/n_0)$$

from  $\nabla_{||} \Sigma_{||}$

$$\left[ D_{||} k_{||}^2 / \omega \right]$$

is key parameter

— decouple for  $\underline{z.f.}$

n.b. PV =  $n - \rho_s^2 \nabla^2 \phi$

$$\frac{d}{dt} (PV) = 0$$

inviscid.

akin conserved phase space density,  $\rightarrow$  total density/charge

b.)  $D_{||} k_{||}^2 / \omega \gg 1 \rightarrow \hat{n}/n_0 \sim e\hat{\phi}/T_e \quad (m, n \neq 0)$

$$\left[ \frac{d}{dt} (\phi - \rho_s^2 \nabla^2 \phi) + v_* \partial_y \phi = 0 \right]$$

$\rightarrow$  H-M

derive via continuity eqn.

$$\underline{\nabla} \cdot \underline{v}_i = \underline{\nabla} \cdot \underline{v}_E + \underline{\nabla} \cdot \underline{v}_{\text{par}}$$

$$\hat{n}_i = \frac{ic|\hat{\phi}}{T}$$

n.b.  $PV = \phi - \rho_s^2 \nabla^2 \phi + \ln n_0(x)$

n.b. Zonal Flows:  $\rho_s^2 \frac{d}{dt} \nabla^2 \phi = -\mu \nabla^2 \phi + \nu \nabla^2 \nabla^2 \phi$

$$\nabla_{||} \rightarrow 0$$

decouple.



An **infinity** of models follow:

- MHD: ideal ballooning  
resistive  $\rightarrow$  RBM

$\rightarrow$  + curvature  
 $\rightarrow$  curvature, e.s

- HW +  $A_{\parallel}$ : drift - Alfvén

- HW + curv.: drift - RBM

- HM + curv. + Ti: Fluid ITG

- gyro-fluids

- GK

N.B.: Most Key advances  
appeared in consideration  
of **simplest** possible models

# Lecture Notes of Non-linear Plasma Theory

## Chapter 6

### Hasegawa-Wakatani, Hasegawa-Mima and Quasi-Geostrophic Models

Xiang Fan — *Notes*  
Prof. Patrick H Diamond — *Lecture*

February 28, 2014

## 1 Introduction

Hasegawa-Wakatani model and Hasegawa-Mima model, which will be called H-W model and H-M model for short in the rest of the lecture notes, are useful to describe drift-wave turbulence, and also important for understanding zonal flow. These two models have very similar form to quasi-geostrophic models.

In section 2 and section 3, we will talk in detail about Hasegawa-Wakatani model and Hasegawa-Mima model respectively. Section 4 is some discussion about H-W and H-M models. In section 5, comparison with quasi-geostrophic is shown. In section 6, the relationship between H-W H-M model and MHD will be discussed.

## 2 Hasegawa-Wakatani Model

H-W model is a consistent model of drift wave turbulence, no forcing added by hand. It is a model describing two variables, density  $n$  and electric potential  $\phi$ . It is a simple limit of 2-fluid system. Now we are going to derive H-W equations<sup>1</sup>, some assumptions are made during this process.

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<sup>1</sup>Thanks to D. Strintzi's lecture note "Simple models of plasma turbulence", see [http://www2.ipp.mpg.de/~fsj/PAPERS\\_1/tutorial\\_3.pdf](http://www2.ipp.mpg.de/~fsj/PAPERS_1/tutorial_3.pdf)

Start from ion force balance equation:

$$\frac{d\mathbf{u}}{dt} = -\frac{e}{m}\nabla\phi + \frac{e}{m}\mathbf{u} \times \mathbf{B} - \nabla p_i - \nabla\Pi + \mathbf{F} \quad (1)$$

Now we assume cold ions,  $T_i \ll T_e$ , thus  $\nabla p_i = 0$ . Assume  $\nabla\Pi$  has the form  $-\nabla\Pi = \mu\nabla^2\mathbf{u}$ , where  $\mu$  is the ion viscosity coefficient. Also we have  $\mathbf{F} = 0$ .

Then let's deal with  $\mathbf{u}$ . The 0th order of it is the  $\mathbf{E} \times \mathbf{B}$  drift:

$$\mathbf{u}_0 = \mathbf{u}_E = -\nabla\phi \times \frac{\mathbf{B}}{B_0^2} \quad (2)$$

where  $B_0$  is the homogeneous background magnetic field. Now let  $\mathbf{u} = \mathbf{u}_0 + \mathbf{u}_1$ , and substitute it into the ion force balance equation (1), then we can get the 1st order of  $\mathbf{u}$ :

$$\mathbf{u}_1 = \mathbf{u}_p + \mathbf{u}_{visc} = -\frac{1}{\omega_{ci}B_0} \frac{d\nabla\phi}{dt} - \frac{\mu}{\omega_{ci}B_0} \nabla^2(\nabla\phi) \quad (3)$$

where  $\omega_{ci}$  is the usual  $\omega_{ci} = eB_0/m$ . The first term  $\mathbf{u}_p$  is the polarization drift, and the second term  $\mathbf{u}_{visc}$  is an additional term caused by viscosity. Here we have introduced a small parameter  $\epsilon = \frac{1}{\omega_{ci}} \frac{\partial}{\partial t}$ ,  $\epsilon \ll 1$  means the strong magnetic field approximation. It is easy to verify  $\frac{\mathbf{u}_1}{\mathbf{u}_0} \sim \epsilon$ .

Note that, although  $\mathbf{u}_0 \gg \mathbf{u}_1$ , we have

$$\nabla \cdot \mathbf{u}_0 = \nabla \cdot \mathbf{u}_E = 0 \quad (4)$$

$$\nabla \cdot \mathbf{u}_1 \neq 0 \quad (5)$$

So the divergence of polarization drift and the viscosity term is not neglectable.

Now we can substitute  $\mathbf{u}$  into the charge conservation equation  $\nabla \cdot \mathbf{J} = 0$ :

$$\nabla_{\perp} \cdot \mathbf{J}_{\perp} = -\nabla_{\parallel} J_{\parallel} \quad (6)$$

where  $\mathbf{J}_{\perp}$  comes from  $\mathbf{u}_1$

$$\mathbf{J}_{\perp} = n|e|\mathbf{u}_1 \quad (7)$$

and  $J_{\parallel}$  comes from the parallel force balance equation (i.e. Ohm's Law):

$$\nabla_{\parallel}\phi + \eta\mathbf{J}_{\parallel} - \frac{1}{en_0}\nabla_{\parallel}p_e = 0 \quad (8)$$

After some substitution and normalization of the variables, we get the first part of the H-W equations:

$$\rho_s^2 \frac{d}{dt} \nabla^2 \phi = -D_{\parallel} \nabla_{\parallel}^2 \left( \phi - \frac{n}{n_0} \right) + \nu \nabla^2 \nabla^2 \phi \quad (9)$$

In order to give the corresponding equation for electron, we start from the force balance equation, but for electron we put:  $\nabla\Pi = 0$ ,  $m_e n_e \frac{d\mathbf{u}}{dt} = 0$ , but we keep the electron-ion friction:

$$\mathbf{F}_{e\parallel} = -m_e n_e \nu_{ei} \mathbf{u}_{e\parallel} = \frac{m_e \nu_{ei}}{e} \mathbf{J}_{\parallel} \quad (10)$$

And the parallel force balance equation (i.e. Ohm's Law) can give us

$$\nabla_{\parallel}\phi + \eta \mathbf{J}_{\parallel} - \frac{1}{en_0} \nabla_{\parallel} p_e = 0 \quad (11)$$

The electron polarization drift is neglectable because of the mass ratio, so the continuity equation is simple:

$$\frac{dn}{dt} + n \nabla_{\parallel} \cdot \mathbf{u}_{e\parallel} = 0 \quad (12)$$

Combine them together, we can get the other part of H-W equations. After changing some notations, we can write the *Hasegawa-Wakatani Equations* in a beautiful way:

$$\boxed{\begin{aligned} \rho_s^2 \frac{d}{dt} \nabla^2 \phi &= -D_{\parallel} \nabla_{\parallel}^2 \left( \phi - \frac{n}{n_0} \right) + \nu \nabla^2 \nabla^2 \phi \\ \frac{d}{dt} n - D_0 \nabla^2 n &= -D_{\parallel} \nabla_{\parallel}^2 \left( \phi - \frac{n}{n_0} \right) \end{aligned}} \quad (13)$$

### 3 Hasegawa-Mima Model

From H-W equations (13), we can see that the key parameter is  $D_{\parallel} k_{\parallel}^2 / \omega$ . If  $D_{\parallel} k_{\parallel}^2 / \omega \gg 1$ , we can get  $\frac{\tilde{n}}{n_0} \sim \frac{e\phi}{T_e}$ , which means the electrons are adiabatic. In both electron adiabatic limit and collisionless limit (i.e.  $\nu = 0$ ), the H-W equations will become the *Hasegawa-Mima Equation*:

$$\boxed{\frac{d}{dt} (\phi - \rho_s^2 \nabla^2 \phi) + v_* \partial_y \phi = 0} \quad (14)$$

It is important to note that, the H-M equation can be written as the form of potential vorticity conservation:

$$\boxed{\frac{d}{dt} (PV) = 0} \quad (15)$$

where



$$PV = \phi - \rho_s^2 \nabla^2 \phi + \ln n_0 \quad (16)$$

PV is short for potential vorticity. What exactly is a potential vorticity? We can say it is a kind of generalization of vorticity. Actually potential vorticity has different form in different systems, for example, the above expression is the potential vorticity in plasmas; another example, is in quasi-geographic model, which will be discussed in section 5. Actually what's important is that, we find a conserved quantity!

## 4 Discussion about H-W and H-M Models

### 4.1 Cartoon image of drift wave

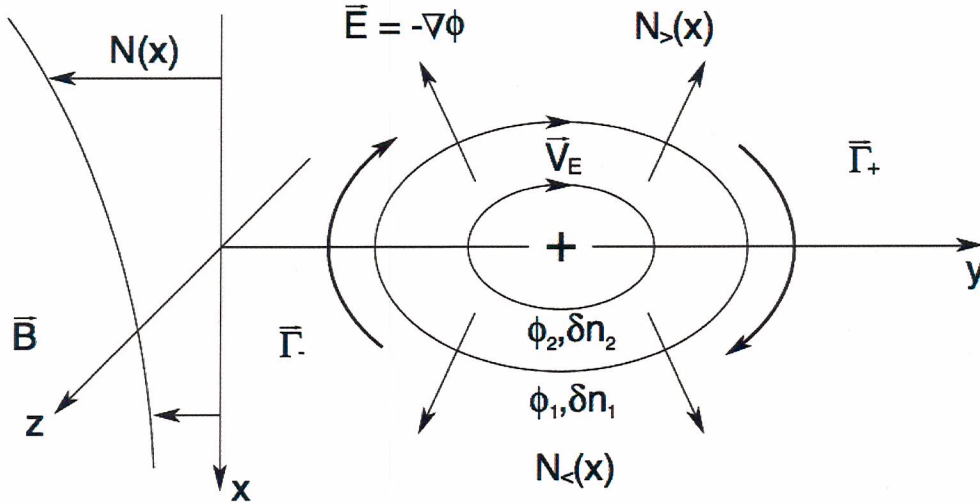


Figure 1: Cartoon image of drift wave.

From <http://peaches.ph.utexas.edu/ifs/ifsreports/Review.pdf>

H-W and H-M equations can support drift waves. Drift wave means density or potential wave caused by drift flows such as  $\mathbf{E} \times \mathbf{B}$  flow. Figure 1 demonstrates a simple example of drift wave. Here is the set up of this simple system (for simplicity, let's assume it's the positive charges that move):

(1) The particle density  $N(x)$  is homogeneous along  $y$  and  $z$  direction, but has a gradient along  $x$ . As shown in the figure, let  $\nabla N$  face  $-x$  direction.

(2)  $\mathbf{B} = \mathbf{B}_0$  is a constant everywhere and its direction is  $+z$ .

(3) There is a positive density perturbation at the “+” point in the figure.

Let’s see what happens next. The electric potential  $\phi$  will rise following the density, then it will produce radiation-shaped electric field  $\mathbf{E} = -\nabla\phi$ . Electrical field  $\mathbf{E}$  along with  $\mathbf{B}$  will produce  $\mathbf{E} \times \mathbf{B}$  flow, and the direction of this flow is a clockwise circle around the “+” position. Note that there are more particles on the upper half compared to the lower half because of the density gradient, so more particles will come to the right, which means the density perturbation is propagating along  $+y$  direction. This is a simple cartoon of the drift wave.

## 4.2 Linear dispersion relations of H-W H-M equations

For H-M equation, let’s assume a plane wave solution  $\phi = \phi_{\mathbf{k}} \exp(i\mathbf{k} \cdot \mathbf{x} - \omega t)$ , and plug it in (14), we can get

$$\omega = \frac{v_* k_y}{1 + \rho_s^2 k^2} \quad (17)$$

For H-W equation, let  $\phi = \phi_{\mathbf{k}} \exp(i\mathbf{k} \cdot \mathbf{x} - \omega t)$  and  $n = n_{\mathbf{k}} \exp(i\mathbf{k} \cdot \mathbf{x} - \omega t)$ , and plug it in (13). This gives us two equations, and the determinant=0 will give us the dispersion relation:

$$\omega \left(1 + \frac{k^2}{1 - i\omega/c_1}\right) = -\mathbf{k} \times \hat{z} \cdot \nabla \ln n_0 - ic_2 k^4 \quad (18)$$

## 4.3 Conservation quantities

In H-M model, generalized energy  $W$  is conserved:

$$W = \int dV \frac{\phi^2 + (\nabla\phi)^2}{2} \quad (19)$$

And also the generalized enstrophy  $U$  is conserved:

$$U = \int dV \frac{(\nabla\phi)^2 + (\nabla^2\phi)^2}{2} \quad (20)$$

## 5 Comparison to quasi-geostrophic model

Hasegawa-Mima model is quite similar to the quasi-geostrophic model (we will call it Q-G for short in this section), and the latter is less abstract, so let’s discuss a little bit to have a more clear picture about these models.

Table 1: Comparison between H-M model and quasi-geostrophic model

Hasegawa-Mima Model	quasi-geostrophic model
Lorentz force	Coriolis force
$\mathbf{E} \times \mathbf{B}$ flow	geostrophic current
potential vorticity conservation	potential vorticity conservation
drift wave	Rossby wave
zonal flow	zonal flow

The basic comparison is in Table 1. In Q-G model, the basic variable to solve  $\phi$  is the geopotential height, while in H-M model  $\phi$  is the electric potential. The basic study object in Q-G model is the motion of wind (or ocean flow). The motion of wind will be affected by Coriolis force, just as the Lorentz force in H-M model. So geostrophic current will be formed, like the  $\mathbf{E} \times \mathbf{B}$  flow. Thus Rossby wave, similar to drift wave, can propagate in this model. In the end, zonal flow will emerge in both models.

Kelvin's Theorem is the governing equation of Q-G model. Let  $\omega$  be the relative angular velocity of the motion of wind, and  $\Omega$  is the planetary angular velocity. Then Kelvin's Theorem says,

$$\oint_C \mathbf{v} \cdot d\mathbf{l} = \int d\mathbf{a} \cdot (\omega + 2\Omega) = Const \quad (21)$$

This theorem is easy to proof, so we omit it here. If we change some variables, it can be written in a better way. Let  $y$  be the velocity component towards the north pole, and define a constant  $\beta = 2\Omega \sin \theta_0 R$ , where  $\sin \theta_0$  is the latitude. Then Kelvin's Theorem can also be written as:

$$\frac{d}{dt}(\omega + \beta y) = 0 \quad (22)$$

Here  $PV = \omega + \beta y$ , so this equation has the form of potential vorticity conservation, just the same as H-M equation (15).

Now let's talk a little about the Rossby wave. We can write the Kelvin's Theorem as following:

$$\frac{d}{dt}(\nabla^2 \phi) + \beta \partial_x \phi = 0 \quad (23)$$

The linear dispersion relation of it is

$$\omega = -\frac{\beta k_x}{k^2} \quad (24)$$

which looks like (17). From this dispersion relation, we can get the group velocity:

$$v_{gy} = 2\beta \frac{k_x k_y}{(k^2)^2} \quad (25)$$

It has the structure of Reynolds stress! So Rossby wave is intimately connected to momentum transport.

## 6 Relationship to MHD

The generalized Ohm's Law is

$$\nabla_{\parallel} \phi - (\mathbf{u} \times \mathbf{B})_{\parallel} + \eta \mathbf{J}_{\parallel} - \frac{1}{en_0} \nabla_{\parallel} p_e = 0 \quad (26)$$

Compare to what we used to derive H-W and H-M equations (8), actually we neglected the second term.

On the other hand, in MHD, what we usually do is to neglect the last term:

$$\eta \mathbf{J}_{\parallel} = (\mathbf{E} + \mathbf{u} \times \mathbf{B})_{\parallel} \quad (27)$$

So we know that H-W/H-M and MHD are in different limit of the generalized Ohm's Law.